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Title: Darrieus Wind Turbine Blade Unsteady Aerodynamics: a Three-Dimensional Navier-Stokes CFD assessment

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Keywords: Darrieus wind turbine, unsteady Navier-Stokes simulations, CFD, tip flows

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Abstract: Thanks to the recent rapid progress in high-performance computing and the growing availability of large computational resources, computational fluid dynamics now offers a cost-effective, versatile and accurate means to improve the understanding of the unsteady aerodynamics of Darrieus wind turbines, increase their efficiency and delivering more cost-effective structurally sound designs.

In this study, a Navier-Stokes CFD research code featuring a very high parallel efficiency was used to thoroughly investigate the threedimensional unsteady aerodynamics of a one-blade Darrieus rotor. Highly spatially and temporally refined time-dependent simulations were carried out using up to 16,000 processor cores per simulation on an IBM BG/Q cluster. The study aims at providing a detailed description and quantification of the main three-dimensional effects associated with the cyclical motion of this turbine type, including tip losses, dynamic stall, vortex propagation and blade/wake interaction. On one hand, the results corroborate the findings of several carefully designed twodimensional studies. On the other hand, they reveal that the threedimensional flow effects affecting Darrieus rotor blades are much more complex than assumed by the conventional lower-fidelity models often used for design applications, and strongly vary during the rotor revolution.

#### Dear Prof. Lund,

new computational resources are thought to provide in the near future an essential contribution to an inner comprehension of complex phenomena taking place in a flow past rotating blades. As confirmed by some very interesting papers appeared in "Energy" in the last few years (all cited in the paper), particular interest is arising around Darrieus turbines due to the potential benefits of CFD in more accurately characterize some critical issues, e.g. the dynamic stall of the airfoils and aero-acoustic emissions.

In the past few years, thanks to the growth of available computational resources, 3D Navier-Stokes CFD analyses have received increasing attention, and some preliminary studies have been published. If many 2D studies showed that the minimum temporal and spatial refinement levels required to obtain gridindependent solutions is quite high, due to the aerodynamic complexity of these unsteady rotor flows, the computational cost of the simulation becomes very large when using 3D unsteady NS CFD for Darrieus rotor aerodynamics. As a result, almost all the studies presently published in the literature were constrained by limited computational resources to use of fairly coarse spatial and temporal refinements, which often did not match the requirements indicated by proper sensitivity analyses. In particular, the common approach found in the literature was to progressively coarsen the meshes when moving to 3D analyses, in order to limit the total number of cells in the range between 1,000,000 and 10,000,000.

In this study, unique simulations were run on an IBM BG/Q cluster. Thanks to the excellent parallel efficiency of the COSA code, the simulations yielding the results presented in this paper could be performed using about 16,000 cores. This required partitioning the 55,000,000 elements grid into 16384 blocks, making use of in-house utilities. Using a time-discretization of 720 steps per revolution, the simulation needed 12 revolutions to achieve a fully periodic state. The wall-clock time required for the complete simulation of the main three-dimensional effects associated with the cyclical motion of this turbine type, including tip losses, dynamic stall, vortex propagation and blade/wake interaction. On one hand, the results corroborate the findings of several carefully designed two-dimensional studies. On the other hand, they reveal that the three-dimensional flow effects affecting Darrieus rotor blades are much more complex than assumed by the conventional lower-fidelity models often used for design applications, and strongly vary during the rotor revolution.

In this view, we believe that the work can be of interest for many readers and contribute in reinforcing the journal position as the main reference for these analyses.

We would be then very pleased if you could consider the paper for publication in "Energy".

Looking forward to hearing from you, best regards.

Francesco Balduzzi Jernej Drofelnik Alessandro Bianchini Giovanni Ferrara Lorenzo Ferrari Michele Sergio Campobasso

Florence, Pisa, Lancaster and Glasgow 06/03/2017

Dear Prof. The,

we would like to thank again the Reviewers for their comments which have enabled us to make additional improvements to the paper, and you for your coordination of the review process.

On the basis of the reviewer's comments, a complete revision of the work has been carried out.

Many parts of the paper have been rewritten and additional data, figures and references have been added, with particular attention to the presentation of the CFD approach and to the assessment of the proposed approach validity and prospects. A further revision of the English (both grammar and style) has also been carried out to improve clarity on. To enable reviewers to more easily track the alterations in response to their questions/comments, many of these linguistic corrections have not been highlighted in blue (especially in the discussion of main results), as they did not alter the main content of the affected sentences.

Like in the first revision, our comments and responses to reviewer's comments have been highlighted in blue both in this communication and in the revised version of the paper.

We really hope that these additional modifications could make the paper worth of publication in *Energy*.

Best regards,

Francesco Balduzzi, Jernej Drofelnik, Alessandro Bianchini, Giovanni Ferrara, Lorenzo Ferrari, Michele Sergio Campobasso

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#### **REVIEWER #1**

The paper has large improvements comparing to the previous version. Most questions have been responsed in a satisfactory manner.

We would like to thank the Reviewer for his/her positive comments about the work we did on the paper with respect to the first draft.

1, It is OK using a one-bladed case for theorical investigation. However, I still has the same question. Is that worth to spend 10 times computational effort to gain about 3 percents of accuracy (Let's suppose the results using fine mesh are more accurate)? For practical applications, i.e., two-bladed or three bladed cases, the computational effort will go to 20 or 30 times. So, according to the comparisons in this paper, actually, I have different opinion to that of the authors. If only considering the aerodynamic force, I don't think such high resolution simulations contribut much. The authors are encougrated to explore the difference of the detailed flow structure further between fine and coarse mesh results, especially for the strong 3D effect.

BTW, if the authors really talk about the sensitivity of the grid. A much more detaied grid sensitivity studing is required. However, that is not included in the main scope of energy journal.

According to the Reviewer's comment, paragraph 2.4 was further extended. Two figures were added (new Fig. 5 and 6) to show the influence of the mesh refinement on the resolution of the 3D flow features.

2, Th authors claimed that the maximum torque locating at theta=88.5 is due to the onset of the stall. More explainations and gictures are required to show that clearly.

Thanks to the Reviewer comment, we understood that some sentences in the paper were misleading. We stated that "the maximum torque in the upwind portion of the revolution is located at  $\vartheta \approx 88.5^{\circ}$ " and "stall in the central blade portion starts shortly before  $\vartheta = 90^{\circ}$ ", but we never clarified when stall actually occurs. We

have added a figure (new Fig. 8) highlighting the onset of stall, and we have modified the text to avoid any further confusion. Please refer to lines 472-482 in the revised paper.

3, The last question is not closely related to this paper. What partitioning method is used in COSA? Does the original blocks generated using ICEM CFD have the same cell number?

The original ANSYS® ICEM® grid generator provided a mesh made of 4096 blocks, almost perfectly balanced in terms of number of cells. Then, the grid was further partitioned into 16384 blocks (1 block per processor) using an in-house utility. All grid blocks had then identical number of cells to optimize the load balance of the parallel simulation.

#### **REVIEWER #2**

The revised manuscript can be considered for publication in Energy pending the raised points below:

Major comments:

a. Abstract

From the phrase, 'A comparison of the CFD integral estimates and the results of a blade-element momentum code is also presented to highlight strengths and weaknesses of low-fidelity codes for Darrieus turbine design'. Numerical simulations are usually compared or validated by means of experimental measurements. In "Results" section, not a single comparison with experimental data is presented. This reviewer still finds this as a major omission.

The authors agree with the Reviewer about the additional benefits that could be ensured by the availability of experimental data. Unfortunately, no experimental tests are presently available for the 1-blade configuration. As discussed in the paper, however, previous 2D CFD studies were carried out on the 3-blade rotor (refs. [21] and [53]), which confirmed the suitability of the proposed numerical approach and also highlighted the most appropriate numerical settings (grid refinement, timestep size, etc.) to be used.

Regarding the results of the BEM analyses, the authors would like to underline that these were not intended to be used as a means for validating the CFD analysis. Conversely, the high-fidelity 3D CFD results served the purpose of pointing out the intrinsic limitations of low-fidelity methods, such as those arising from the use of simplified models to account for tip losses).

#### b. Introduction

Although the authors have referred a lot of articles on both 2D and 3D VAWT rotor simulations, but still the following articles are suggested to add:

1. M. D. Bausas and L. A. M. Danao, The aerodynamics of a camber-bladed vertical axis wind turbine in unsteady wind, Energy 93 (2015) 1155-1164

2. L.A. Danao, J. Edwards, O. Eboibi, R. Howell, A numerical investigation into the influence of unsteady wind on the performance and aerodynamics of a vertical axis wind turbine, Appl. Energy 116 (2014) 111-124

3. D.W. Wekesa, C. Wang, Y. Wei, W. Zhu, Experimental and numerical study of turbulence effect on aerodynamic performance of a small-scale vertical axis wind turbine. Journal of Wind Engineering and Industrial Aerodynamics Vol. 157, 2016, 1-14.

The authors thank the Reviewer for these interesting suggestions. The three references have been added in the paper.

#### c. Methodology

Consider collapsing sections 2, 3 and 4 into one section (like "Methodology") while keeping the subsections.

The authors were pleased to accept the suggestion of the Reviewer. The paper is now made of 4 sections: previous sections 2, 3, and 4 were collapsed in the new Section 2 "Numerical methodology".

In line 313-316, the authors indicate that "....the blade was attached at midchord." However, the blade is usually balanced at 1/4 of the chord (0.25c) from the leading edge so consideration of the moment is taken at that point.

The Reviewer is right about the general design guidelines about the blade-spoke connection point. In the present case, however, the blade was attached at mid-chord since the case study was derived from the rotor experimentally tested in the wind tunnel (full detail is available in ref. [24]).

The rationality of the boundary conditions should be explained. The flow flux is not constant at the inlet of the computational domain. And how is the turbulent intensity 5% of inlet flow defined?

Imposed boundary conditions at far-field were those often used for this type of simulations, i.e. constant velocity magnitude and direction on inflow patches of the far-field boundary and constant static pressure on outflow patches of the far-field boundary (the density is practically constant everywhere due to low speed of the application). The turbulence intensity is the ratio of the root-mean-square of the turbulent velocity fluctuations and the mean velocity, as customary in turbulent flow analyses. The value of 5% was used to account for the high-frequency low-amplitude turbulent fluctuations occurring in a fairly stable wind regime. The investigation of the effects of large wind fluctuations of an unsteady wind regime (of the type reported in the references cited by the Reviewer at Point b) was not carried out because this is not one of the objectives of this study. It is however a very interesting topic for future extensions of the research reported in this article.

A CFD code flow solver COSA is mentioned. However, additional description of the following should be provided:

- a. Computational domain (dimensions and similarity with wind tunnel section)
- b. Boundary conditions discretization method adopted to meshing
- c. Software used to meshing
- d. Number of cells, y+, ks, dimension of first cell close to the wall, wall function.

All the details indicated by the Reviewer have been added and/or clarified in the revised version of the paper (accordingly highlighted in blue colored text).

Add one title subsection where the authors describe (e.g. title: "Numerical set-up"):

- a. numerical approach (RANS, URANS, LES)
- b. turbulence model
- c. numerical schemes for the equations
- d. time step size study
- e. algorithm solver
- f. CFD code (software)
- g. calculation resource/cost

All the details indicated by the Reviewer have been added and/or clarified in the revised version of the paper (accordingly highlighted in blue colored text).

The definition and justification of the objectives have been clearly indicated. However, numerical error analysis of the methodology is not presented. In addition, there's no mesh independence and time step size studies.

A section dedicated to the grid and timestep sensitivity analysis has been provided during the first revision of the paper. However, prompted by the Reviewers' comments, we have now further improved it including new data and figures (see new Section 2.4).

#### d. Results and discussion

From Figure 5, the 2D simulation results over-predicts the Cm compared to the 3D, yet the overall shape of the curves is maintained. Justify this using power coefficient CP curve and offer an explanation including comparison with the literature data mentioned in section 1.

As suggested by the Reviewer, we have further extended the discussion on the comparison between the 2D and 3D curves by adding comments related to similar analyses available in the reviewed literature.

The authors assert that due to the large burden associated with running the 3D time-dependent simulation, only a single operating condition was simulated, corresponding to a tip-speed ration (TSR) of 3.3. This can hold true for the 3D case, but for the 2D case, different tip speed ratios can be incorporated and a power coefficient curve plotted and compared with literature data to check the suitability of the numerical model. And why the choice of tip speed ratio of 3.3? I thought the choice at lower tsr with converged solution would ensure convergence at higher tsr.

Unfortunately, no experimental tests/data are presently available for this 1-blade configuration that can be used to make a comparison with CFD simulations. As discussed in the paper, however, previous 2D CFD studies were carried out on the 3-blade rotor (refs. [26] and [53]), which confirmed the suitability of the proposed numerical approach and also discussed the choice of adequate numerical settings (grid refinement, timestep size, etc.) .for this type of CFD analysis.

The comment of the Reviewer is, however, very appropriate and prompted us to introduce both a discussion on why we selected TSR=3.3, and a fairly reliable power curve of the 1-blade rotor (new Fig. 3) in order to visualize the position of the selected operating condition with respect to the point of peak power coefficient. Please refer to lines 369-381 in the revised paper.

Although the authors state that the results are in agreement with previous analyses of streamlines and pressure coefficient profiles, the discussion fails to relate the findings and observations to other relevant studies in the literature. As a result, there appears to be no discussion on the implication and limitation of the findings. A discussion should be added to explain the significance/implication of the Darrieus wind turbine single blade analysis in comparison to analyses in the literature.

As suggested by the Reviewer, a new paragraph has been added in the paper to relate the findings and observations to other relevant studies in the literature, with the aim of comparing the efficiency decrease in terms of reduction of equivalent blade height. Please refer to lines 53-543 in the revised paper. Moreover, additional comments were provided on the shift of the torque peak as a function of the span position. Please refer to lines 464-471 in the revised paper.

Minor comments:

i. In the highlights, change 16.000 to 16,000 Corrected.

ii. In highlight, remove a colon in bullet 4 Removed.

iii. In the entire manuscript, change "free stream" to "free-stream" Changed.

iv. Consider changing the section titled "Results" to "Results and discussion" Changed.

- Analysis of the 3D unsteady aerodynamics of a Darrieus wind turbine blade in motion
- Highly spatially and temporally refined time-dependent simulations carried out with the COSA code
- One month calculation time on more than 16.000 processors on a IBM BG/Q cluster
- Detailed description of: tip losses, dynamic stall, vortex propagation and blade/wake interaction

# Darrieus Wind Turbine Blade Unsteady Aerodynamics: a Three-Dimensional Navier-Stokes CFD assessment

3

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16

# 17 Abstract

Energized by the recent rapid progress in high-performance computing and the growing availability of large computational resources, computational fluid dynamics (CFD) is offering a cost-effective, versatile and accurate means to improve the understanding of the unsteady aerodynamics of Darrieus wind turbines, increase their efficiency and delivering more costeffective and structurally sound designs.

23 In this study, a Navier-Stokes CFD research code featuring a very high parallel efficiency was used to thoroughly investigate the three-dimensional unsteady aerodynamics 24 of a Darrieus rotor blade. Highly spatially and temporally resolved unsteady simulations were 25 carried out using more than 16,000 processor cores on an IBM BG/Q cluster. The study aims 26 at providing a detailed description and quantification of the main three-dimensional effects 27 associated with the periodic motion of this turbine type, including tip losses, dynamic stall, 28 vortex propagation and blade/wake interaction. Presented results reveal that the three-29 dimensional flow effects affecting Darrieus rotor blades are significantly more complex than 30 assumed by the lower-fidelity models often used for design applications, and strongly vary 31 during the rotor revolution. A comparison of the CFD integral estimates and the results of a 32 blade-element momentum code is also presented to highlight strengths and weaknesses of 33 low-fidelity codes for Darrieus turbine design. 34

The reported CFD results provide a valuable and reliable benchmark for the calibration of lower-fidelity models, which are still key to industrial design due to their very high execution speed.

38

# 39 Keywords

- 40 Darrieus wind turbine, unsteady Navier-Stokes simulations, CFD, tip flows
- 41

## 42 Nomenclature

43	Latin symbols		
44	AoA	angle of attack	
45	AR	aspect ratio	[-]
46	С	blade chord	[m]
47	$C_t$	torque coefficient	[-]
48	$C_p$	pressure coefficient	[-]
49	ĊP	power coefficient	[-]
50	BEM	Blade Element Momentum	
51	CFD	Computational Fluid Dynamics	
52	Н	turbine height	[m]
53	k	turbulent kinetic energy	$[m^{2}/s^{2}]$
54	NS	Navier-Stokes	
55	р	static pressure	[Pa]
56	PDEs	Partial Differential Equations	
57	R	turbine radius	[m]
58	RANS	Reynolds-Averaged Navier-Stokes	
59	SST	Shear Stress Transport	
60	Т	torque per unit length	[Nm]
61	TSR	tip-speed ratio	[-]
62	и, v, w	Cartesian components of local fluid velocity vector	[m/s]
63	U	magnitude of absolute wind speed	[m/s]
64	<u>v</u>	local fluid velocity vector	[m/s]
65	$\underline{v}_b$	local grid velocity vector	[m/s]
66	VAWTs	Vertical-Axis Wind Turbines	
67	W	magnitude of relative wind speed	[m/s]
68	<i>x</i> , <i>y</i> , <i>z</i>	reference axes	
69	$y^+$	dimensionless wall distance	[-]
70			
71	<u>Greek symbols</u>		
72	9	azimuthal angle	[deg]
73	$\mu_t$	turbulent viscosity	[Kg/m/s]
74	ρ	air density	[kg/Nm <sup>3</sup> ]
75	$\Phi$	computational domain diameter	[m]
76	Ψ	computational domain height	[m]
77	ω	specific turbulence dissipation rate	[1/s]
78	$\Omega$	turbine revolution speed	[rad/s]
79		-	
80	<u>Subscripts</u>		
81	00	value at infinity	
82	ave	averaged value	
83		-	

# 84 **1. Introduction**

85 *1.1 Background* 

After most research on vertical-axis wind turbines (VAWTs) came to a standstill in the mid 90's [1], the Darrieus wind turbine [2] is receiving again increasing attention of both researchers and manufacturers [3-6]. For distributed wind power generation in the built environment [7], inherent advantages of this turbine type, such as performance insensitivity 90 to wind direction, generator often positioned on the ground, low noise emissions [8], enhanced performance in skewed [9] or highly turbulent and unsteady flows [10-12], may 91 outweigh disadvantages, such as lower power coefficients and more difficult start-up, with 92 93 respect to typical horizontal axis machines. Moreover, in densely populated areas VAWTs are often preferred to other turbine types because they are perceived as aesthetically more 94 pleasant and thus easier to integrate in the landscape [13]. The applicability of Darrieus wind 95 96 turbines for utility-scale power generation making use of floating platforms also appears to 97 present important benefits in terms of overall dynamic stability [14].

