

Existence and non-uniqueness of global weak solutions to inviscid primitive and Boussinesq equations

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Abstract

We consider the initial value problem for the inviscid Primitive and Boussinesq equations in three spatial dimensions. We recast both systems as an abstract Euler-type system and apply the methods of convex integration of De Lellis and Székelyhidi to show the existence of infinitely many global weak solutions of the studied equations for general initial data. We also introduce an appropriate notion of dissipative solutions and show the existence of suitable initial data which generate infinitely many dissipative solutions.

1 Introduction

The Boussinesq equations are used to model the behaviour of oceans. Recall that the Boussinesq approximation consists in neglecting changes of density except in the buoyancy terms and results in a system coupling the incompressible Navier-Stokes equations (for an unknown velocity field $\mathbf{u} = \mathbf{u}(t, \mathbf{x}) = (u, v, w)$ and pressure $p = p(t, \mathbf{x})$) with the convection-diffusion equation (for an unknown temperature $\theta = \theta(t, \mathbf{x})$). Physically relevant references can be found in [20]. We will also consider the effect of the Coriolis force in the form $\Omega \times \mathbf{u}$ for a vector function $\Omega = (\Omega_x, \Omega_y, \Omega_z)$ and neglect the effect of viscosity. The inviscid Boussinesq equations then read as

$$\partial_t u + \mathbf{u} \cdot \nabla_{\mathbf{x}} u + \Omega_y w - \Omega_z v + \partial_x p = 0, \quad (1a)$$

$$\partial_t v + \mathbf{u} \cdot \nabla_{\mathbf{x}} v - \Omega_x w + \Omega_z u + \partial_y p = 0, \quad (1b)$$

$$\partial_t w + \mathbf{u} \cdot \nabla_{\mathbf{x}} w + \Omega_x v - \Omega_y u + \partial_z p = -\theta, \quad (1c)$$

$$\operatorname{div}_{\mathbf{x}} \mathbf{u} = 0, \quad (1d)$$

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$$\partial_t \theta + \mathbf{u} \cdot \nabla_{\mathbf{x}} \theta - \lambda_1 (\partial_{xx}^2 + \partial_{yy}^2) \theta - \lambda_2 \partial_{zz}^2 \theta = 0 \quad (1e)$$

for unknown functions u, v, w, p and $\theta: [0, T) \times U \rightarrow \mathbb{R}$. We consider $U \subseteq \mathbb{R}^3$ an open bounded set. The parameters $T, \lambda_1,$ and λ_2 are given positive real constants without additional restrictions. We will also denote $Q = (0, T) \times U$.

When modeling the large scale behaviour of oceans or the atmosphere, one spatial scale (vertical) is essentially smaller than the other (horizontal) ones. The primitive equations, which are also considered, can be obtained as a formal singular limit of the Boussinesq equations in the way that the convective derivative of the vertical velocity coordinate is neglected. The momentum equation for the vertical velocity component is then replaced by the hydrostatic approximation. Under the already given notation, the inviscid primitive equations consist of the following system of partial differential equations:

$$\partial_t u + \mathbf{u} \cdot \nabla_{\mathbf{x}} u - \Omega_z v + \Omega_y w + \partial_x p = 0, \quad (2a)$$

$$\partial_t v + \mathbf{u} \cdot \nabla_{\mathbf{x}} v + \Omega_z u - \Omega_x w + \partial_y p = 0, \quad (2b)$$

$$\partial_z p = -\theta, \quad (2c)$$

$$\operatorname{div} \mathbf{u} = 0, \quad (2d)$$

$$\partial_t \theta + \mathbf{u} \cdot \nabla_{\mathbf{x}} \theta - \lambda_1 (\partial_{xx}^2 + \partial_{yy}^2) \theta - \lambda_2 \partial_{zz}^2 \theta = 0. \quad (2e)$$

To complete both systems, we assume the “no-flow” boundary condition for (u, v, w) and homogeneous Dirichlet condition for θ :

$$\mathbf{u}(t, \mathbf{x}) \cdot \eta(t, \mathbf{x}) = 0 \quad \text{on } (0, T) \times \partial U, \quad (3a)$$

$$\theta(t, \mathbf{x}) = 0 \quad \text{on } (0, T) \times \partial U, \quad (3b)$$

where η denotes the exterior normal to the boundary ∂U . Both systems describe the time evolution of u, v and θ and therefore it makes sense to prescribe initial conditions for these quantities. We assume that

$$u(0, \cdot) = u_0, v(0, \cdot) = v_0 \text{ and } \theta(0, \cdot) = \theta_0 \quad \text{in } U. \quad (4)$$