Historically, the aerodynamic performance analysis of these rotors has been carried out with low-fidelity methods, like the Blade Element Momentum (BEM) theory [1,15-17] or lifting line methods [18-19]. More recently, however, the intrinsic limitations of these models made clear that higher-fidelity tools are needed in order to understand in greater depth the complex unsteady aerodynamics of Darrieus rotors [20], such as the interaction of the blades with macro vortices [21] or dynamic stall [22].

While experimental testing is often quite difficult and expensive, Navier-Stokes (NS) 104 Computational Fluid Dynamics (CFD) can be a versatile and accurate means to improve the 105 106 understanding of VAWT unsteady aerodynamics and achieve higher-performance, structurally sound and more cost-effective Darrius turbine designs. The use of NS CFD for 107 simulating time-dependent Darrieus turbine aerodynamics is rapidly increasing due to both 108 the ongoing development and deployment of more powerful high-performance computing 109 hardware, such as large clusters of multi- and many-core processors [23], and also the 110 development of computationally more efficient algorithms. 111

112 113

# 1.2 Previous CFD studies on Darrieus VAWTs

Early use of the Reynolds-Averaged Navier-Stokes (RANS) CFD technology for 114 Darrieus rotor aerodynamics for investigating the complex fluid mechanics of these machines 115 was based mostly on two-dimensional (2D) simulations (e.g. [24]). An extensive literature 116 review of 2D RANS CFD studies is provided by Balduzzi et al. [25], along with an overview 117 of the numerical settings frequently used for Darrieus rotor RANS studies and guidelines for 118 the optimal set-up of these simulations. Two-dimensional RANS analyses, suitably corrected 119 120 for three-dimensional (3D) effects, such as struts resistive torque and blade tip losses, have been used to estimate the turbine overall performance [26] and predominantly 2D 121 phenomena, like virtual camber [27] and virtual incidence [28] effects, the influence of 122 unsteady wind conditions on turbine aerodynamics [29], the evolution of the flow field at 123 start-up [30], and turbine/wake interactions [31]. 124

However, the use of 2D simulations to analyse the flow field past real rotors may result 125 in significant uncertainties, due to the difficulty of reliably quantifying complex 3D 126 aerodynamic features such as blade tip flows, their dependence on the blade tip geometry and 127 their impact on the overall efficiency as a function of the blade aspect ratio. Moreover, most 128 3D aerodynamic features of Darrieus rotor flows vary not only spatially (e.g. dynamic stall 129 decreases from midspan to the blade tips, as shown below), but also temporally during each 130 revolution. It is difficult to develop corrections to improve the predictions of time-dependent 131 2D CFD analyses, and the resulting uncertainty on unsteady loads may severely impair both 132 aerodynamic and structural (e.g. fatigue) assessments. Therefore 3D CFD simulations are key 133 to characterizing and quantifying the aforementioned 3D aerodynamic phenomena. This is 134 important for reducing the uncertainty associated with modeling such phenomena on the basis 135 of a relatively small amount of data referring to existing turbines, and assumptions based on 136 overly simplistic analytical models. However, large computational resources are needed for 137 such simulations, due to the high temporal and spatial grid refinement needed for accurately 138 139 resolving all design-driving aerodynamic phenomena.

140 Comparisons of 2D and 3D simulations are sometimes carried out considering test cases for which experimental data are available, as in Howell et al. [32] and Lam et al. [33]. 141 In [32] the use of 2D RANS CFD led to relatively poor agreement with experiments: a 142 maximum power coefficient CP of 0.371 at a tip-speed ratio (TSR) of 2.4 was predicted 143 against a measured maximum CP of 0.186 at TSR=1.85. Using 3D simulations, the 144 maximum power coefficient was instead correctly predicted, although the shape of computed 145 and measured power curves presented significant differences. The k- $\varepsilon$  re-normalization group 146 turbulence model [34] was used for all simulations, but no detailed information on the mesh 147 size was provided, except for the indication of a high dimensionless wall distance  $(y^+ \approx 10)$ 148 149 which required the use of wall functions. Also in [35] notable discrepancies between the results of 2D and 3D RANS simulations were observed: the 2D simulations predicted a 150 maximum power coefficient of 0.43 at TSR=4.5 against a maximum CP of 0.27 at TSR=1.85 151 predicted by the 3D analyses. A fairly coarse grid, consisting of 2.95 million elements was 152 used for the 3D simulations of the considered two-blade rotor, and the k- $\omega$  Shear Stress 153 Transport (SST) turbulence model [36] was used. 154

Gosselin et al. [37] used 2D and 3D RANS simulations with the  $k-\omega$  SST turbulence 155 model to investigate the dependence of 3D effects on the blade aspect ratio, finding that an 156 aspect ratio of 7 led to a relative efficiency drop of 60 percent with respect to the 2D analysis. 157 Although the simulations were performed with very refined meshes (up to 700 nodes on each 158 airfoil), the article reports that no rigorous mesh-independence was obtained. Joo et al. [38] 159 analysed the aerodynamic characteristics of a two-blade rotor as a function of design 160 parameters such as solidity and optimal TSR using the 3D RANS model coupled to a 161 realizable k- $\varepsilon$  turbulence model. They used a computational mesh of 1.2 million elements 162 and compared their baseline results with available experimental data: a general 163 overestimation of the power curve was noticed, with a 10% discrepancy at the peak power. 164 165 Moreover, significant shape differences of computed and measured power curves were observed, particularly in the right branch of such curves (i.e. for high TSR values), with the 166 measured curve being steeper than the computed one. A two-blade Darrieus rotor with 167 straight blades was analysed by Li et al. [35,39] by means of wind tunnel experiments and 3D 168 RANS simulations using the  $k-\omega$  SST turbulence model. Numerical results compared 169 favourably to experimental data in the left branch (i.e. low TSR values) of the power curve, 170 but CFD significantly overestimated power for higher TSR, possibly due to excessively small 171 distance between the rotor and the farfield boundaries of the physical domain (about 2 rotor 172 diameters from the rotor center). The simulations used a grid with about 5 million elements, 173 and predicted a peak power coefficient of 0.24 at TSR=2.09 whereas experiments showed a 174 175 peak *CP* of 0.18 at TSR=2.18.

Alaimo et al. [40] carried out a comparative study of the aerodynamic performance of 176 three-blade Darrieus rotors using straight and helical blades. For the three-blade rotors they 177 178 analysed, they found that blade tip vortex flows significantly reduced the rotor performance and that the use of helical blades significantly reduces this power loss. The largest grids used 179 for those 3D RANS analyses had about 10 million elements, and turbulence was modelled 180 using the k- $\varepsilon$  turbulence model with wall functions to enable the use of relatively coarse grids 181 and enhance numerical stability. De Marco et al. [41] performed 3D RANS simulations to 182 analyse the influence of the geometry of the blade supporting arms on the turbine 183 performance. Using grids featuring between 4 and 18 million elements and the k- $\omega$  SST 184 model, they found that inclined and aerodynamically shaped supporting arms can 185 significantly increase the mean power coefficient. Using computational meshes with up to 12 186 187 million elements and the k- $\omega$  SST model, Zamani et al. [42] characterized with 3D RANS simulations the impact of J-shaped blades on Darrieus rotor torque and power characteristics 188 at low and medium TSR values, finding that this blade shape significantly increases the rotor 189

190 performance in these regimes, resulting in improved start-up characteristics. Orlandi et al. 191 [43] used 3D RANS simulations and the  $k-\omega$  SST model to study the influence of skewed 192 wind conditions on the aerodynamic characteristics of a two-blade Darrieus turbine; to limit 193 the computational burden of the 3D analyses, grids with about 10 million elements were used.

A recent Navier-Stokes CFD study of a three-blade Darrieus rotor using pitching blades to further improve the aerodynamic performance has made use of a Large Eddy Simulation [44], an approach that can yield more accurate results than the RANS method. However, resolved LES analyses require computational grids far larger than those needed for gridindependent RANS analyses, and this makes the use of resolved 3D LES simulations even more difficult than that of grid-independent 3D RANS analyses.

The aforementioned 3D CFD analyses highlighted new important aerodynamic 200 phenomena, but in almost all cases limited availability of computational resources imposed 201 202 the use of fairly coarse spatial and temporal refinement, and this may result in uncertainty due to lack of complete grid-independence of the CFD solutions. Recent parametric analyses 203 investigating the impact of several numerical parameters on the computationally less 204 demanding 2D CFD analysis of Darrieus rotors [25,45-47] showed that the analysis reliability 205 206 - in terms of accuracy of both performance prediction and resolution of important flow structures - is tremendously affected by the quality of the meshing and time-stepping 207 strategies. These studies highlighted that the minimum temporal and spatial refinement 208 required to obtain grid-independent solutions is quite high, due to the aerodynamic 209 complexity of these unsteady flows. Because of these constraints, the computational cost of 210 reliable 3D unsteady NS analyses of Darrieus rotor flows is extremely large due to the 211 212 necessity of maintaining the high temporal resolution indicated by the 2D parametric studies and a high level of spatial refinement both in the grid planes normal to the rotor axis and the 213 3<sup>rd</sup> direction orthogonal to such planes. Refinement in the 3<sup>rd</sup> direction is essential to reliably 214 resolving 3D flow features. For example, the parametric study of [25] showed that temporal 215 and spatial grid-independent 2D RANS analyses of a three-blade rotor require grids with at 216 least 400,000 elements. To preserve the same accuracy level in a 3D RANS simulation of the 217 same turbine (modelling only half of the rotor making use of symmetry boundary conditions 218 on the plane at rotor midspan and ensuring adequate refinement in the tip region) the mesh 219 would consist of at least 90 million elements, which is almost ten times the size of the finest 220 meshes used in the 3D RANS studies of Darrieus rotor flows published to date. Failing to 221 maintain these refinement levels may reduce the benefits achievable by using 3D RANS 222 simulations to improve Darrieus rotor design. 223

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# 1.3 Study aim

In this study, the COSA RANS research code, which features a very high parallel 226 efficiency, is used to investigate in great detail the 3D flow features of a rotating Darrieus 227 rotor blade and the impact of flow three-dimensionality on power generation efficiency. More 228 specifically, the study aims at providing a highly accurate analysis of the main 3D 229 phenomena occurring during each revolution of the considered one-blade rotor, including tip 230 vortices, dynamic stall and downstream vortex propagation, and to assess the impact of these 231 phenomena on the overall performance of this rotor. The use of a single rotating blade for the 232 type of analyses reported herein is not uncommon (see for example [40]). This set-up enables 233 a better understanding of individual key fluid mechanics phenomena adversely impacting 234 loads and energy efficiency of Darrieus rotors, and this information constitutes the first 235 knowledge level required to improve the design of these machines. Follow-on studies will 236 237 focus on additional 3D fluid mechanic aspects resulting from the multi-blade environment making use of computational resources larger than those used in the present study. 238

To maximize the analysis reliability, a time-dependent 3D simulation using very high levels of spatial and temporal refinement is carried out using a large 98,304-core IBM BG/Q cluster.

The presented test case is expected to be highly valuable to other research groups both to verify new CFD approaches and to calibrate lower-fidelity models (e.g. model based on lifting line theory and free vortex methods), which are key to industrial design due to their extremely low computational cost.

The paper is organized as follows. Section 2 presents the numerical methodology that 246 has been followed in the study: sub-section 2.1 reports the governing equations solved by the 247 248 COSA CFD code for the analysis of Darrieus rotor flows, sub-section 2.2 summarizes the main numerical features and previous work carried out with this code, and sub-section 2.3 249 provides the main features of the case study and describes the adopted numerical set-up. 250 Section 3 presents the main results of the 3D CFD analysis and compares them to those of the 251 2D analysis of the same case study, to highlight the impact of 3D effects. In Section 3 the 252 results of the RANS CFD analyses are also compared with those of the blade element 253 momentum theory to highlight strengths and weaknesses of this engineering approach. A 254 summary of the study and concluding remarks are finally provided in Section 4. 255 256

## 257 2. Numerical methodology

### 258 **2.1 Governing equations**

The compressible NS equations are a system of 5 nonlinear partial differential 259 equations (PDEs) expressing the conservation of mass, momentum and energy in a viscous 260 fluid flow. Averaging these equations on the longest time-scales of turbulence yields the so-261 called RANS equations, which feature additional terms depending on the Reynolds stress 262 tensor. Making use of Boussinesq approximation, this tensor has an expression similar to that 263 264 of the laminar or molecular stress tensor, with the molecular viscosity replaced by a turbulent or eddy viscosity [48-49]. In the COSA CFD code, the eddy viscosity is computed by means 265 of the two-equation  $k - \omega$  SST turbulence model [36]. Thus, turbulent flows are determined by 266 267 solving a system of 7 PDEs.

Given a moving time-dependent control volume C(t) with time-dependent boundary S(t), the Arbitrary Lagrangian–Eulerian integral form of the system of the time-dependent RANS and SST equations in an absolute frame of reference is:

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$$\frac{\partial}{\partial t} \left( \int_{C(t)} \mathbf{U} dC \right) + \oint_{S(t)} \left( \underline{\Phi}_c - \underline{\Phi}_d \right) \cdot d\underline{S} - \int_{C(t)} \mathbf{S} dC = 0$$
(1)

(2)

272 where **U** is the array of conservative variables defined as:

$$\mathbf{U} = \left[ \rho \ \rho \underline{\nu}' \ \rho E \ \rho k \ \rho \omega \right]'$$

The symbols  $\rho$ ,  $\underline{v}$ , E, k and  $\omega$  denote respectively fluid density, flow velocity vector of Cartesian components (u,v,w), total energy per unit mass, turbulent kinetic energy per unit mass and specific dissipation rate of turbulent energy, and the superscript ' denotes the transpose operator. The total energy is defined as  $E=e+(\underline{v}\cdot\underline{v})/2+k$ , where *e* denotes the internal energy per unit mass; the perfect gas law is used to express the static pressure *p* as a function of  $\rho$ , *E*, *k* and the mean flow kinetic energy per unit mass ( $\underline{v}\cdot\underline{v}$ )/2. The generalized convective flux vector is defined as:

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$$\underline{\mathbf{\Phi}}_{c} = \underline{\mathbf{E}}_{c}\underline{i} + \underline{\mathbf{F}}_{c}\underline{j} + \underline{\mathbf{G}}_{c}\underline{k} - \underline{v}_{b}\mathbf{U}$$
(3)

where  $\mathbf{E}_c$ ,  $\mathbf{F}_c$  and  $\mathbf{G}_c$  are respectively the x-, y- and z-component of  $\underline{\mathbf{\Phi}}_c$  and are given by:

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$$\begin{cases} \mathbf{E}_{c} = \left[\rho u \ \rho u^{2} + p \ \rho uv \ \rho uw \ \rho uH \ \rho uk \ \rho u\omega\right]' \\ \mathbf{F}_{c} = \left[\rho v \ \rho uv \ \rho v^{2} + p \ \rho vw \ \rho vH \ \rho vk \ \rho v\omega\right]' \\ \mathbf{G}_{c} = \left[\rho w \ \rho uw \ \rho vw \ \rho w^{2} + p \ \rho wH \ \rho wk \ \rho w\omega\right]' \end{cases}$$
(4)

in which  $H=E+p/\rho$  is the total enthalpy per unit mass. The vector  $\underline{v}_{b}$  is the velocity of the boundary S, and the flux term  $-\underline{v}_{b}\mathbf{U}$  is its contribution of the boundary motion to the overall flux balance.

The expressions of the diffusive fluxes  $\underline{\Phi}_c$  and the turbulent source term *S* appearing in Eq. (1) can be found in [48] and [50].