For the Boussinesq equations, we also prescribe the initial vertical velocity

$$w(0, \cdot) = w_0 \quad \text{in } U. \quad (5)$$

Remark. The main results of the article hold also for other boundary conditions for θ for which solutions of (1e) or (2e) with $\mathbf{u} \in L^\infty(Q; \mathbb{R}^3)$ belong to $\mathcal{C}(\overline{Q})$.

Let us recall known results about the mentioned systems. The system (1) shares many similarities with the Euler system (i.e. when $\theta = 0$). In two dimensions, the global well-posedness for regular initial data was established in [6] (see also [9] for the recent development).

To the best of our knowledge, the question of the existence of global solutions of (1) in 3D remains open. We give a positive answer to this question in the case of weak solutions. A similar system, namely (1) in dimension 2 with $\lambda_1 = \lambda_2 = 0$ and without the temperature in (1c), was treated in [3] using a slightly different approach.

Considering three spatial dimensions, there are a few mathematical results connected to the *viscid* (Navier-Stokes-like) analogue of system (2). The local in time existence of regular solutions was presented in [20], where a proof of the global in time existence of weak solutions can also be found. The existence of global regular solutions under the assumption that initial data are slowly varying in the z -variable was proved in [18]. Cao and Titi demonstrated in [5] that the solutions emanating from regular initial data stay regular for all times $t > 0$. The regularity was also shown in the case of homogeneous Dirichlet boundary conditions in [19]. Very recently, global strong well-posedness in L^p was given in [17]. These results should be put into comparison with the similar Navier-Stokes system for which the question on the global regularity is still open. Very recently, it was shown in [4] that if one drops the viscous term and considers the system (2) with suitable boundary conditions then a finite time blow-up occurs for some specific regular initial data. Local existence of regular solutions for inviscid primitive equations in 2D was given in [2].

A question remaining open is whether there exist global weak solutions for any (suitably regular) initial data for (2) with (3). At first glance, there is almost no hope in any kind of positive answer. The inviscid primitive equations differ notably from the incompressible Euler system. In comparison to the Euler system, primitive equations are degenerate with respect to w . It is known that the system is not hyperbolic and that the boundary value problem is ill-posed for pointwise boundary conditions, see [21] and also [22]. On the other hand, we recall that De Lellis and Székelyhidi (see e. g. [10], [11]) extended the possibility to use techniques of convex integration on the Euler system. They constructed infinitely many "oscillatory" weak solutions satisfying even different admissibility criteria, yet exceptionally non-unique. The aim of this paper is to demonstrate that the inviscid primitive equations also admit such oscillatory solutions. We will employ the recent refinements of the De Lellis and Székelyhidi approach, carried out in [13] and in [8] for the Euler-Fourier system or in [14] for Savage-Hutter model.

We give the reader the outline of the rest of the article: in Section 2 we define the notion of weak solution and formulate the main results. In Section 3 we give a reformulation of the given systems into an abstract Euler-type problem. In Sections 4 and 5 we present the proof of existence of infinitely weak solutions with general initial conditions for the abstract problem combining approaches from [10], [11], [7], [8] and [15]. The result is extended in Section 6, where the existence of some suitable initial data allowing for infinitely many dissipative weak solutions is proven. For the reader's convenience, Section 7 contains some auxiliary results which are employed in the article.

2 The main results

We will denote by $\mathcal{C}([0, T]; X_w)$ the set of continuous functions from $[0, T]$ with values in a Banach space X equipped with the weak topology. For $B \subseteq \mathbb{R}^d$ open we denote $\mathcal{D}(B)$ the topological vector space of smooth functions with compact support in B and $\mathcal{D}'(B)$ its topological dual.

2.1 The Boussinesq equations

We start with introducing the definition of weak solutions to the problem (1) supplemented by (3) and (4), (5).