290 **2.2 COSA CFD code** 

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291 COSA is a compressible density-based finite volume code that solves the system of PDEs corresponding to Eq. (1) using structured multi-block grids. The code features a steady 292 flow solver, a time-domain (TD) solver for the solution of general unsteady problems [48-293 49], and a harmonic balance solver for the rapid solution of periodic flows [50-52]. The 294 second-order space discretization of the convective fluxes of both the RANS and the SST 295 equations uses an upwind scheme based on Van Leer's MUSCL extrapolations and Roe's 296 flux difference splitting. The second order discretization of all diffusive fluxes is instead 297 298 based on central finite-differencing. The space-discretized RANS and SST equations are 299 integrated in a fully-coupled fashion with an explicit solution strategy based on full 300 approximation scheme multigrid featuring a four-stage Runge-Kutta smoother. Convergence acceleration is achieved by means of local time-stepping and implicit residual smoothing. For 301 general time-dependent problems, the TD equations are integrated using a second order 302 accurate dual time-stepping approach. 303

Comprehensive information on the numerical methods used by COSA and thorough 304 validation analyses are reported in [50,52] and other references cited therein. For unsteady 305 problems involving oscillating wings and cross-flow open rotors such as the Darrieus 306 turbines, COSA solves the governing equations in the absolute frame of reference using 307 body-fitted grids. In the case of Darrieus rotors in open field operation this implies that the 308 entire computational grid rotates about the rotational axis of the turbine. The suitability of 309 COSA for the simulation of Darrieus wind turbines has been recently assessed through 310 comparative analyses with both commercial CFD codes and experimental data [53-54]. 311

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## 2.3 Case study and computational model

The selected case study is a one-blade H-Darrieus rotor using the NACA 0021 airfoil. 314 The blade chord (c=0.0858 m), the blade length (H=1.5 m) and the rotor radius (R=0.515 m) 315 were set equal to those used in the case-study of [24]; the blade was attached to the spoke at 316 midchord according to the original 3-blade model of [24]. The decision of simulating a single 317 318 blade was based both on physical considerations and on hardware limitations. First, a one-319 blade model is sufficient to investigate all the desired 3D flow structures that lead to an efficiency reduction of a finite blade. At the same time, the use of a single blade allows one to 320 isolate and analyze fundamental aerodynamic phenomena of finite-length blade 321 322 aerodynamics, removing additional aerodynamic effects due to multiple blade/wake interactions occurring in a multi-blade rotor. From a practical viewpoint, the need of ensuring 323 an adequate level of spatial refinement both in the grid planes normal to the rotor axis and in 324

the axial direction would have required a grid with more than 100 million elements for athree-blade rotor, which was beyond the resources available for this project.

To further reduce the computational cost of the 3D simulation, the central symmetry of 327 H-Darrieus rotors was exploited, enabling to simulate only one half of the rotor flow, thus 328 halving computational costs. Consequently, the aspect ratio (AR) of the simulated blade 329 portion is 8.74 which is half that of the actual blade. The modeled blade portion was 330 331 contained in a cylindrical domain (Fig. 1) of radius  $\Phi=240R$ , a value chosen to guarantee a full development of the wake, based on the sensitivity analyses reported in [53]. The domain 332 height was set to  $\Psi=2.53H$ , corresponding to half the height of the wind tunnel where the 333 334 original 3-blade model was tested [24,54]; measured data from these tests were previously used for validating the robustness of the RANS CFD methodology [26,53] also used in the 335 present study. 336

The 3D structured multi-block grid (2D and 3D views are reported in Fig. 2) was 337 obtained with the software ANSYS<sup>®</sup> ICEM<sup>®</sup> by first generating a 2D mesh past the airfoil 338 using the optimal mesh settings identified in [47,49], and then extruding this mesh in the 339 spanwise (z) direction and filling up with grid cells the volume between the blade tip and the 340 upper (circular) farfield boundary. The far-field boundary condition enforced on the lateral 341 (cylindrical) boundary and the upper boundary of the domain is based on suitable 342 combinations of one-dimensional Riemann invariants and user-given freestream data, namely 343 pressure, density and velocity components. The sub-set of these far-field data combined with 344 345 suitable Riemann invariants depends on whether the fluid stream enters or leaves the computational domain at the considered boundary point (the code detects automatically 346 347 inflow and outflow points of the boundaries at each iteration). The complete definition of this far-field boundary condition is provided in [55]. On the blade surface, a no-slip condition is 348 enforced. Since the equations are solved in the absolute frame of reference, this requires 349 350 imposing that the fluid velocity at the blade surface equals the velocity of the blade surface itself at the considered wall point, where pressure and density are extrapolated from the 351 interior domain. The 2D grid section normal to the z-axis and containing the airfoil (Fig. 2(a)) 352 consisted of  $4.3 \times 10^5$  quadrilateral cells. The airfoil was discretized with 580 nodes and the 353 first element height was set to  $5.8 \times 10^{-5} c$  to guarantee a dimensionless wall distance  $y^+$  lower 354 than 1 throughout the revolution. As recommended in [25], a fairly high mesh refinement of 355 both leading and trailing edge regions was adopted (Fig. 2(b)), and a high refinement in the 356 airfoil region within one chord from the airfoil surface was also used to resolve the separated 357 flow regions at high angle of attack (AoA) [27]. After extrusion in the z direction, 80 grid 358 layers in the half-blade span were formed (Fig. 2(c)), with progressive grid clustering from 359 360 midspan to tip to ensure an accurate description of tip flows. A fairly high grid refinement was also adopted in the whole tip region above the blade in order to capture the flow 361 separation and the tip vortices. The final mesh consisted of 64 million hexahedral cells. 362

The rotor flow field was computed by solving the system of governing equations corresponding to Eq. (1), that is by solving the RANS and SST equations in the absolute frame of reference. In such frame, the entire body-fitted grid rotates past the rotor axis, the additional flux components due to the grid motion is accounted for by the term  $-\underline{v}_b \mathbf{U}$ appearing in Eq. (3), and no sliding surface is required.

To keep computational costs within the limits of the available resources, only one operating condition was simulated, corresponding to a tip-speed ration (*TSR*) of 3.3. This condition corresponds to the same revolution speed already analyzed by some of the authors for the 3-blade turbine in [53]. For a 1-blade rotor, this TSR corresponds to a different point of the rotor power curve. The operating condition corresponding to this TSR, however, was considered of particular interest also for the 1-blade rotor because, also in this case, a) it corresponds to fairly high efficiency and thus a regime at which the rotor is expected to work more often than at other TSRs, and b) it features several complex aerodynamic phenomena (e.g. stall and strong tip vortices) posing a significant modelling challenge for the CFD analysis. Figure 3 displays the power coefficient at *TSR*=3.3 evaluated with the CFD analysis reported below on the expected power curve, which was calculated with a computationally more affordable code based on Lifting Line Theory coupled to a free vortex wake model. The model was successfully tuned on this case-study in [56] and thus it is expected to provide a power curve prediction fairly consistent with the CFD analysis reported below.

382 The free-stream wind speed was U=9.0 m/s. The turbulence farfield boundary 383 conditions were a turbulent kinetic energy (*k*) based on 5% turbulence intensity and a 384 characteristic length of 0.07 m.

The 3D and 2D simulations reported below were performed with the time-domain 385 solver of COSA. The 3D simulation was run on an IBM BG/Q cluster [57] featuring 8,144 386 16-core nodes for a total of 98,304 cores. Exploiting the outstanding parallel efficiency of 387 COSA, the simulation could be carried out using about 16,000 cores. This required 388 partitioning the grid into 16384 blocks using in-house utilities, and this operation was 389 performed starting from a grid with fewer blocks generated with the ANSYS<sup>®</sup> ICEM<sup>®</sup> grid 390 generator. All grid blocks had identical number of cells to optimize the load balance of the 391 392 parallel simulation. Using a time-discretization yielding 720 steps per revolution, the simulation needed 12 revolutions to achieve a fully periodic state. The flow field was 393 considered periodic once the difference between the mean torque values of the last two 394 revolutions was smaller than 0.1% of the mean torque in the revolution before the last. The 395 wall-clock time required for this 3D simulation was about 653 hours (27.2 days). 396

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## 2.4 Grid and time-step sensitivity analyses

One of the key elements of this study is that the 3D calculation was carried out using a high level of spatial and temporal resolution. The 3D grid used to carry out the analyses reported in Section 3 was obtained by extruding in the third direction the  $4.3 \times 10^5$ -element 2D grid described above, and such grid was shown to provide accurate and grid-independent results in [53].

To assess the impact of using coarser spatial and temporal refinement on the computed solution, the considered flow regime was also simulated using only 360 steps per revolution and a coarser 3D grid with 8 million elements, obtained from the 64million element fine grid by removing every second line in all three directions.

The periodic profiles of the instantaneous torque coefficient  $C_t$  obtained with the coarse and fine grids are compared in Fig. 4, and the definition of  $C_t$  is provided by Eq. (5), in which *T* denotes the instantaneous torque on the entire blade,  $U_{\infty}$  and  $\rho_{\infty}$  denote respectively the farfield wind speed and the air density, *c* is the blade chord, and H is the overall blade length. The angular position  $\vartheta=0^\circ$  corresponds to the blade leading edge facing the oncoming wind and entering the upwind half of its revolution.

414  $C_{t} = \frac{T}{\frac{1}{2}\rho_{\infty}U_{\infty}^{2}c^{2}H}$  (5)

The comparison shows that differences between the two predictions occur over most parts of the period, particularly around the maximum values of  $C_t$ . These discrepancies are caused by differences in the prediction of strength and timing of stall on the airfoils and under-resolved wakes and wake/blade interactions when using the coarse grid. The position of the curve peak (maximum  $C_t$  in the upwind region of rotor trajectory) predicted by the coarse grid has an error of about 3 degrees in azimuthal coordinates, leading to a shift of the 421 curve in the range between  $\vartheta = 90^{\circ}$  and  $\vartheta = 300^{\circ}$ . Such discrepancies, reported in Fig. 4 also as 422 the difference between the coarse and fine grid profiles normalized by the revolution-423 averaged mean torque of the fine grid (curve labeled "% variation") result in the mean torque 424 coefficient obtained with the coarse grid being 3.2 percent higher than that obtained with the 425 fine grid. As discussed in the following, this difference corresponds to nearly 40 percent of 426 the energy efficiency loss due to finite blade length effects. This highlights the importance of 427 using a fine grid for this type of analyses.

The impact of the mesh refinement on the resolution of some of the 3D flow 428 phenomena occurring during the revolution are examined in Fig. 5. This figure shows the 429 extent of the vortices generated at the blade tip at  $9=80^{\circ}$  predicted with the two meshes. The 430 red and blue vortices represent the regions of ascending and descending flow, respectively. 431 The higher dissipation of the coarse mesh leads to an under-prediction of the downstream 432 propagation of the vortex, which is reduced from about three chords (Fig 5(b)) to less than 433 two chords (Fig 5(a)). The coarse grid under-estimation of the tip effects contributes to the 434 overestimation of the torque highlighted in Fig. 4. The vorticity contours at midspan when 435 the blade is at  $9=315^{\circ}$  are compared in Fig. 6 to assess the resolution of the free convection of 436 vorticity in the downstream region. With the finer mesh the wake is resolved more sharply, 437 thus fulfilling essential prerequisites for adequately resolving blade-wake interactions in the 438 downwind part of the revolution. The under-resolution of the wake in the downwind rotor 439 region contributes to the higher torque produced by the blade when interacting with the wake 440 shed in the upstream trajectory. The impact of all these vortical phenomena on the rotor 441 performance is even higher in multi-blade rotors, due to higher number of interactions (and 442 thus energy loss events) per revolution. 443

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### 445 **3. Results and discussion**

Figure 7(a) reports the instantaneous torque coefficient per unit length  $(C_{tz})$  at different span lengths along the blade (0 percent and 100 percent correspond to midspan and tip, respectively). The instantaneous torque coefficient per unit length  $C_{tz}$  is defined by Eq. (6). Here  $T_z$  denotes the instantaneous torque per unit blade length at the considered spanwise position.

$$C_{tz} = \frac{I_{z}}{\frac{1}{2}\rho_{\infty}U_{\infty}^{2}c^{2}}$$

(6)

Figure 7(b) reports three torque profiles. The profile labelled 2D refers to the results of 452 a 2D simulation of the same rotor, and corresponds to the "ideal" torque of a blade with 453 infinite span, i.e. without any secondary effects at the blade tip. This 2D simulation was 454 carried out using a mesh equal to the midspan section of the 3D fine mesh and the same 455 numerical parameters of the 3D simulations. The torque profile labelled "0%" is the torque 456 per unit blade length at midspan of the finite-length rotor, whereas the torque profile labelled 457 3D is the overall torque coefficient  $C_t$  of the 3D rotor defined in Eq. (7). The result obtained 458 by using this definition is identical to that obtained by using Eq. (5). 459

460 
$$C_t = \frac{2}{H} \int_{0}^{\frac{H}{2}} C_{tz} dz$$
 (7)

461 Examination of these profiles reveals several important facts. Firstly, the ideal 2D 462 torque and the 3D torque profiles are characterized by similar patterns, including the

occurrence of two relative maxima, one in the upwind the other in the downwind regions, and 463 also similar azimuthal positions of both maxima: the maximum torque in the upwind portion 464 of the revolution is located at  $\vartheta \approx 88.5^{\circ}$  and the maximum torque in the downwind portion of 465 the revolution is located at  $\vartheta \approx 257^{\circ}$  in both cases. This behaviour is in line with the analyses 466 of both Lam [33] and Alaimo [40], which showed that the periodic torque profiles obtained 467 with 2D and 3D simulations differ significantly for their amplitudes but have comparable 468 shapes. Figure 7(b) also highlights that the differences between the 2D torque profile and that 469 at midspan of the 3D rotor are negligible, highlighting that 3D flow effects due to tip flows 470 471 do not reach this position.

472 Examination of all profiles of Fig. 7(b) shows that the effects of blade finite-length effects are very small when the blade loading is low, i.e. when the angle of attack is low 473  $(0^{\circ} < 9 < 40^{\circ} and 130^{\circ} < 9 < 210^{\circ})$ : in these portions of the revolution, the 2D and both 3D curves 474 are almost superimposed. When the incidence increases, the blade load also increases and the 475 blade starts experiencing stall. Figure 8 reports the top view of the vorticity contours at 476 midspan at three azimuthal positions to examine the onset of stall in the upwind zone. At 477  $\vartheta$ =70° a small separation region forms on the suction side of the blade. At  $\vartheta$ =80° the blade 478 stall has become significant, since the flow is detached from the blade. At the position of 479 torque peak a large region of the suction surface is affected by stall. Consequently, the torque 480 loss due to tip effects also increases because the strength of tip vortex flow increases with the 481 flow incidence. The same behaviour can be seen also in the downwind zones. Closer 482 inspection of the 2D and mean 3D CP curves shows that these effects are strongest in the 483 upwind region of the period, where a maximum difference of 9.7 percent between the torque 484 485 peaks occurs.

- Examining the torque profiles at the spanwise positions considered in Fig. 4(a), some additional observations can be made:
- The torque profiles of the blade sections at 20%, 40% and 50% semispan are almost identical, indicating that at least half of the blade is characterized by a predominantly 2D flow with negligible impact of tip flow effects;
- The torque profiles of the blade sections at 60%, 70% and 80% show a progressive reduction of the torque peak, down to -14 percent with respect to the midspan section.
   The remainder of the torque curve is less affected, especially in the downwind zone;
- The torque profiles of the blade sections at 90%, 95% and 97.5% show that at these
   positions, 3D effects are strong throughout the whole revolution. Notably, in the
   regions of positive torque production, the efficiency is remarkably reduced;
- In proximity of the blade tip (99%), almost no positive contribution to the torque output is given, due to the large load reduction;
- The azimuthal position of the torque peak occurs later in the cycle as one moves towards the tip, with a 5° shift between the 0% and 97.5% sections. This can be explained with a reduction of the incidence angle (downwash), as shown below. The experiments of Li et al. [35] highlight the same trend and show that the aforementioned shift is even more pronounced for a turbine with a very low aspect ratio (AR=4.5).

To compare the CFD prediction of the impact of finite blade effects on turbine 504 performance to that of the widespread low-fidelity BEM theory, Fig. 9 compares the 2D and 505 mean 3D torque profiles obtained with NS CFD and the corresponding estimates obtained 506 with the VARDAR research code, a state-of-the-art BEM code developed at the University of 507 Florence [6,17-18] using the ubiquitous Leicester-Prandtl model for the finite-wing 508 correction [58]. The two BEM profiles of Fig. 9 differ in that one includes tip flow corrections 509 and the other does not. Examination of these profiles shows that the reduction of the torque 510 peak in the upwind portion of the revolution predicted by the CFD analyses is in good 511 agreement with that estimated with the simplified tip flow model included in the BEM 512

theory, and the shapes of the CFD and BEM torque profiles are in a qualitatively good agreement. Conversely, the patterns of the torque curves in the downwind portion of the revolution predicted by the BEM and CFD analyses are significantly different, and the torque reduction due to blade finite length predicted by the BEM analysis is higher than predicted by CFD. This comparative analysis highlights the potential of using CFD also for further improving the predictions of low-fidelity engineering tools, which are key to Darrieus rotor industrial design due to their extremely small computational requirements.