Definition 1. We call the quintet of functions (u, v, w, p, θ) a *weak solution of the inviscid Boussinesq equations* with (3), (4) if

- $u, v, w \in \mathcal{C}([0, T]; L_w^2(U)), p \in L^1(Q)$ and equations

$$\begin{aligned} \int_0^T \int_U u \partial_t \phi_1 \, d\mathbf{x} \, dt + \int_0^T \int_U \mathbf{u} \mathbf{u} \cdot \nabla_{\mathbf{x}} \phi_1 \, d\mathbf{x} \, dt + \int_U u_0(\cdot) \phi_1(0, \cdot) \, d\mathbf{x} \\ + \int_0^T \int_U (-\Omega_y w + \Omega_z v) \phi_1 \, d\mathbf{x} \, dt + \int_0^T \int_U p \partial_x \phi_1 \, d\mathbf{x} \, dt = 0, \end{aligned} \quad (6)$$

$$\begin{aligned} \int_0^T \int_U v \partial_t \phi_2 \, d\mathbf{x} \, dt + \int_0^T \int_U v \mathbf{u} \cdot \nabla_{\mathbf{x}} \phi_2 \, d\mathbf{x} \, dt + \int_U v_0(\cdot) \phi_2(0, \cdot) \, d\mathbf{x} \\ + \int_0^T \int_U (\Omega_x w - \Omega_z u) \phi_2 \, d\mathbf{x} \, dt + \int_0^T \int_U p \partial_y \phi_2 \, d\mathbf{x} \, dt = 0, \end{aligned} \quad (7)$$

$$\begin{aligned} \int_0^T \int_U w \partial_t \phi_3 \, d\mathbf{x} \, dt + \int_0^T \int_U w \mathbf{u} \cdot \nabla_{\mathbf{x}} \phi_3 \, d\mathbf{x} \, dt + \int_U w_0(\cdot) \phi_3(0, \cdot) \, d\mathbf{x} \\ + \int_0^T \int_U (-\Omega_x v + \Omega_y u) \phi_3 \, d\mathbf{x} \, dt + \int_0^T \int_U p \partial_z \phi_3 \, d\mathbf{x} \, dt = \int_0^T \int_U \theta \phi_3 \, d\mathbf{x} \, dt \end{aligned} \quad (8)$$

are satisfied for any $\phi_1, \phi_2, \phi_3 \in \mathcal{D}([0, T] \times U)$,

- $\mathbf{u} \chi_Q$ solves (1d) in $\mathcal{D}'((0, T) \times \mathbb{R}^3)$, i. e.

$$\int_0^T \int_U \mathbf{u} \cdot \nabla_{\mathbf{x}} \phi \, d\mathbf{x} \, dt = 0 \text{ for every } \phi \in \mathcal{D}((0, T) \times \mathbb{R}^3), \quad (9)$$

- $\theta \in W^{1,p}((0, T); L^p(U)) \cap L^p((0, T); W^{2,p}(U) \cap W_0^{1,p}(U))$ for a $p \in (1, \infty)$ and (1e) holds almost everywhere in Q and $\theta(0, \cdot) = \theta_0(\cdot)$ in the sense of time traces.

Theorem 2.1. *Let $T > 0$, U be a bounded open set with $\partial U \in \mathcal{C}^2$, $\mathbf{u}_0 \in L^\infty(U; \mathbb{R}^3) \cap \mathcal{C}(U; \mathbb{R}^3)$ with $\operatorname{div}_{\mathbf{x}}(u_0 \chi_U) = 0$ in the sense of distributions, $\theta_0 \in L^\infty(Q) \cap \mathcal{C}^2(Q)$ and $\Omega = \Omega(\mathbf{x}) \in L^\infty(U; \mathbb{R}^3)$. Then there exist infinitely many weak solutions to the Boussinesq equations in the sense of Definition 1.*

For the Boussinesq equations, the total energy is defined as the sum of the kinetic and potential energy:

$$E_{Bous}(t) = \int_U \frac{1}{2} |\mathbf{u}(t, \mathbf{x})|^2 + z \theta(t, \mathbf{x}) \, d\mathbf{x},$$

see also [23]. Referring to [12], we recall that the Boussinesq equations violate the principle of conservation of total energy. The quantity E_{Bous} would be conserved if the heat dissipation were neglected.

Definition 2. We say that a weak solution of the Boussinesq equations satisfies the *strong energy inequality* if $E_{Bous}(t)$ is non-increasing on $[0, T]$. We also call such solutions *dissipative*.

Let us mention that the weak solutions given by Theorem 2.1 are violating the strong energy inequality, particularly

$$\liminf_{t \rightarrow 0^+} E_{Bous}(t) > E_{Bous}(0).$$

Theorem 2.2. *Let $\Omega \in L^\infty(U; \mathbb{R}^3)$ and $\theta_0 \in L^\infty(U) \cap \mathcal{C}^2(U)$. Then there exists $\mathbf{u}_0 \in L^\infty(U; \mathbb{R}^3)$ for which we can find infinitely many weak dissipative solutions of the Boussinesq equations emanating from \mathbf{u}_0 .*

2.2 The primitive equations

Analogously, we present the definition of the weak solutions to (2):

Definition 3. We call the quintet of functions (u, v, w, p, θ) a *weak solution of the inviscid primitive equations* with (3), (4) if

- $\mathbf{u} = (u, v, w) \in L^2(Q; \mathbb{R}^3)$, $u, v \in \mathcal{C}([0, T]; L^2_w(U))$, $p \in L^1(Q)$, $\partial_z p \in L^1(Q)$ and equations (6) and (7) are satisfied for any $\phi_1, \phi_2 \in \mathcal{D}([0, T] \times U)$,
- $\mathbf{u}\chi_Q$ solves (9),
- $\theta \in W^{1,p}((0, T); L^p(U)) \cap L^p((0, T); W^{2,p}(U) \cap W_0^{1,p}(U))$ for a $p \in (1, \infty)$ and (2e) holds almost everywhere in Q and $\theta(0, \cdot) = \theta_0(\cdot)$ in the sense of time traces.
- equation (2c) holds for the weak derivative of p almost everywhere in Q .

As we will see, the problem of finding weak solutions of the primitive equations is highly underdetermined. Let us fix a function p and supplement the system by an equation describing the evolution of w :

$$\partial_t w + \mathbf{u} \cdot \nabla_{\mathbf{x}} w + \Omega_x v - \Omega_y u + \partial_z p = 0. \tag{10}$$

The equations (2a), (2b) and (10) can be recast in the usual vector form

$$\partial_t \mathbf{u} + \operatorname{div}_{\mathbf{x}}(\mathbf{u} \otimes \mathbf{u}) + \Omega \times \mathbf{u} + \nabla_{\mathbf{x}} p = 0,$$

where $\mathbf{u} = (u, v, w)$. We use the notion *extended primitive equations* for the system (2) coupled with (10) together with an additional initial condition for w . For the sake of completeness, we present the definition of the corresponding weak solution.

Definition 4. We call (\mathbf{u}, p, θ) a *weak solution of the extended primitive equations* with (3), (4), (5) if

- (\mathbf{u}, p, θ) is a weak solution of the inviscid primitive equations with (3), (4)

- $w \in \mathcal{C}([0, T]; L_w^2(U))$ and

$$\begin{aligned} & \int_0^T \int_U w \partial_t \phi_3 \, d\mathbf{x} \, dt + \int_0^T \int_U w \mathbf{u} \cdot \nabla_{\mathbf{x}} \phi_3 \, d\mathbf{x} \, dt + \int_U w_0(\cdot) \phi_3(0, \cdot) \, d\mathbf{x} \\ & + \int_0^T \int_U (-\Omega_x v + \Omega_y u) \phi_3 \, d\mathbf{x} \, dt + \int_0^T \int_U p \partial_z \phi_3 \, d\mathbf{x} \, dt = 0 \end{aligned} \quad (11)$$

is satisfied for any $\phi_3 \in \mathcal{D}([0, T] \times U)$.

Remark. Because of the well-posedness result, it seems to be unreasonable to work with the extended primitive equations. However, all the results following the approach of De Lellis and Székelyhidi (see e.g. [10], [11], [13] or [8]) are foreshadowing that weak formulations of inviscid problems in fluid dynamics are surprisingly highly underdetermined. The main results of this paper, namely Theorem 2.3, 2.5 and Corollary 2.4, are in agreement with this observation.