To provide a different quantitative perspective of the impact of tip losses, Fig. 10 520 compares the CFD and BEM profiles of mean torque coefficient per unit length. For each 521 522 blade height the mean value is obtained by averaging the profiles of Fig. 4(a) over one revolution. The figure also reports the constant mean torque values of the 2D and 3D 523 simulations for both the CFD and BEM models. All curves are normalized with respect to the 524 mean 2D torque coefficient.One sees that the mean blade performance is almost unaffected 525 by tip-effects up to approximately 70% semispan. More specifically, it is found that tip flow 526 effects adversely affect the performance of the blade for a span length of approximately 2.6c 527 (yellow zone in Fig. 10). In terms of aggregate data, the tip effects yield a reduction of the 528 rotor torque of 8.6% with respect to the 2D calculation with virtually infinite span. This can 529 be seen as an equivalent reduction of the actual blade's height of 0.75c for each half blade 530 (red colored zone in Fig. 10). Such a correction factor needs to be accounted for when 531 estimating the turbine performance by means of 2D simulations. 532

The observations above are in accordance with the findings of Li e al. [35] in terms of 533 performance drop as a function of the distance from the tip. Their experiments showed that at 534 535 55% semispan, corresponding to a distance of 1.0c from the tip, the torque peak is greatly reduced. At this blade height, they found a CP reduction of 40% over the midspan value at 536 TSR=2.2 and 60% at TSR=2.5, corresponding to an equivalent reduction of the actual blade's 537 538 height by 1.8c and 2.7c, respectively. Other analyses focused on estimating the mean power reduction due to finite blade length effects through comparisons of 2D and 3D CFD analyses 539 [32,33,37,40], but their results are not directly comparable with the present study due to the 540 use of different aspect ratio, rotor solidity, TSR, airfoil geometry and number blades.. 541 Overall, the equivalent height reduction can vary from 0.8c for a NACA 0022 three-blade 542 rotor at TSR=1.3 [32] up to 5c for a NACA 0018 two-blade rotor at TSR=4.5 [33]. 543

To investigate in greater detail the 3D phenomena accounting for energy efficiency reduction, the Mach contours and streamlines at the angular position of maximum separation  $(\vartheta=120^\circ)$  are examined in Fig. 11(a). Different spanwise sections are considered to analyse the flow pattern alterations from midspan to the blade tip.

548 In the central portion of the blade (from midspan to about 70% semispan) the streamlines are contained in planes orthogonal to the blade axis, indicating a predominantly 549 2D flow character, and a fairly large region of separated flow in the rear of the suction side. 550 Closer to the tip (90% semispan) the downwash due to the tip flow reduces the effective AoA 551 with respect to that at midspan, and the extension of the stall region is thus reduced. The skin 552 friction lines and contours of the z velocity component (w) on the blade suction surface 553 reported in Fig. 11(b) show the extension of the region affected by downwash. Near the tip, 554 the flow on the pressure side is no longer able to follow the blade profile, and travels over the 555 tip due to the pressure difference between the pressure side and the suction side. The tip 556 vortex flow is responsible for the downwash velocity component and therefore for the 557 incidence variation along the span, in accordance with the theory of finite wings [58]. It is 558 noted that the finite wing effects occurring in Darrieus rotors are more complex than those 559 560 encountered in fixed finite wings. This is primarily because of the flow curvature associated with the circular trajectory of the blade, and also the flow nonlinearities due to dynamic stall. 561

To quantify the impact of these effects, it is convenient to examine the curves of the 562 torque coefficient per unit length at midspan and 90% semispan (Fig. 12). The percentage 563 difference between the two curves (i.e. the torque coefficient difference between the curves at 564 each azimuthal angle divided by the revolution-averaged torque coefficient at midspan) is 565 also reported to quantify the dependence of the torque variation on the azimuthal position. A 566 notable torque reduction occurs in the interval  $40^{\circ} < 9 < 130^{\circ}$ . In addition, a large and sudden 567 torque reduction occurs towards the end of the revolution, in the interval  $315^{\circ} < 9 < 340^{\circ}$ , a 568 range in which the AoA is decreasing and goes below the value yielding stall. Also, an 569 inversion in the expected trend is noticed close to  $\vartheta$ =150°, where the tip section performs 570 571 better than the midspan section: the torque of the section at 90% semispan is about 10 percent higher than that at midspan. According to the finite wing theory, the lift should be in fact 572 always reduced in proximity of the tip. Therefore, the inversion at  $\vartheta$ =150° cannot be 573 explained with this theory alone. This occurrence and the sudden torque loss of the tip section 574 towards the end of the revolution are analysed in further detail below. 575

To investigate the origin of the sudden torque reduction at the blade tip in the interval 576 315°<9<340°, isosurfaces of the turbulent kinetic energy field at selected azimuthal positions 577 are examined in Fig. 13. The color scale is based on the intensity of the velocity component 578 along the z-axis (w). Three azimuthal positions of the blade are considered:  $\vartheta = 60^{\circ}$ ,  $\vartheta = 180^{\circ}$ 579 and  $\vartheta$ =315°. During the upwind half of the revolution ( $\vartheta$ =60°) the tip vortex is strong, since 580 the vertical component of velocity is fairly high. A high turbulence region is then generated 581 from the blade tip. At  $\vartheta$ =180°, the region of high turbulent kinetic energy corresponding to 582 the tip vortex is increased in size and length, and is still associated with large values of w. 583 This strong vortex detaches from the blade, is convected by the wind, and is re-encountered 584 by the blade at  $9=315^{\circ}$ . The blade interaction with this vortex induces a more pronounced 585 reduction of the torque with respect to the 2D case, where this effect is absent. 586

587 To investigate the reasons for the higher torque of the 90% section over the midspan section at  $\vartheta$ =150°, top views of the streamlines at  $\vartheta$ =150° and  $\vartheta$ =48° are examined in Fig. 14. 588 The position  $9=48^{\circ}$  is selected because this is the other angular position of the upwind half of 589 the revolution experiencing the same AoA of  $\vartheta$ =150°. Streamlines on both the pressure and 590 suction sides of the blade are visualized at four different span locations. At  $9=48^{\circ}$  the 591 downwash effect is visible: moving from midspan to the tip, the incidence of the oncoming 592 flow decreases and the air stream after the trailing edge is more aligned to the airfoil chord. 593 This phenomenon is not very pronounced due to the low loading on the blade at this angular 594 position. At  $9=150^{\circ}$ , moving from midspan to the tip, the incidence of the oncoming flow is 595 progressively reduced similarly to what seen at  $9=48^{\circ}$ . However, the flow pattern on the 596 suction side of the central portion of the blade is significantly different from that at  $9=48^{\circ}$ , 597 despite the fact that the AoA is similar in the two cases. A large separation region exists at 598  $\vartheta$ =150° due to stall. Due to the finite wing length, a strong modification of this flow pattern is 599 observed moving towards the tip: from 70% semispan, the flow is attached due to lower 600 downwash-induced loading and is more aligned to the airfoil chord after the trailing edge. 601

The observations above can be explained by a combined effect of downwash and 602 dynamic stall. From  $\vartheta = 0^{\circ}$  to  $\vartheta = 90^{\circ}$  the AoA increases and stall in the central blade portion 603 occurs between  $9=70^{\circ}$  and  $9=80^{\circ}$ . The dominant effect is that of the downwash which 604 reduces the AoA to the outer portion of the blade. When the AoA reaches its maximum 605 towards  $\vartheta = 90^\circ$ , the central portion of the blade experiences high level of stall. From  $\vartheta = 90^\circ$  to 606  $\vartheta$ =180° the AoA decreases but the central portion of the blade remains stalled due to delay of 607 the flow in readjusting to the decreasing incidence (a distinctive feature of dynamic stall). 608 However, the outer sections of the blade remain stall-free, and this is the reason why at 609  $\vartheta$ =150° the torque of the tip sections is higher than that of the midspan section, whereas the 610 opposite is observed at  $9=48^{\circ}$ . 611

Fig. 15 presents an analysis of the same type of that of Fig. 14 for the angular positions  $\vartheta = 210^{\circ}$  and  $\vartheta = 300^{\circ}$ . Both positions belong to the downwind portion of the rotor trajectory and are characterized by a comparable AoA. However at  $\vartheta = 210^{\circ}$  the AoA is increasing whereas at  $\vartheta = 300^{\circ}$  the AoA is decreasing. One notices that the streamline pattern at  $\vartheta = 210^{\circ}$  is similar to that at  $\vartheta = 48^{\circ}$ . At  $\vartheta = 300^{\circ}$  the streamline patterns from midspan to tip are the same as those at  $\vartheta = 210^{\circ}$ . The similarity of the flow patterns at these two positions is due to the fact that no stall occurs in the downwind portion of the rotor trajectory.

Fig. 16 depicts the blade streamlines at  $\vartheta$ =315°, the position at which the tip vortex interacts with the outboard portion of the blade in its downwind trajectory, as highlighted in Fig. 13. One observes a sudden deviation of the oncoming flow in the tip region with respect to the flow direction at midspan. Such deviation is due to the blade-vortex interaction, which prevails over the effects due to downwash.

All aforementioned results can be more quantitatively described by evaluating the pressure coefficient  $(C_p)$  distributions and the vorticity contours along the blade. The pressure coefficient used in this study is defined by Eq. (7), where *p* denotes the static pressure at the airfoil surface. Due to the difficulty of properly defining the actual relative wind speed at each blade height, the relative flow velocity  $w_{th}$  used to calculate  $C_p$  neglects the induced velocity and is computed using the vectorial sum of the absolute free-stream velocity and entrainment velocity  $\Omega R$ .

Fig. 17 reports the  $C_p$  profiles at different blade heights for three key angular positions: maximum loading ( $\vartheta$ =80°), inversion of torque of midspan and tip sections ( $\vartheta$ =150°) and maximum loading in the downwind half of the revolution ( $\vartheta$ =240°). The objective of this analysis is to highlight the impact of downwash and stall at different angular positions.

$$C_{p} = \frac{p - p_{\infty}}{\frac{1}{2}\rho_{\infty}w_{th}^{2}}$$
(7)

636 At  $9=80^{\circ}$  the blade is subject to high loading (high AoA and high relative speed). The top subplot of Fig. 17 confirms that, in these conditions, 3D flow effects affect almost 40 637 percent of the blade (from the tip to 60% semispan), since moving from midspan to the tip, 638 the  $C_p$  profile at 60% already shows a slight loading reduction with respect to midspan. 639 Closer to the tip, the suction side of the blade is characterized by an almost constant pressure, 640 indicating that this blade portion generates a small lift. As a result, the torque of the tip 641 sections is substantially lower than that of the midspan section, and the torque becomes 642 negative at 97.5% midspan, as shown in Fig. 7. At 9=240° (middle subplot of Fig. 16) the 643 AoA is high but the relative speed magnitude is lower than at  $9=80^{\circ}$ . In these conditions 3D 644 flow effects affect only the last 20 percent of the semispan (i.e. from 80% semispan to tip): 645 646 significant differences in the  $C_p$  profiles with respect to the midspan values are observed only on the last 10 percent of the blade, where the loading becomes significantly smaller than at 647 midspan. Unlike at the two angular positions just discussed, a strong flow separation due to 648 stall occurs at  $\vartheta$ =150° (bottom subplot of Fig. 17). This is highlighted by the pressure profiles 649 at 0% and 60% semispan, which feature a fairly shallow slope on the suction side. In this 650 651 circumstance, the lower AoA at the tip sections induced by the tip vortex-related downwash 652 results in the flow past such tip sections remaining attached and these sections outperforming the midspan region of the blade. 653

The evolution of the vorticity contours at different blade span heights is presented in Fig. 18. In the upwind half of the revolution, the two positions  $\vartheta=40^{\circ}$  and  $\vartheta=140^{\circ}$  are of particular interest. Although at these two positions the torque profiles along the blade are comparable (see Fig. 7(a) and Fig. 7(b)), the vorticity patterns and thus the flow field are remarkably different. On the other hand, moving to the downwind half of the revolution, one sees that the vorticity patterns around the blade are quite similar at all azimuthal positions.
These patterns are in line with the previous analyses of streamlines and pressure coefficient
profiles.

Figure 19 reports the top view of the vorticity contours at four different span locations at the two aforementioned azimuthal positions and highlights the vorticity differences in greater detail. At  $\vartheta$ =40° the vorticity contours are very similar, moving from midspan to tip, whereas at  $\vartheta$ =140° the large separation region due to stall is clearly visible along a large central portion of the blade.

# 668 **4.** Conclusions

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A 3D time-accurate Reynolds-averaged Navier-Stokes CFD analysis of an aspect ratio 669 17.5 blade rotating in Darrieus-like motion has been presented. Special attention was paid to 670 the description of 3D flow effects and their impact on the energy efficiency of Darrieus rotor 671 672 blades. This was accomplished also by comparative analyses of 3D and 2D CFD analyses. The presented 3D CFD results were obtained with a highly refined analysis using a grid with 673 64 million elements and time-marching the flow field to a periodic state using 720 time-steps 674 per revolution. A 3D mesh sensitivity analysis was also presented. The main outcomes of the 675 analysis can be summarized as follows: 676

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- a) 3D flow effects due to finite blade length reduce the mean power of the considered 17.5 aspect ratio blade by 8.6 percent with respect to the torque of the corresponding infinite blade. Such mean torque reduction corresponds to a reduction of the effective blade length of 1.5c (0.75c for each half blade).
- b) A strong interaction between the tip-vortex released in the upwind portion of the blade revolution and the blade traveling in the downwind region occurs at  $\vartheta$ =315°, and this yields an additional reduction of the outboard blade sections in this region of the revolution.
- c) Finite blade length effects do not modify significantly the overall shape of the blade
  torque profile over the revolution with respect to the torque profile of the
  c) corresponding infinite blade;
- d) For given azimuthal position, the torque profile along the blade height varies substantially from midspan to tip, and the pattern of these variations strongly depends on the azimuthal position; i.e. on the magnitude of the relative velocity of the oncoming flow and its local angle of attack;
- e) The mean torque reduction predicted by the 3D CFD analysis and that of a state-of-the-art BEM analysis using tip loss corrections is comparable, but the profiles of the blade torque in the downwind portion of the revolution differ significantly. The reliability of BEM analyses may be improved by using 3D CFD results to develop azimuthal position-dependent tip loss corrections;
- f) The 3D grid sensitivity analysis highlighted that the use of a coarser grid, with size 697 comparable to those used in most 3D Darrieus studies to date, may yield uncertainty 698 levels in the prediction of tip vortex flows, blade/wake/tip vortex interactions, and 699 dynamic stall timings and strength. All these phenomena affect torque and power 700 generation. The mean power predicted by a typical coarse grid and the fine grid of 701 this study differed by more than 3 percent. and significantly larger differences are 702 expected for multi-blade rotors due to higher number of blade/wake/tip vortex 703 704 encounters per revolution.

Future work will include investigating 3D flow effects at different tip-speed ratios, particularly the lower ones, at which the impact of dynamic stall is expected to be more pronounced than at the considered regime, and extending this analysis to multi-blade turbines, to assess in detail all aspects of wake/blade interactions. This type of high-fidelity analyses provides valuable data for validating and further improving the reliability of lowfidelity tools such as BEM codes and codes based on lifting line theory and free vortex transport methods. Due to their extremely high execution speeds, these engineering tools are of crucial importance to improving the design of future small and large Darrieus turbines.

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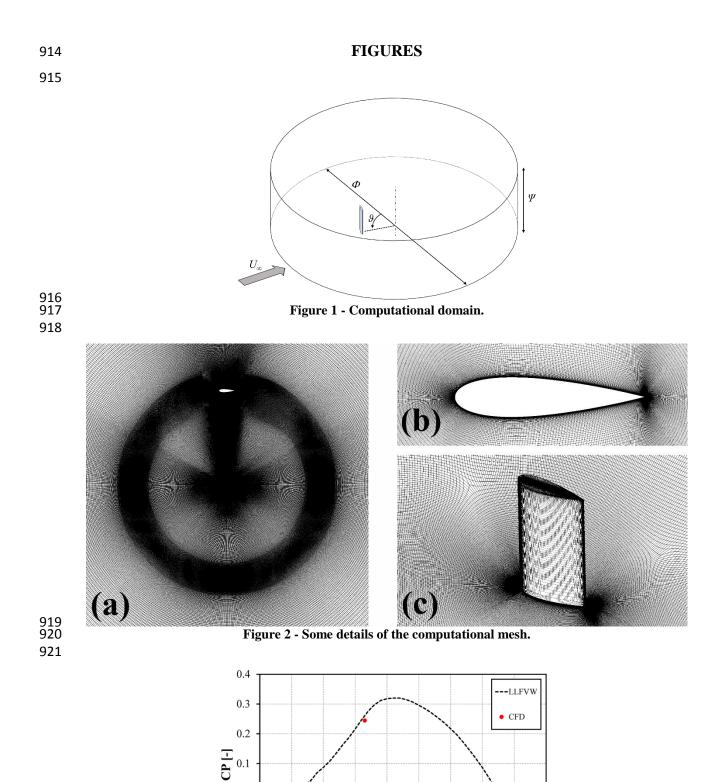
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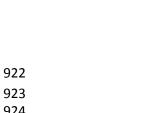
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Figure 3 - Attended power curve of the 1-blade model.

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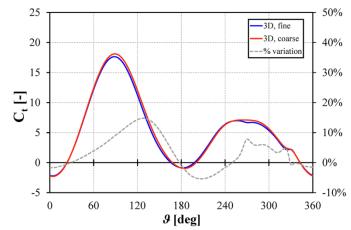


Figure 4 - Differences in the torque profile between the selected mesh and a coarser one.

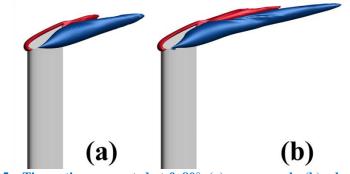


Figure 5 – Tip vortices generated at  $9=80^{\circ}$ : (a) coarse mesh; (b) selected mesh.

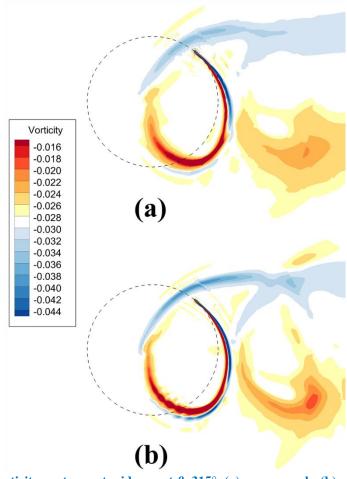
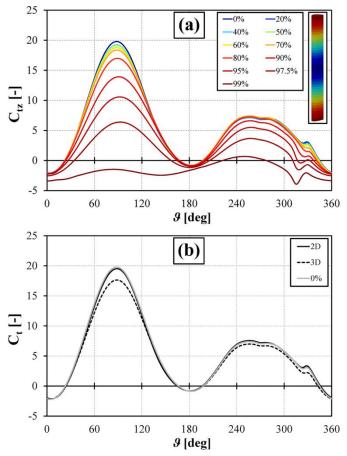
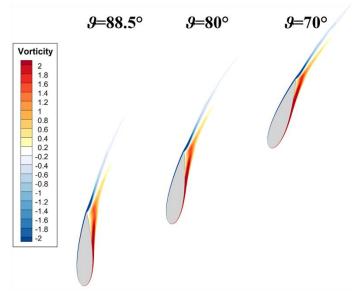


Figure 6 - Vorticity contours at midspan at  $9=315^{\circ}$ : (a) coarse mesh; (b) selected mesh.

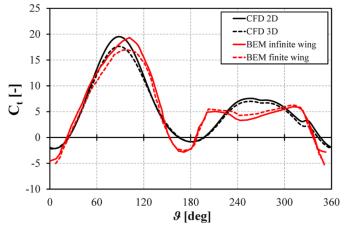


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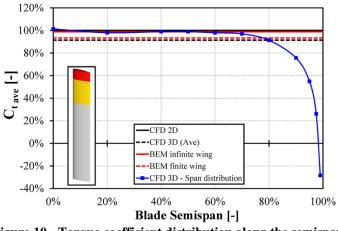
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Figure 8 - Vorticity contours at midspan: *9*=70°, *9*=80° and *9*=88.5°.



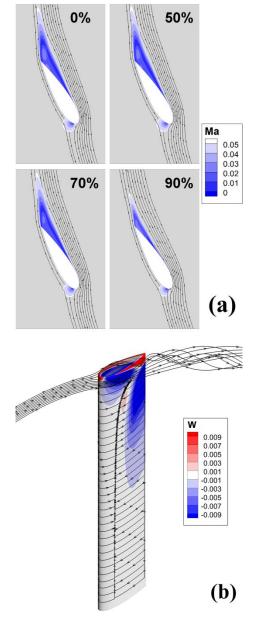
9419 [deg]942Figure 9 - Torque coefficient profiles: 2D and 3D CFD data vs. BEM simulations either including or943neglecting the finite-wind effects.





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Figure 10 - Torque coefficient distribution along the semispan.



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 949 Figure 11 – Downwash effect at *9*=120°: (a) Mach contours and streamlines at different semispan
 950 locations; (b) flow streamlines in the tip region, skin friction lines and z velocity component on the blade
 951 suction surface.
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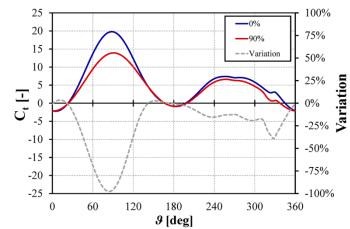


Figure 12 - Comparison of torque coefficient curves at 0 and 90 percent semispan.

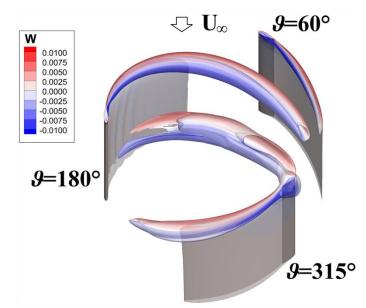


Figure 13 - Isosurfaces of turbulent kinetic energy *k* colored with the contour of *w*.

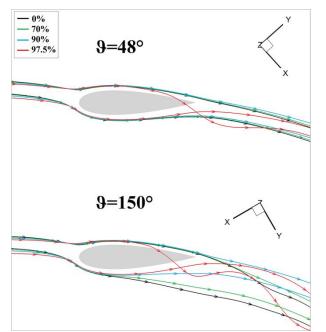


Figure 14- Streamlines at different span lengths: 9=48° and 9=150°.



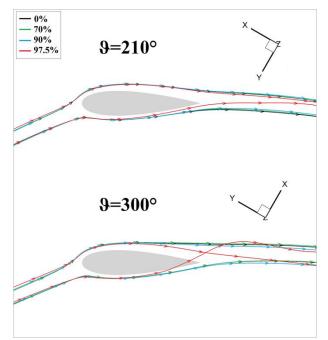


Figure 15 - Streamlines at different span lengths:  $\vartheta$ =210° and  $\vartheta$ =300°.

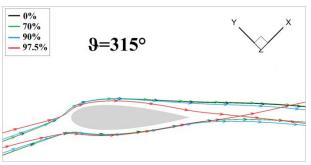


Figure 16 - Streamlines at different span lengths: 9=315°.

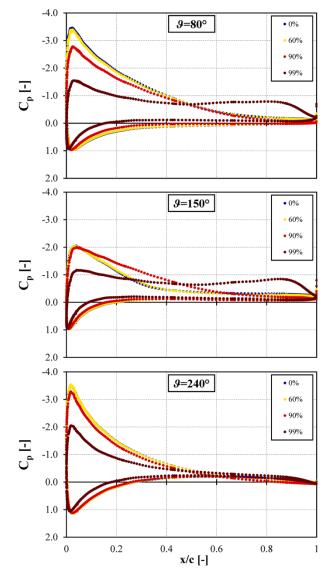


Figure 17 - Pressure coefficient profiles at different span lengths:  $9=80^{\circ}$ ,  $9=150^{\circ}$  and  $9=240^{\circ}$ .

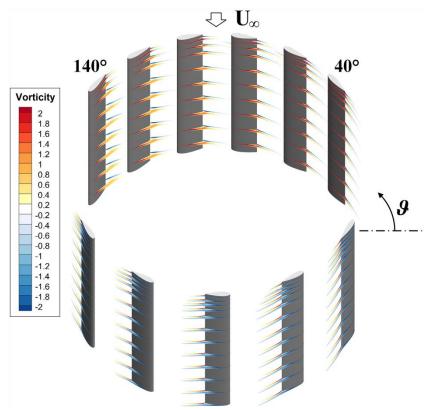


Figure 18 - Vorticity contours at different span lengths during the revolution.

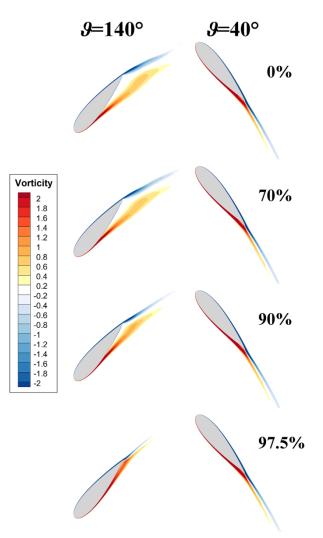


Figure 19 - Vorticity contours at different semispan locations:  $9=40^{\circ}$  and  $9=140^{\circ}$ .

# Darrieus Wind Turbine Blade Unsteady Aerodynamics: a Three-Dimensional Navier-Stokes CFD assessment

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## 17 Abstract

Energized by the recent rapid progress in high-performance computing and the growing availability of large computational resources, computational fluid dynamics (CFD) is offering a cost-effective, versatile and accurate means to improve the understanding of the unsteady aerodynamics of Darrieus wind turbines, increase their efficiency and delivering more costeffective and structurally sound designs.

23 In this study, a Navier-Stokes CFD research code featuring a very high parallel efficiency was used to thoroughly investigate the three-dimensional unsteady aerodynamics 24 of a Darrieus rotor blade. Highly spatially and temporally resolved unsteady simulations were 25 carried out using more than 16,000 processor cores on an IBM BG/Q cluster. The study aims 26 at providing a detailed description and quantification of the main three-dimensional effects 27 associated with the periodic motion of this turbine type, including tip losses, dynamic stall, 28 vortex propagation and blade/wake interaction. Presented results reveal that the three-29 dimensional flow effects affecting Darrieus rotor blades are significantly more complex than 30 assumed by the lower-fidelity models often used for design applications, and strongly vary 31 during the rotor revolution. A comparison of the CFD integral estimates and the results of a 32 blade-element momentum code is also presented to highlight strengths and weaknesses of 33 low-fidelity codes for Darrieus turbine design. 34

The reported CFD results provide a valuable and reliable benchmark for the calibration of lower-fidelity models, which are still key to industrial design due to their very high execution speed.

38

## 39 Keywords

- 40 Darrieus wind turbine, unsteady Navier-Stokes simulations, CFD, tip flows
- 41

#### 42 Nomenclature

43	<u>Latin symbols</u>		
44	AoA	angle of attack	
45	AR	aspect ratio	[-]
46	С	blade chord	[m]
47	$C_t$	torque coefficient	[-]
48	$C_p$	pressure coefficient	[-]
49	CP	power coefficient	[-]
50	BEM	Blade Element Momentum	
51	CFD	Computational Fluid Dynamics	
52	Н	turbine height	[m]
53	k	turbulent kinetic energy	$[m^{2}/s^{2}]$
54	NS	Navier-Stokes	
55	р	static pressure	[Pa]
56	PDEs	Partial Differential Equations	
57	R	turbine radius	[m]
58	RANS	Reynolds-Averaged Navier-Stokes	
59	SST	Shear Stress Transport	
60	Т	torque per unit length	[Nm]
61	TSR	tip-speed ratio	[-]
62	и, v, w	Cartesian components of local fluid velocity vector	[m/s]
63	U	magnitude of absolute wind speed	[m/s]
64	<u>V</u>	local fluid velocity vector	[m/s]
65	$\frac{-}{v_b}$	local grid velocity vector	[m/s]
66	VAWTs	Vertical-Axis Wind Turbines	
67	W	magnitude of relative wind speed	[m/s]
68	<i>x</i> , <i>y</i> , <i>z</i>	reference axes	
69	$y^+$	dimensionless wall distance	[-]
70			
71	<u>Greek symbols</u>		
72	9	azimuthal angle	[deg]
73	$\mu_t$	turbulent viscosity	[Kg/m/s]
74	ρ	air density	[kg/Nm <sup>3</sup> ]
75	$\Phi$	computational domain diameter	[m]
76	Ψ	computational domain height	[m]
77	ω	specific turbulence dissipation rate	[1/s]
78	$\Omega$	turbine revolution speed	[rad/s]
79			
80	<u>Subscripts</u>		
81	$\infty$	value at infinity	
82	ave	averaged value	
83			

# 84 **1. Introduction**

85 *1.1 Background* 

After most research on vertical-axis wind turbines (VAWTs) came to a standstill in the mid 90's [1], the Darrieus wind turbine [2] is receiving again increasing attention of both researchers and manufacturers [3-6]. For distributed wind power generation in the built environment [7], inherent advantages of this turbine type, such as performance insensitivity 90 to wind direction, generator often positioned on the ground, low noise emissions [8], enhanced performance in skewed [9] or highly turbulent and unsteady flows [10-12], may 91 outweigh disadvantages, such as lower power coefficients and more difficult start-up, with 92 93 respect to typical horizontal axis machines. Moreover, in densely populated areas VAWTs are often preferred to other turbine types because they are perceived as aesthetically more 94 pleasant and thus easier to integrate in the landscape [13]. The applicability of Darrieus wind 95 96 turbines for utility-scale power generation making use of floating platforms also appears to 97 present important benefits in terms of overall dynamic stability [14].

Historically, the aerodynamic performance analysis of these rotors has been carried out with low-fidelity methods, like the Blade Element Momentum (BEM) theory [1,15-17] or lifting line methods [18-19]. More recently, however, the intrinsic limitations of these models made clear that higher-fidelity tools are needed in order to understand in greater depth the complex unsteady aerodynamics of Darrieus rotors [20], such as the interaction of the blades with macro vortices [21] or dynamic stall [22].

While experimental testing is often quite difficult and expensive, Navier-Stokes (NS) 104 Computational Fluid Dynamics (CFD) can be a versatile and accurate means to improve the 105 106 understanding of VAWT unsteady aerodynamics and achieve higher-performance, structurally sound and more cost-effective Darrius turbine designs. The use of NS CFD for 107 simulating time-dependent Darrieus turbine aerodynamics is rapidly increasing due to both 108 the ongoing development and deployment of more powerful high-performance computing 109 hardware, such as large clusters of multi- and many-core processors [23], and also the 110 development of computationally more efficient algorithms. 111

112 113

## 1.2 Previous CFD studies on Darrieus VAWTs

Early use of the Reynolds-Averaged Navier-Stokes (RANS) CFD technology for 114 Darrieus rotor aerodynamics for investigating the complex fluid mechanics of these machines 115 was based mostly on two-dimensional (2D) simulations (e.g. [24]). An extensive literature 116 review of 2D RANS CFD studies is provided by Balduzzi et al. [25], along with an overview 117 of the numerical settings frequently used for Darrieus rotor RANS studies and guidelines for 118 the optimal set-up of these simulations. Two-dimensional RANS analyses, suitably corrected 119 120 for three-dimensional (3D) effects, such as struts resistive torque and blade tip losses, have been used to estimate the turbine overall performance [26] and predominantly 2D 121 phenomena, like virtual camber [27] and virtual incidence [28] effects, the influence of 122 unsteady wind conditions on turbine aerodynamics [29], the evolution of the flow field at 123 start-up [30], and turbine/wake interactions [31]. 124

However, the use of 2D simulations to analyse the flow field past real rotors may result 125 in significant uncertainties, due to the difficulty of reliably quantifying complex 3D 126 aerodynamic features such as blade tip flows, their dependence on the blade tip geometry and 127 their impact on the overall efficiency as a function of the blade aspect ratio. Moreover, most 128 3D aerodynamic features of Darrieus rotor flows vary not only spatially (e.g. dynamic stall 129 decreases from midspan to the blade tips, as shown below), but also temporally during each 130 revolution. It is difficult to develop corrections to improve the predictions of time-dependent 131 2D CFD analyses, and the resulting uncertainty on unsteady loads may severely impair both 132 aerodynamic and structural (e.g. fatigue) assessments. Therefore 3D CFD simulations are key 133 to characterizing and quantifying the aforementioned 3D aerodynamic phenomena. This is 134 important for reducing the uncertainty associated with modeling such phenomena on the basis 135 of a relatively small amount of data referring to existing turbines, and assumptions based on 136 overly simplistic analytical models. However, large computational resources are needed for 137 such simulations, due to the high temporal and spatial grid refinement needed for accurately 138 139 resolving all design-driving aerodynamic phenomena.

140 Comparisons of 2D and 3D simulations are sometimes carried out considering test cases for which experimental data are available, as in Howell et al. [32] and Lam et al. [33]. 141 In [32] the use of 2D RANS CFD led to relatively poor agreement with experiments: a 142 maximum power coefficient CP of 0.371 at a tip-speed ratio (TSR) of 2.4 was predicted 143 against a measured maximum CP of 0.186 at TSR=1.85. Using 3D simulations, the 144 maximum power coefficient was instead correctly predicted, although the shape of computed 145 and measured power curves presented significant differences. The k- $\varepsilon$  re-normalization group 146 turbulence model [34] was used for all simulations, but no detailed information on the mesh 147 size was provided, except for the indication of a high dimensionless wall distance  $(y^+ \approx 10)$ 148 149 which required the use of wall functions. Also in [35] notable discrepancies between the results of 2D and 3D RANS simulations were observed: the 2D simulations predicted a 150 maximum power coefficient of 0.43 at TSR=4.5 against a maximum CP of 0.27 at TSR=1.85 151 predicted by the 3D analyses. A fairly coarse grid, consisting of 2.95 million elements was 152 used for the 3D simulations of the considered two-blade rotor, and the k- $\omega$  Shear Stress 153 Transport (SST) turbulence model [36] was used. 154

Gosselin et al. [37] used 2D and 3D RANS simulations with the  $k-\omega$  SST turbulence 155 model to investigate the dependence of 3D effects on the blade aspect ratio, finding that an 156 aspect ratio of 7 led to a relative efficiency drop of 60 percent with respect to the 2D analysis. 157 Although the simulations were performed with very refined meshes (up to 700 nodes on each 158 airfoil), the article reports that no rigorous mesh-independence was obtained. Joo et al. [38] 159 analysed the aerodynamic characteristics of a two-blade rotor as a function of design 160 parameters such as solidity and optimal TSR using the 3D RANS model coupled to a 161 realizable k- $\varepsilon$  turbulence model. They used a computational mesh of 1.2 million elements 162 and compared their baseline results with available experimental data: a general 163 overestimation of the power curve was noticed, with a 10% discrepancy at the peak power. 164 165 Moreover, significant shape differences of computed and measured power curves were observed, particularly in the right branch of such curves (i.e. for high TSR values), with the 166 measured curve being steeper than the computed one. A two-blade Darrieus rotor with 167 straight blades was analysed by Li et al. [35,39] by means of wind tunnel experiments and 3D 168 RANS simulations using the  $k-\omega$  SST turbulence model. Numerical results compared 169 favourably to experimental data in the left branch (i.e. low TSR values) of the power curve, 170 but CFD significantly overestimated power for higher TSR, possibly due to excessively small 171 distance between the rotor and the farfield boundaries of the physical domain (about 2 rotor 172 diameters from the rotor center). The simulations used a grid with about 5 million elements, 173 and predicted a peak power coefficient of 0.24 at TSR=2.09 whereas experiments showed a 174 175 peak *CP* of 0.18 at TSR=2.18.

Alaimo et al. [40] carried out a comparative study of the aerodynamic performance of 176 three-blade Darrieus rotors using straight and helical blades. For the three-blade rotors they 177 178 analysed, they found that blade tip vortex flows significantly reduced the rotor performance and that the use of helical blades significantly reduces this power loss. The largest grids used 179 for those 3D RANS analyses had about 10 million elements, and turbulence was modelled 180 using the k- $\varepsilon$  turbulence model with wall functions to enable the use of relatively coarse grids 181 and enhance numerical stability. De Marco et al. [41] performed 3D RANS simulations to 182 analyse the influence of the geometry of the blade supporting arms on the turbine 183 performance. Using grids featuring between 4 and 18 million elements and the k- $\omega$  SST 184 model, they found that inclined and aerodynamically shaped supporting arms can 185 significantly increase the mean power coefficient. Using computational meshes with up to 12 186 187 million elements and the k- $\omega$  SST model, Zamani et al. [42] characterized with 3D RANS simulations the impact of J-shaped blades on Darrieus rotor torque and power characteristics 188 at low and medium TSR values, finding that this blade shape significantly increases the rotor 189

190 performance in these regimes, resulting in improved start-up characteristics. Orlandi et al. 191 [43] used 3D RANS simulations and the  $k-\omega$  SST model to study the influence of skewed 192 wind conditions on the aerodynamic characteristics of a two-blade Darrieus turbine; to limit 193 the computational burden of the 3D analyses, grids with about 10 million elements were used.

A recent Navier-Stokes CFD study of a three-blade Darrieus rotor using pitching blades to further improve the aerodynamic performance has made use of a Large Eddy Simulation [44], an approach that can yield more accurate results than the RANS method. However, resolved LES analyses require computational grids far larger than those needed for gridindependent RANS analyses, and this makes the use of resolved 3D LES simulations even more difficult than that of grid-independent 3D RANS analyses.

The aforementioned 3D CFD analyses highlighted new important aerodynamic 200 phenomena, but in almost all cases limited availability of computational resources imposed 201 202 the use of fairly coarse spatial and temporal refinement, and this may result in uncertainty due to lack of complete grid-independence of the CFD solutions. Recent parametric analyses 203 investigating the impact of several numerical parameters on the computationally less 204 demanding 2D CFD analysis of Darrieus rotors [25,45-47] showed that the analysis reliability 205 206 - in terms of accuracy of both performance prediction and resolution of important flow structures - is tremendously affected by the quality of the meshing and time-stepping 207 strategies. These studies highlighted that the minimum temporal and spatial refinement 208 required to obtain grid-independent solutions is quite high, due to the aerodynamic 209 complexity of these unsteady flows. Because of these constraints, the computational cost of 210 reliable 3D unsteady NS analyses of Darrieus rotor flows is extremely large due to the 211 212 necessity of maintaining the high temporal resolution indicated by the 2D parametric studies and a high level of spatial refinement both in the grid planes normal to the rotor axis and the 213 3<sup>rd</sup> direction orthogonal to such planes. Refinement in the 3<sup>rd</sup> direction is essential to reliably 214 resolving 3D flow features. For example, the parametric study of [25] showed that temporal 215 and spatial grid-independent 2D RANS analyses of a three-blade rotor require grids with at 216 least 400,000 elements. To preserve the same accuracy level in a 3D RANS simulation of the 217 same turbine (modelling only half of the rotor making use of symmetry boundary conditions 218 on the plane at rotor midspan and ensuring adequate refinement in the tip region) the mesh 219 would consist of at least 90 million elements, which is almost ten times the size of the finest 220 meshes used in the 3D RANS studies of Darrieus rotor flows published to date. Failing to 221 maintain these refinement levels may reduce the benefits achievable by using 3D RANS 222 simulations to improve Darrieus rotor design. 223

224 225

## 1.3 Study aim

In this study, the COSA RANS research code, which features a very high parallel 226 efficiency, is used to investigate in great detail the 3D flow features of a rotating Darrieus 227 rotor blade and the impact of flow three-dimensionality on power generation efficiency. More 228 specifically, the study aims at providing a highly accurate analysis of the main 3D 229 phenomena occurring during each revolution of the considered one-blade rotor, including tip 230 vortices, dynamic stall and downstream vortex propagation, and to assess the impact of these 231 phenomena on the overall performance of this rotor. The use of a single rotating blade for the 232 type of analyses reported herein is not uncommon (see for example [40]). This set-up enables 233 a better understanding of individual key fluid mechanics phenomena adversely impacting 234 loads and energy efficiency of Darrieus rotors, and this information constitutes the first 235 knowledge level required to improve the design of these machines. Follow-on studies will 236 237 focus on additional 3D fluid mechanic aspects resulting from the multi-blade environment making use of computational resources larger than those used in the present study. 238

To maximize the analysis reliability, a time-dependent 3D simulation using very high levels of spatial and temporal refinement is carried out using a large 98,304-core IBM BG/Q cluster.

The presented test case is expected to be highly valuable to other research groups both to verify new CFD approaches and to calibrate lower-fidelity models (e.g. model based on lifting line theory and free vortex methods), which are key to industrial design due to their extremely low computational cost.

The paper is organized as follows. Section 2 presents the numerical methodology that 246 has been followed in the study: sub-section 2.1 reports the governing equations solved by the 247 248 COSA CFD code for the analysis of Darrieus rotor flows, sub-section 2.2 summarizes the main numerical features and previous work carried out with this code, and sub-section 2.3 249 provides the main features of the case study and describes the adopted numerical set-up. 250 Section 3 presents the main results of the 3D CFD analysis and compares them to those of the 251 2D analysis of the same case study, to highlight the impact of 3D effects. In Section 3 the 252 results of the RANS CFD analyses are also compared with those of the blade element 253 momentum theory to highlight strengths and weaknesses of this engineering approach. A 254 summary of the study and concluding remarks are finally provided in Section 4. 255 256

#### 257 **2. Numerical methodology**

#### 258 **2.1 Governing equations**

The compressible NS equations are a system of 5 nonlinear partial differential 259 equations (PDEs) expressing the conservation of mass, momentum and energy in a viscous 260 fluid flow. Averaging these equations on the longest time-scales of turbulence yields the so-261 called RANS equations, which feature additional terms depending on the Reynolds stress 262 tensor. Making use of Boussinesq approximation, this tensor has an expression similar to that 263 264 of the laminar or molecular stress tensor, with the molecular viscosity replaced by a turbulent or eddy viscosity [48-49]. In the COSA CFD code, the eddy viscosity is computed by means 265 of the two-equation  $k \cdot \omega$  SST turbulence model [36]. Thus, turbulent flows are determined by 266 267 solving a system of 7 PDEs.

Given a moving time-dependent control volume C(t) with time-dependent boundary S(t), the Arbitrary Lagrangian–Eulerian integral form of the system of the time-dependent RANS and SST equations in an absolute frame of reference is:

271 
$$\frac{\partial}{\partial t} \left( \int_{C(t)} \mathbf{U} dC \right) + \oint_{S(t)} \left( \underline{\Phi}_c - \underline{\Phi}_d \right) \cdot d\underline{S} - \int_{C(t)} \mathbf{S} dC = 0$$
(1)

272 where U is the array of conservative variables defined as:

273 
$$\mathbf{U} = \begin{bmatrix} \rho & \rho v' & \rho E & \rho k & \rho \omega \end{bmatrix}''_{-}$$

(2)

The symbols  $\rho$ ,  $\underline{v}$ , E, k and  $\omega$  denote respectively fluid density, flow velocity vector of Cartesian components (u,v,w), total energy per unit mass, turbulent kinetic energy per unit mass and specific dissipation rate of turbulent energy, and the superscript ' denotes the transpose operator. The total energy is defined as  $E=e+(\underline{v}\cdot\underline{v})/2+k$ , where *e* denotes the internal energy per unit mass; the perfect gas law is used to express the static pressure *p* as a function of  $\rho$ , *E*, *k* and the mean flow kinetic energy per unit mass ( $\underline{v}\cdot\underline{v}$ )/2. The generalized convective flux vector is defined as:

281 
$$\underline{\mathbf{\Phi}}_{c} = \underline{\mathbf{E}}_{c}\underline{i} + \underline{\mathbf{F}}_{c}\underline{j} + \underline{\mathbf{G}}_{c}\underline{k} - \underline{v}_{b}\mathbf{U}$$
(3)

where  $\mathbf{E}_c$ ,  $\mathbf{F}_c$  and  $\mathbf{G}_c$  are respectively the x-, y- and z-component of  $\underline{\mathbf{\Phi}}_c$  and are given by:

283  

$$\begin{bmatrix}
\mathbf{E}_{c} = \left[\rho u \ \rho u^{2} + p \ \rho uv \ \rho uw \ \rho uH \ \rho uk \ \rho u\omega\right]' \\
\mathbf{F}_{c} = \left[\rho v \ \rho uv \ \rho v^{2} + p \ \rho vw \ \rho vH \ \rho vk \ \rho v\omega\right]' \\
\mathbf{G}_{c} = \left[\rho w \ \rho uw \ \rho vw \ \rho w^{2} + p \ \rho wH \ \rho wk \ \rho w\omega\right]'$$
(4)

in which  $H=E+p/\rho$  is the total enthalpy per unit mass. The vector  $\underline{v}_{\underline{b}}$  is the velocity of the boundary S, and the flux term  $-\underline{v}_{\underline{b}}\mathbf{U}$  is its contribution of the boundary motion to the overall flux balance.

The expressions of the diffusive fluxes  $\underline{\Phi}_c$  and the turbulent source term *S* appearing in Eq. (1) can be found in [48] and [50].

290 **2.2 COSA CFD code** 

COSA is a compressible density-based finite volume code that solves the system of 291 PDEs corresponding to Eq. (1) using structured multi-block grids. The code features a steady 292 flow solver, a time-domain (TD) solver for the solution of general unsteady problems [48-293 49], and a harmonic balance solver for the rapid solution of periodic flows [50-52]. The 294 second-order space discretization of the convective fluxes of both the RANS and the SST 295 equations uses an upwind scheme based on Van Leer's MUSCL extrapolations and Roe's 296 flux difference splitting. The second order discretization of all diffusive fluxes is instead 297 based on central finite-differencing. The space-discretized RANS and SST equations are 298 299 integrated in a fully-coupled fashion with an explicit solution strategy based on full approximation scheme multigrid featuring a four-stage Runge-Kutta smoother. Convergence 300 acceleration is achieved by means of local time-stepping and implicit residual smoothing. For 301 general time-dependent problems, the TD equations are integrated using a second order 302 accurate dual time-stepping approach. 303

Comprehensive information on the numerical methods used by COSA and thorough 304 validation analyses are reported in [50,52] and other references cited therein. For unsteady 305 306 problems involving oscillating wings and cross-flow open rotors such as the Darrieus turbines, COSA solves the governing equations in the absolute frame of reference using 307 body-fitted grids. In the case of Darrieus rotors in open field operation this implies that the 308 entire computational grid rotates about the rotational axis of the turbine. The suitability of 309 COSA for the simulation of Darrieus wind turbines has been recently assessed through 310 comparative analyses with both commercial CFD codes and experimental data [53-54]. 311

312 313

289

#### 2.3 Case study and computational model

The selected case study is a one-blade H-Darrieus rotor using the NACA 0021 airfoil. 314 The blade chord (c=0.0858 m), the blade length (H=1.5 m) and the rotor radius (R=0.515 m) 315 were set equal to those used in the case-study of [24]; the blade was attached to the spoke at 316 midchord according to the original 3-blade model of [24]. The decision of simulating a single 317 blade was based both on physical considerations and on hardware limitations. First, a one-318 blade model is sufficient to investigate all the desired 3D flow structures that lead to an 319 efficiency reduction of a finite blade. At the same time, the use of a single blade allows one to 320 isolate and analyze fundamental aerodynamic phenomena of finite-length blade 321 aerodynamics, removing additional aerodynamic effects due to multiple blade/wake 322 interactions occurring in a multi-blade rotor. From a practical viewpoint, the need of ensuring 323 an adequate level of spatial refinement both in the grid planes normal to the rotor axis and in 324

the axial direction would have required a grid with more than 100 million elements for athree-blade rotor, which was beyond the resources available for this project.

To further reduce the computational cost of the 3D simulation, the central symmetry of 327 H-Darrieus rotors was exploited, enabling to simulate only one half of the rotor flow, thus 328 halving computational costs. Consequently, the aspect ratio (AR) of the simulated blade 329 portion is 8.74 which is half that of the actual blade. The modeled blade portion was 330 331 contained in a cylindrical domain (Fig. 1) of radius  $\Phi=240R$ , a value chosen to guarantee a full development of the wake, based on the sensitivity analyses reported in [53]. The domain 332 height was set to  $\Psi=2.53H$ , corresponding to half the height of the wind tunnel where the 333 334 original 3-blade model was tested [24,54]; measured data from these tests were previously used for validating the robustness of the RANS CFD methodology [26,53] also used in the 335 present study. 336

The 3D structured multi-block grid (2D and 3D views are reported in Fig. 2) was 337 obtained with the software ANSYS<sup>®</sup> ICEM<sup>®</sup> by first generating a 2D mesh past the airfoil 338 using the optimal mesh settings identified in [47,49], and then extruding this mesh in the 339 spanwise (z) direction and filling up with grid cells the volume between the blade tip and the 340 341 upper (circular) farfield boundary. The far-field boundary condition enforced on the lateral (cylindrical) boundary and the upper boundary of the domain is based on suitable 342 combinations of one-dimensional Riemann invariants and user-given freestream data, namely 343 344 pressure, density and velocity components. The sub-set of these far-field data combined with 345 suitable Riemann invariants depends on whether the fluid stream enters or leaves the computational domain at the considered boundary point (the code detects automatically 346 347 inflow and outflow points of the boundaries at each iteration). The complete definition of this far-field boundary condition is provided in [55]. On the blade surface, a no-slip condition is 348 enforced. Since the equations are solved in the absolute frame of reference, this requires 349 350 imposing that the fluid velocity at the blade surface equals the velocity of the blade surface itself at the considered wall point, where pressure and density are extrapolated from the 351 interior domain. The 2D grid section normal to the z-axis and containing the airfoil (Fig. 2(a)) 352 consisted of  $4.3 \times 10^5$  quadrilateral cells. The airfoil was discretized with 580 nodes and the 353 first element height was set to  $5.8 \times 10^{-5} c$  to guarantee a dimensionless wall distance y<sup>+</sup> lower 354 than 1 throughout the revolution. As recommended in [25], a fairly high mesh refinement of 355 both leading and trailing edge regions was adopted (Fig. 2(b)), and a high refinement in the 356 airfoil region within one chord from the airfoil surface was also used to resolve the separated 357 flow regions at high angle of attack (AoA) [27]. After extrusion in the z direction, 80 grid 358 layers in the half-blade span were formed (Fig. 2(c)), with progressive grid clustering from 359 360 midspan to tip to ensure an accurate description of tip flows. A fairly high grid refinement was also adopted in the whole tip region above the blade in order to capture the flow 361 separation and the tip vortices. The final mesh consisted of 64 million hexahedral cells. 362

The rotor flow field was computed by solving the system of governing equations corresponding to Eq. (1), that is by solving the RANS and SST equations in the absolute frame of reference. In such frame, the entire body-fitted grid rotates past the rotor axis, the additional flux components due to the grid motion is accounted for by the term  $-\underline{v}_b \mathbf{U}$ appearing in Eq. (3), and no sliding surface is required.

To keep computational costs within the limits of the available resources, only one operating condition was simulated, corresponding to a tip-speed ration (*TSR*) of 3.3. This condition corresponds to the same revolution speed already analyzed by some of the authors for the 3-blade turbine in [53]. For a 1-blade rotor, this TSR corresponds to a different point of the rotor power curve. The operating condition corresponding to this TSR, however, was considered of particular interest also for the 1-blade rotor because, also in this case, a) it corresponds to fairly high efficiency and thus a regime at which the rotor is expected to work more often than at other TSRs, and b) it features several complex aerodynamic phenomena (e.g. stall and strong tip vortices) posing a significant modelling challenge for the CFD analysis. Figure 3 displays the power coefficient at *TSR*=3.3 evaluated with the CFD analysis reported below on the expected power curve, which was calculated with a computationally more affordable code based on Lifting Line Theory coupled to a free vortex wake model. The model was successfully tuned on this case-study in [56] and thus it is expected to provide a power curve prediction fairly consistent with the CFD analysis reported below.

The free-stream wind speed was U=9.0 m/s. The turbulence farfield boundary conditions were a turbulent kinetic energy (*k*) based on 5% turbulence intensity and a characteristic length of 0.07 m.

The 3D and 2D simulations reported below were performed with the time-domain 385 solver of COSA. The 3D simulation was run on an IBM BG/Q cluster [57] featuring 8,144 386 16-core nodes for a total of 98,304 cores. Exploiting the outstanding parallel efficiency of 387 COSA, the simulation could be carried out using about 16,000 cores. This required 388 partitioning the grid into 16384 blocks using in-house utilities, and this operation was 389 performed starting from a grid with fewer blocks generated with the ANSYS<sup>®</sup> ICEM<sup>®</sup> grid 390 generator. All grid blocks had identical number of cells to optimize the load balance of the 391 392 parallel simulation. Using a time-discretization yielding 720 steps per revolution, the simulation needed 12 revolutions to achieve a fully periodic state. The flow field was 393 considered periodic once the difference between the mean torque values of the last two 394 revolutions was smaller than 0.1% of the mean torque in the revolution before the last. The 395 wall-clock time required for this 3D simulation was about 653 hours (27.2 days). 396

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#### 2.4 Grid and time-step sensitivity analyses

One of the key elements of this study is that the 3D calculation was carried out using a high level of spatial and temporal resolution. The 3D grid used to carry out the analyses reported in Section 3 was obtained by extruding in the third direction the  $4.3 \times 10^5$ -element 2D grid described above, and such grid was shown to provide accurate and grid-independent results in [53].

To assess the impact of using coarser spatial and temporal refinement on the computed solution, the considered flow regime was also simulated using only 360 steps per revolution and a coarser 3D grid with 8 million elements, obtained from the 64million element fine grid by removing every second line in all three directions.

The periodic profiles of the instantaneous torque coefficient  $C_t$  obtained with the coarse and fine grids are compared in Fig. 4, and the definition of  $C_t$  is provided by Eq. (5), in which *T* denotes the instantaneous torque on the entire blade,  $U_{\infty}$  and  $\rho_{\infty}$  denote respectively the farfield wind speed and the air density, *c* is the blade chord, and H is the overall blade length. The angular position  $\vartheta=0^\circ$  corresponds to the blade leading edge facing the oncoming wind and entering the upwind half of its revolution.

414  $C_{t} = \frac{T}{\frac{1}{2}\rho_{\infty}U_{\infty}^{2}c^{2}H}$  (5)

The comparison shows that differences between the two predictions occur over most parts of the period, particularly around the maximum values of  $C_t$ . These discrepancies are caused by differences in the prediction of strength and timing of stall on the airfoils and under-resolved wakes and wake/blade interactions when using the coarse grid. The position of the curve peak (maximum  $C_t$  in the upwind region of rotor trajectory) predicted by the coarse grid has an error of about 3 degrees in azimuthal coordinates, leading to a shift of the 421 curve in the range between  $\vartheta = 90^{\circ}$  and  $\vartheta = 300^{\circ}$ . Such discrepancies, reported in Fig. 4 also as 422 the difference between the coarse and fine grid profiles normalized by the revolution-423 averaged mean torque of the fine grid (curve labeled "% variation") result in the mean torque 424 coefficient obtained with the coarse grid being 3.2 percent higher than that obtained with the 425 fine grid. As discussed in the following, this difference corresponds to nearly 40 percent of 426 the energy efficiency loss due to finite blade length effects. This highlights the importance of 427 using a fine grid for this type of analyses.

The impact of the mesh refinement on the resolution of some of the 3D flow 428 phenomena occurring during the revolution are examined in Fig. 5. This figure shows the 429 extent of the vortices generated at the blade tip at  $\vartheta = 80^{\circ}$  predicted with the two meshes. The 430 red and blue vortices represent the regions of ascending and descending flow, respectively. 431 The higher dissipation of the coarse mesh leads to an under-prediction of the downstream 432 propagation of the vortex, which is reduced from about three chords (Fig 5(b)) to less than 433 two chords (Fig 5(a)). The coarse grid under-estimation of the tip effects contributes to the 434 overestimation of the torque highlighted in Fig. 4. The vorticity contours at midspan when 435 the blade is at  $9=315^{\circ}$  are compared in Fig. 6 to assess the resolution of the free convection of 436 vorticity in the downstream region. With the finer mesh the wake is resolved more sharply, 437 thus fulfilling essential prerequisites for adequately resolving blade-wake interactions in the 438 downwind part of the revolution. The under-resolution of the wake in the downwind rotor 439 region contributes to the higher torque produced by the blade when interacting with the wake 440 shed in the upstream trajectory. The impact of all these vortical phenomena on the rotor 441 performance is even higher in multi-blade rotors, due to higher number of interactions (and 442 thus energy loss events) per revolution. 443

#### 444

#### 445 **3. Results and discussion**

Figure 7(a) reports the instantaneous torque coefficient per unit length ( $C_{tz}$ ) at different span lengths along the blade (0 percent and 100 percent correspond to midspan and tip, respectively). The instantaneous torque coefficient per unit length  $C_{tz}$  is defined by Eq. (6). Here  $T_z$  denotes the instantaneous torque per unit blade length at the considered spanwise position.

$$C_{tz} = \frac{T_{z}}{\frac{1}{2}\rho_{\infty}U_{\infty}^{2}c^{2}}$$
(6)

Figure 7(b) reports three torque profiles. The profile labelled 2D refers to the results of 452 a 2D simulation of the same rotor, and corresponds to the "ideal" torque of a blade with 453 infinite span, i.e. without any secondary effects at the blade tip. This 2D simulation was 454 carried out using a mesh equal to the midspan section of the 3D fine mesh and the same 455 numerical parameters of the 3D simulations. The torque profile labelled "0%" is the torque 456 per unit blade length at midspan of the finite-length rotor, whereas the torque profile labelled 457 3D is the overall torque coefficient  $C_t$  of the 3D rotor defined in Eq. (7). The result obtained 458 by using this definition is identical to that obtained by using Eq. (5). 459

460 
$$C_t = \frac{2}{H} \int_{0}^{\frac{H}{2}} C_{tz} dz$$
 (7)

Examination of these profiles reveals several important facts. Firstly, the ideal 2D torque and the 3D torque profiles are characterized by similar patterns, including the

occurrence of two relative maxima, one in the upwind the other in the downwind regions, and 463 also similar azimuthal positions of both maxima: the maximum torque in the upwind portion 464 of the revolution is located at  $9 \approx 88.5^{\circ}$  and the maximum torque in the downwind portion of 465 the revolution is located at  $\vartheta \approx 257^{\circ}$  in both cases. This behaviour is in line with the analyses 466 of both Lam [33] and Alaimo [40], which showed that the periodic torque profiles obtained 467 with 2D and 3D simulations differ significantly for their amplitudes but have comparable 468 shapes. Figure 7(b) also highlights that the differences between the 2D torque profile and that 469 at midspan of the 3D rotor are negligible, highlighting that 3D flow effects due to tip flows 470 do not reach this position. 471

472 Examination of all profiles of Fig. 7(b) shows that the effects of blade finite-length effects are very small when the blade loading is low, i.e. when the angle of attack is low 473  $(0^{\circ} < 9 < 40^{\circ} and 130^{\circ} < 9 < 210^{\circ})$ : in these portions of the revolution, the 2D and both 3D curves 474 are almost superimposed. When the incidence increases, the blade load also increases and the 475 blade starts experiencing stall. Figure 8 reports the top view of the vorticity contours at 476 midspan at three azimuthal positions to examine the onset of stall in the upwind zone. At 477  $\vartheta$ =70° a small separation region forms on the suction side of the blade. At  $\vartheta$ =80° the blade 478 stall has become significant, since the flow is detached from the blade. At the position of 479 torque peak a large region of the suction surface is affected by stall. Consequently, the torque 480 loss due to tip effects also increases because the strength of tip vortex flow increases with the 481 flow incidence. The same behaviour can be seen also in the downwind zones. Closer 482 inspection of the 2D and mean 3D CP curves shows that these effects are strongest in the 483 upwind region of the period, where a maximum difference of 9.7 percent between the torque 484 485 peaks occurs.

- Examining the torque profiles at the spanwise positions considered in Fig. 4(a), some additional observations can be made:
- The torque profiles of the blade sections at 20%, 40% and 50% semispan are almost identical, indicating that at least half of the blade is characterized by a predominantly 2D flow with negligible impact of tip flow effects;
- The torque profiles of the blade sections at 60%, 70% and 80% show a progressive reduction of the torque peak, down to -14 percent with respect to the midspan section.
   The remainder of the torque curve is less affected, especially in the downwind zone;
- The torque profiles of the blade sections at 90%, 95% and 97.5% show that at these
   positions, 3D effects are strong throughout the whole revolution. Notably, in the
   regions of positive torque production, the efficiency is remarkably reduced;
- In proximity of the blade tip (99%), almost no positive contribution to the torque output is given, due to the large load reduction;
- The azimuthal position of the torque peak occurs later in the cycle as one moves towards the tip, with a 5° shift between the 0% and 97.5% sections. This can be explained with a reduction of the incidence angle (downwash), as shown below. The experiments of Li et al. [35] highlight the same trend and show that the aforementioned shift is even more pronounced for a turbine with a very low aspect ratio (AR=4.5).

To compare the CFD prediction of the impact of finite blade effects on turbine 504 performance to that of the widespread low-fidelity BEM theory, Fig. 9 compares the 2D and 505 mean 3D torque profiles obtained with NS CFD and the corresponding estimates obtained 506 with the VARDAR research code, a state-of-the-art BEM code developed at the University of 507 Florence [6,17-18] using the ubiquitous Leicester-Prandtl model for the finite-wing 508 correction [58]. The two BEM profiles of Fig. 9 differ in that one includes tip flow corrections 509 and the other does not. Examination of these profiles shows that the reduction of the torque 510 peak in the upwind portion of the revolution predicted by the CFD analyses is in good 511 agreement with that estimated with the simplified tip flow model included in the BEM 512

theory, and the shapes of the CFD and BEM torque profiles are in a qualitatively good agreement. Conversely, the patterns of the torque curves in the downwind portion of the revolution predicted by the BEM and CFD analyses are significantly different, and the torque reduction due to blade finite length predicted by the BEM analysis is higher than predicted by CFD. This comparative analysis highlights the potential of using CFD also for further improving the predictions of low-fidelity engineering tools, which are key to Darrieus rotor industrial design due to their extremely small computational requirements.

To provide a different quantitative perspective of the impact of tip losses, Fig. 10 520 compares the CFD and BEM profiles of mean torque coefficient per unit length. For each 521 522 blade height the mean value is obtained by averaging the profiles of Fig. 4(a) over one revolution. The figure also reports the constant mean torque values of the 2D and 3D 523 simulations for both the CFD and BEM models. All curves are normalized with respect to the 524 mean 2D torque coefficient.One sees that the mean blade performance is almost unaffected 525 by tip-effects up to approximately 70% semispan. More specifically, it is found that tip flow 526 effects adversely affect the performance of the blade for a span length of approximately 2.6c 527 (yellow zone in Fig. 10). In terms of aggregate data, the tip effects yield a reduction of the 528 rotor torque of 8.6% with respect to the 2D calculation with virtually infinite span. This can 529 be seen as an equivalent reduction of the actual blade's height of 0.75c for each half blade 530 (red colored zone in Fig. 10). Such a correction factor needs to be accounted for when 531 estimating the turbine performance by means of 2D simulations. 532

The observations above are in accordance with the findings of Li e al. [35] in terms of 533 performance drop as a function of the distance from the tip. Their experiments showed that at 534 535 55% semispan, corresponding to a distance of 1.0c from the tip, the torque peak is greatly reduced. At this blade height, they found a CP reduction of 40% over the midspan value at 536 TSR=2.2 and 60% at TSR=2.5, corresponding to an equivalent reduction of the actual blade's 537 538 height by 1.8c and 2.7c, respectively. Other analyses focused on estimating the mean power reduction due to finite blade length effects through comparisons of 2D and 3D CFD analyses 539 [32,33,37,40], but their results are not directly comparable with the present study due to the 540 use of different aspect ratio, rotor solidity, TSR, airfoil geometry and number blades.. 541 Overall, the equivalent height reduction can vary from 0.8c for a NACA 0022 three-blade 542 rotor at TSR=1.3 [32] up to 5c for a NACA 0018 two-blade rotor at TSR=4.5 [33]. 543

To investigate in greater detail the 3D phenomena accounting for energy efficiency reduction, the Mach contours and streamlines at the angular position of maximum separation  $(\vartheta=120^\circ)$  are examined in Fig. 11(a). Different spanwise sections are considered to analyse the flow pattern alterations from midspan to the blade tip.

548 In the central portion of the blade (from midspan to about 70% semispan) the streamlines are contained in planes orthogonal to the blade axis, indicating a predominantly 549 2D flow character, and a fairly large region of separated flow in the rear of the suction side. 550 Closer to the tip (90% semispan) the downwash due to the tip flow reduces the effective AoA 551 with respect to that at midspan, and the extension of the stall region is thus reduced. The skin 552 friction lines and contours of the z velocity component (w) on the blade suction surface 553 reported in Fig. 11(b) show the extension of the region affected by downwash. Near the tip, 554 the flow on the pressure side is no longer able to follow the blade profile, and travels over the 555 tip due to the pressure difference between the pressure side and the suction side. The tip 556 vortex flow is responsible for the downwash velocity component and therefore for the 557 incidence variation along the span, in accordance with the theory of finite wings [58]. It is 558 noted that the finite wing effects occurring in Darrieus rotors are more complex than those 559 560 encountered in fixed finite wings. This is primarily because of the flow curvature associated with the circular trajectory of the blade, and also the flow nonlinearities due to dynamic stall. 561

To quantify the impact of these effects, it is convenient to examine the curves of the 562 torque coefficient per unit length at midspan and 90% semispan (Fig. 12). The percentage 563 difference between the two curves (i.e. the torque coefficient difference between the curves at 564 each azimuthal angle divided by the revolution-averaged torque coefficient at midspan) is 565 also reported to quantify the dependence of the torque variation on the azimuthal position. A 566 notable torque reduction occurs in the interval  $40^{\circ} < 9 < 130^{\circ}$ . In addition, a large and sudden 567 torque reduction occurs towards the end of the revolution, in the interval  $315^{\circ} < 9 < 340^{\circ}$ , a 568 range in which the AoA is decreasing and goes below the value yielding stall. Also, an 569 inversion in the expected trend is noticed close to  $\vartheta$ =150°, where the tip section performs 570 571 better than the midspan section: the torque of the section at 90% semispan is about 10 percent higher than that at midspan. According to the finite wing theory, the lift should be in fact 572 always reduced in proximity of the tip. Therefore, the inversion at  $\vartheta$ =150° cannot be 573 explained with this theory alone. This occurrence and the sudden torque loss of the tip section 574 towards the end of the revolution are analysed in further detail below. 575

To investigate the origin of the sudden torque reduction at the blade tip in the interval 576 315°<9<340°, isosurfaces of the turbulent kinetic energy field at selected azimuthal positions 577 are examined in Fig. 13. The color scale is based on the intensity of the velocity component 578 along the z-axis (w). Three azimuthal positions of the blade are considered:  $\vartheta = 60^{\circ}$ ,  $\vartheta = 180^{\circ}$ 579 and  $\vartheta$ =315°. During the upwind half of the revolution ( $\vartheta$ =60°) the tip vortex is strong, since 580 the vertical component of velocity is fairly high. A high turbulence region is then generated 581 from the blade tip. At  $\vartheta$ =180°, the region of high turbulent kinetic energy corresponding to 582 the tip vortex is increased in size and length, and is still associated with large values of w. 583 584 This strong vortex detaches from the blade, is convected by the wind, and is re-encountered by the blade at  $9=315^{\circ}$ . The blade interaction with this vortex induces a more pronounced 585 reduction of the torque with respect to the 2D case, where this effect is absent. 586

587 To investigate the reasons for the higher torque of the 90% section over the midspan section at  $\vartheta$ =150°, top views of the streamlines at  $\vartheta$ =150° and  $\vartheta$ =48° are examined in Fig. 14. 588 The position  $9=48^{\circ}$  is selected because this is the other angular position of the upwind half of 589 the revolution experiencing the same AoA of  $\vartheta$ =150°. Streamlines on both the pressure and 590 suction sides of the blade are visualized at four different span locations. At  $9=48^{\circ}$  the 591 downwash effect is visible: moving from midspan to the tip, the incidence of the oncoming 592 flow decreases and the air stream after the trailing edge is more aligned to the airfoil chord. 593 This phenomenon is not very pronounced due to the low loading on the blade at this angular 594 position. At  $9=150^{\circ}$ , moving from midspan to the tip, the incidence of the oncoming flow is 595 progressively reduced similarly to what seen at  $9=48^{\circ}$ . However, the flow pattern on the 596 suction side of the central portion of the blade is significantly different from that at  $9=48^{\circ}$ , 597 despite the fact that the AoA is similar in the two cases. A large separation region exists at 598  $\vartheta$ =150° due to stall. Due to the finite wing length, a strong modification of this flow pattern is 599 observed moving towards the tip: from 70% semispan, the flow is attached due to lower 600 downwash-induced loading and is more aligned to the airfoil chord after the trailing edge. 601

The observations above can be explained by a combined effect of downwash and 602 dynamic stall. From  $\vartheta = 0^{\circ}$  to  $\vartheta = 90^{\circ}$  the AoA increases and stall in the central blade portion 603 occurs between  $9=70^{\circ}$  and  $9=80^{\circ}$ . The dominant effect is that of the downwash which 604 reduces the AoA to the outer portion of the blade. When the AoA reaches its maximum 605 towards  $\vartheta = 90^\circ$ , the central portion of the blade experiences high level of stall. From  $\vartheta = 90^\circ$  to 606  $\vartheta$ =180° the AoA decreases but the central portion of the blade remains stalled due to delay of 607 the flow in readjusting to the decreasing incidence (a distinctive feature of dynamic stall). 608 However, the outer sections of the blade remain stall-free, and this is the reason why at 609  $\vartheta$ =150° the torque of the tip sections is higher than that of the midspan section, whereas the 610 opposite is observed at  $9=48^{\circ}$ . 611

Fig. 15 presents an analysis of the same type of that of Fig. 14 for the angular positions  $\vartheta = 210^{\circ}$  and  $\vartheta = 300^{\circ}$ . Both positions belong to the downwind portion of the rotor trajectory and are characterized by a comparable AoA. However at  $\vartheta = 210^{\circ}$  the AoA is increasing whereas at  $\vartheta = 300^{\circ}$  the AoA is decreasing. One notices that the streamline pattern at  $\vartheta = 210^{\circ}$  is similar to that at  $\vartheta = 48^{\circ}$ . At  $\vartheta = 300^{\circ}$  the streamline patterns from midspan to tip are the same as those at  $\vartheta = 210^{\circ}$ . The similarity of the flow patterns at these two positions is due to the fact that no stall occurs in the downwind portion of the rotor trajectory.

Fig. 16 depicts the blade streamlines at  $\vartheta$ =315°, the position at which the tip vortex interacts with the outboard portion of the blade in its downwind trajectory, as highlighted in Fig. 13. One observes a sudden deviation of the oncoming flow in the tip region with respect to the flow direction at midspan. Such deviation is due to the blade-vortex interaction, which prevails over the effects due to downwash.

All aforementioned results can be more quantitatively described by evaluating the pressure coefficient  $(C_p)$  distributions and the vorticity contours along the blade. The pressure coefficient used in this study is defined by Eq. (7), where *p* denotes the static pressure at the airfoil surface. Due to the difficulty of properly defining the actual relative wind speed at each blade height, the relative flow velocity  $w_{th}$  used to calculate  $C_p$  neglects the induced velocity and is computed using the vectorial sum of the absolute free-stream velocity and entrainment velocity  $\Omega R$ .

Fig. 17 reports the  $C_p$  profiles at different blade heights for three key angular positions: maximum loading ( $\theta$ =80°), inversion of torque of midspan and tip sections ( $\theta$ =150°) and maximum loading in the downwind half of the revolution ( $\theta$ =240°). The objective of this analysis is to highlight the impact of downwash and stall at different angular positions.

$$C_{p} = \frac{p - p_{\infty}}{\frac{1}{2}\rho_{\infty}w_{th}^{2}}$$
(7)

636 At  $9=80^{\circ}$  the blade is subject to high loading (high AoA and high relative speed). The top subplot of Fig. 17 confirms that, in these conditions, 3D flow effects affect almost 40 637 percent of the blade (from the tip to 60% semispan), since moving from midspan to the tip, 638 the  $C_p$  profile at 60% already shows a slight loading reduction with respect to midspan. 639 Closer to the tip, the suction side of the blade is characterized by an almost constant pressure, 640 indicating that this blade portion generates a small lift. As a result, the torque of the tip 641 sections is substantially lower than that of the midspan section, and the torque becomes 642 negative at 97.5% midspan, as shown in Fig. 7. At 9=240° (middle subplot of Fig. 16) the 643 AoA is high but the relative speed magnitude is lower than at  $9=80^{\circ}$ . In these conditions 3D 644 flow effects affect only the last 20 percent of the semispan (i.e. from 80% semispan to tip): 645 646 significant differences in the  $C_p$  profiles with respect to the midspan values are observed only on the last 10 percent of the blade, where the loading becomes significantly smaller than at 647 midspan. Unlike at the two angular positions just discussed, a strong flow separation due to 648 stall occurs at  $\vartheta$ =150° (bottom subplot of Fig. 17). This is highlighted by the pressure profiles 649 at 0% and 60% semispan, which feature a fairly shallow slope on the suction side. In this 650 651 circumstance, the lower AoA at the tip sections induced by the tip vortex-related downwash 652 results in the flow past such tip sections remaining attached and these sections outperforming the midspan region of the blade. 653

The evolution of the vorticity contours at different blade span heights is presented in Fig. 18. In the upwind half of the revolution, the two positions  $\vartheta=40^{\circ}$  and  $\vartheta=140^{\circ}$  are of particular interest. Although at these two positions the torque profiles along the blade are comparable (see Fig. 7(a) and Fig. 7(b)), the vorticity patterns and thus the flow field are remarkably different. On the other hand, moving to the downwind half of the revolution, one sees that the vorticity patterns around the blade are quite similar at all azimuthal positions.
These patterns are in line with the previous analyses of streamlines and pressure coefficient
profiles.

Figure 19 reports the top view of the vorticity contours at four different span locations at the two aforementioned azimuthal positions and highlights the vorticity differences in greater detail. At  $\vartheta$ =40° the vorticity contours are very similar, moving from midspan to tip, whereas at  $\vartheta$ =140° the large separation region due to stall is clearly visible along a large central portion of the blade.

# 668 **4. Conclusions**

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A 3D time-accurate Reynolds-averaged Navier-Stokes CFD analysis of an aspect ratio 669 17.5 blade rotating in Darrieus-like motion has been presented. Special attention was paid to 670 the description of 3D flow effects and their impact on the energy efficiency of Darrieus rotor 671 672 blades. This was accomplished also by comparative analyses of 3D and 2D CFD analyses. The presented 3D CFD results were obtained with a highly refined analysis using a grid with 673 64 million elements and time-marching the flow field to a periodic state using 720 time-steps 674 per revolution. A 3D mesh sensitivity analysis was also presented. The main outcomes of the 675 analysis can be summarized as follows: 676

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- a) 3D flow effects due to finite blade length reduce the mean power of the considered 17.5 aspect ratio blade by 8.6 percent with respect to the torque of the corresponding infinite blade. Such mean torque reduction corresponds to a reduction of the effective blade length of 1.5c (0.75c for each half blade).
- b) A strong interaction between the tip-vortex released in the upwind portion of the blade revolution and the blade traveling in the downwind region occurs at  $\vartheta$ =315°, and this yields an additional reduction of the outboard blade sections in this region of the revolution.
- c) Finite blade length effects do not modify significantly the overall shape of the blade
  torque profile over the revolution with respect to the torque profile of the
  c) corresponding infinite blade;
- d) For given azimuthal position, the torque profile along the blade height varies substantially from midspan to tip, and the pattern of these variations strongly depends on the azimuthal position; i.e. on the magnitude of the relative velocity of the oncoming flow and its local angle of attack;
- e) The mean torque reduction predicted by the 3D CFD analysis and that of a state-of-the-art BEM analysis using tip loss corrections is comparable, but the profiles of the blade torque in the downwind portion of the revolution differ significantly. The reliability of BEM analyses may be improved by using 3D CFD results to develop azimuthal position-dependent tip loss corrections;
- f) The 3D grid sensitivity analysis highlighted that the use of a coarser grid, with size 697 comparable to those used in most 3D Darrieus studies to date, may yield uncertainty 698 levels in the prediction of tip vortex flows, blade/wake/tip vortex interactions, and 699 dynamic stall timings and strength. All these phenomena affect torque and power 700 generation. The mean power predicted by a typical coarse grid and the fine grid of 701 this study differed by more than 3 percent. and significantly larger differences are 702 expected for multi-blade rotors due to higher number of blade/wake/tip vortex 703 704 encounters per revolution.

Future work will include investigating 3D flow effects at different tip-speed ratios, particularly the lower ones, at which the impact of dynamic stall is expected to be more pronounced than at the considered regime, and extending this analysis to multi-blade turbines, to assess in detail all aspects of wake/blade interactions. This type of high-fidelity analyses provides valuable data for validating and further improving the reliability of lowfidelity tools such as BEM codes and codes based on lifting line theory and free vortex transport methods. Due to their extremely high execution speeds, these engineering tools are of crucial importance to improving the design of future small and large Darrieus turbines.

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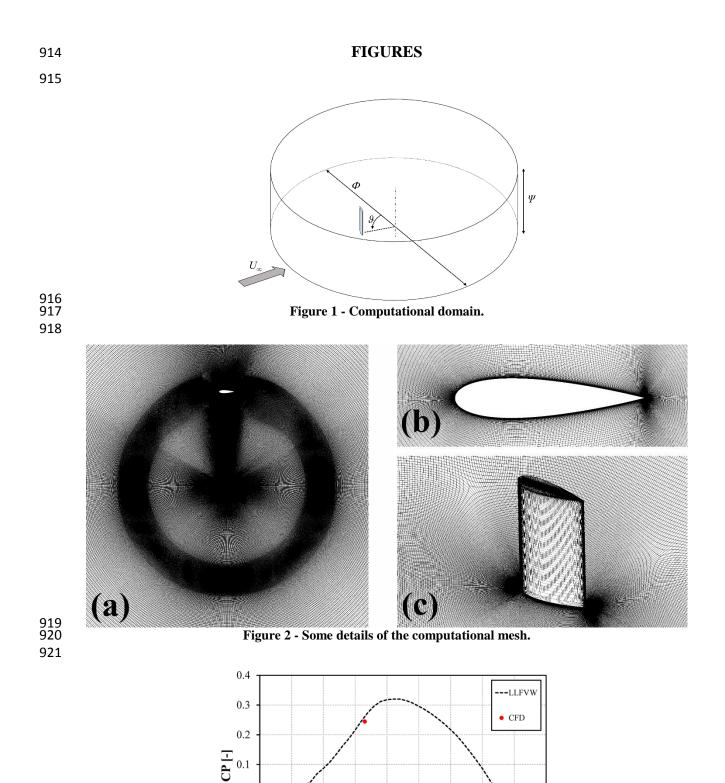


Figure 3 - Attended power curve of the 1-blade model.

4.0

4.0 5.0 TSR [-]

7.0

6.0

9.0

8.0

0.0

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-0.2

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1.0

2.0

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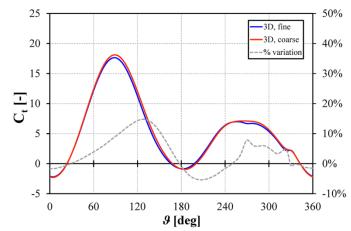


Figure 4 - Differences in the torque profile between the selected mesh and a coarser one.

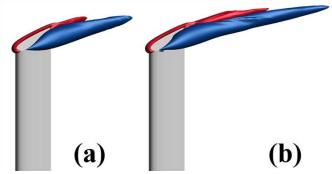


Figure 5 – Tip vortices generated at  $\vartheta$ =80°: (a) coarse mesh; (b) selected mesh.

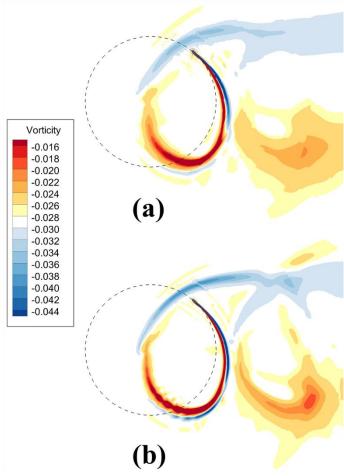
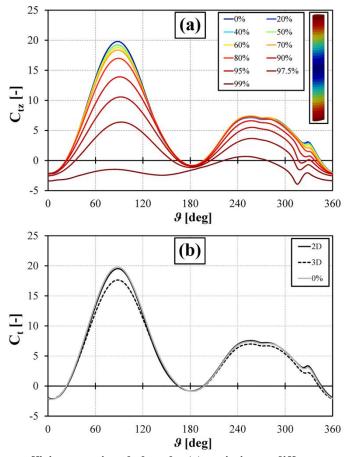
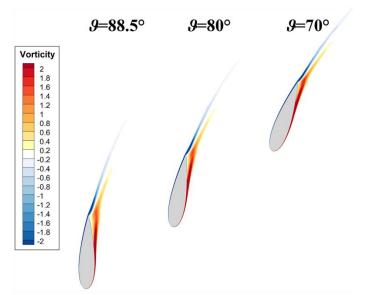


Figure 6 - Vorticity contours at midspan at  $9=315^{\circ}$ : (a) coarse mesh; (b) selected mesh.

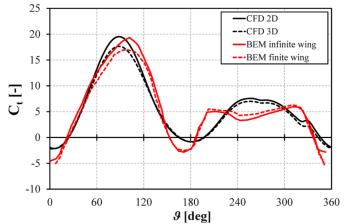


935 Figure 7 - Torque coefficient vs azimuthal angle: (a) variation at different span lengths; (b) 2D simulations compared to the 3D profile at midspan and average 3D profile. 



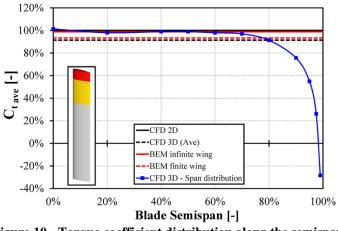
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Figure 8 - Vorticity contours at midspan: 9=70°, 9=80° and 9=88.5°.



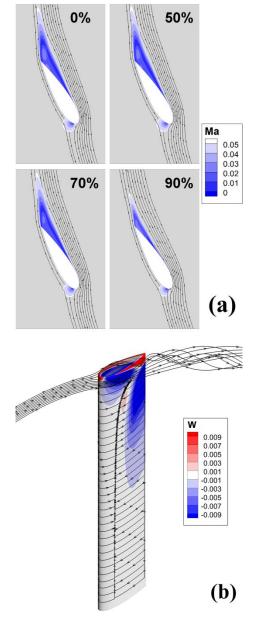
941 942 Figure 9 - Torque coefficient profiles: 2D and 3D CFD data vs. BEM simulations either including or 943 neglecting the finite-wind effects.





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Figure 10 - Torque coefficient distribution along the semispan.



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 949
 949 Figure 11 – Downwash effect at *9*=120°: (a) Mach contours and streamlines at different semispan
 950 locations; (b) flow streamlines in the tip region, skin friction lines and z velocity component on the blade
 951 suction surface.
 952

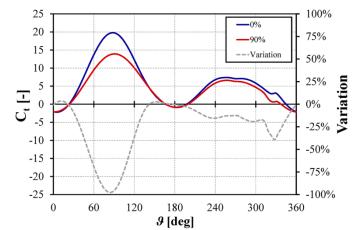


Figure 12 - Comparison of torque coefficient curves at 0 and 90 percent semispan.



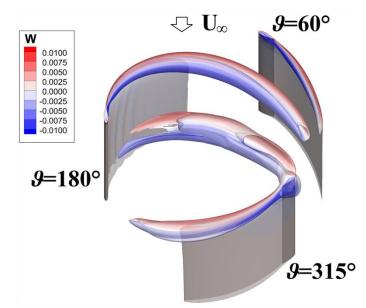


Figure 13 - Isosurfaces of turbulent kinetic energy *k* colored with the contour of *w*.

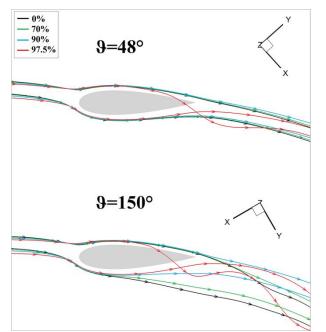


Figure 14- Streamlines at different span lengths: 9=48° and 9=150°.



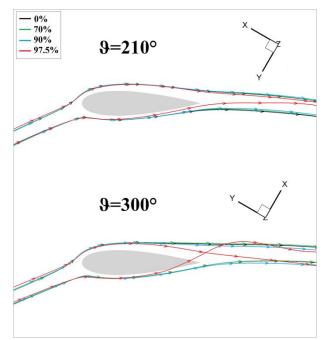


Figure 15 - Streamlines at different span lengths:  $\vartheta$ =210° and  $\vartheta$ =300°.

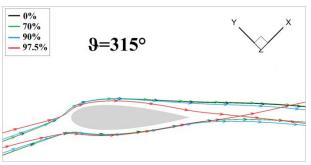


Figure 16 - Streamlines at different span lengths: 9=315°.

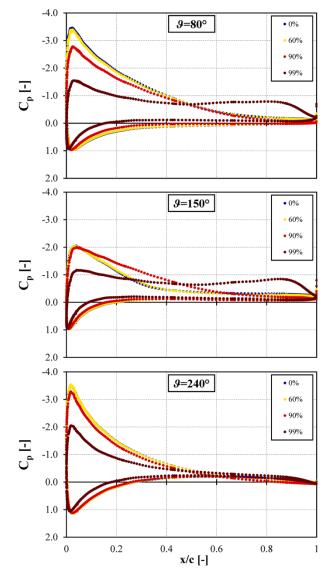


Figure 17 - Pressure coefficient profiles at different span lengths:  $9=80^{\circ}$ ,  $9=150^{\circ}$  and  $9=240^{\circ}$ .

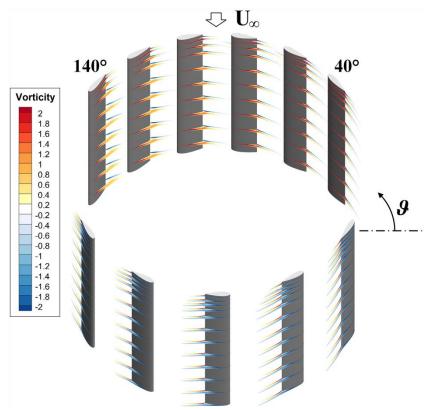


Figure 18 - Vorticity contours at different span lengths during the revolution.

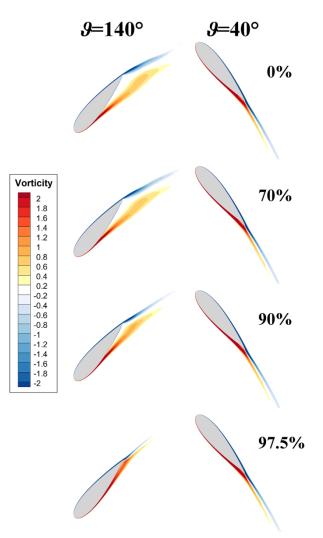


Figure 19 - Vorticity contours at different semispan locations:  $9=40^{\circ}$  and  $9=140^{\circ}$ .