Theorem 2.3. *Let $T > 0$, U be a bounded open set with $\partial U \in \mathcal{C}^2$, $\mathbf{u}_0 \in L^\infty(U; \mathbb{R}^3) \cap \mathcal{C}(U; \mathbb{R}^3)$ with $\operatorname{div}_{\mathbf{x}}(u_0 \chi_U) = 0$ in the sense of distributions, $\theta_0 \in L^\infty(Q) \cap \mathcal{C}^2(Q)$ and $\Omega \in L^\infty(U; \mathbb{R}^3)$. Then there exist infinitely many weak solutions to the extended primitive equations with (3), (4) and (5).*

Corollary 2.4. *Let $\theta_0 \in L^\infty(Q) \cap \mathcal{C}^2(Q)$, $\Omega = \Omega(\mathbf{x}) \in L^\infty(U; \mathbb{R}^3)$ and let $u_0, v_0 \in L^\infty(U) \cap \mathcal{C}(U)$ be such that exists $w_0 \in L^\infty(U) \cap \mathcal{C}(U)$ satisfying*

$$\operatorname{div}_{\mathbf{x}}((u_0, v_0, w_0) \chi_U) = 0 \quad (12)$$

in the sense of distributions on \mathbb{R}^3 . Then there exist infinitely many weak solutions to the primitive equations with (3) and (4).

Remark. The technical assumption on u_0 and v_0 is needed only because we are considering boundary conditions (3a). If we took $U = \mathbb{T}^3$ then the additional condition leading to (12) would be $\partial_x u_0 + \partial_y v_0 \in L^\infty(U) \cap \mathcal{C}(U)$.

To the best of our knowledge, there are no a priori estimates on (u, v, w) in the case of inviscid primitive equations. Still, it is possible to find initial data for which there exist infinitely many weak solutions of the primitive equations satisfying the conservation of the kinetic energy or which are dissipating the mechanical energy. Let us define

$$E_{Prim}(t) = \int_U \frac{1}{2} (|u(t, \mathbf{x})|^2 + |v(t, \mathbf{x})|^2 + |w(t, \mathbf{x})|^2) \, d\mathbf{x}.$$

Definition 5. We say that a weak solution of the extended primitive equations or primitive equations satisfies the *strong energy inequality* if $E_{Prim}(t)$ is non-increasing on $[0, T)$. We also call such solutions *dissipative*.

Similarly to the previous section the weak solutions given by Theorem 2.3 are violating the strong energy inequality, particularly

$$\liminf_{t \rightarrow 0^+} E_{Prim}(t) > E_{Prim}(0).$$

Theorem 2.5. *There exists $\mathbf{u}_0 \in L^\infty(U; \mathbb{R}^3)$ for which we can find infinitely many weak dissipative solutions of the extended primitive equations emanating from \mathbf{u}_0 .*

Remark. To obtain the largest possible space for initial temperatures in which the given method holds, we can apply the theory of maximal regularity for parabolic equations (see e. g. [1]). Particularly, θ_0 can be taken arbitrarily from the interpolation space $[L^p, W^{2,p}]_\alpha$ for a suitable $p \in (1, \infty)$ and $\alpha \in (0, 1)$.

3 Abstract Euler-type system

To use the techniques from [10], [11], we will follow [14], [15] and reformulate the Boussinesq and the extended primitive equations as an Euler-type equation. Let us denote by $\mathbf{u} \odot \mathbf{u} = \mathbf{u} \otimes \mathbf{u} - \frac{1}{3}|\mathbf{u}|^2\mathbb{I}$ the traceless part of the symmetric matrix $\mathbf{u} \otimes \mathbf{u}$. We will introduce operators $\mathbb{H}: L^\infty(Q; \mathbb{R}^3) \rightarrow L^1(Q; \mathbb{R}_{0,sym}^{3 \times 3})$, $\Pi: L^\infty(Q; \mathbb{R}^3) \rightarrow L^1(Q)$ and consider the abstract Euler-type system

$$\partial_t \mathbf{u} + \operatorname{div}_{\mathbf{x}}(\mathbf{u} \odot \mathbf{u} + \mathbb{H}(\mathbf{u})) + \nabla_{\mathbf{x}} \left(\Pi[\mathbf{u}] + \frac{1}{3}|\mathbf{u}|^2 \right) = 0 \text{ in } Q, \quad (13a)$$

$$\operatorname{div}_{\mathbf{x}}(\mathbf{u}) = 0 \text{ in } Q, \quad (13b)$$

$$\mathbf{u} \cdot \boldsymbol{\eta} = 0 \text{ on } (0, T) \times \partial U, \quad (13c)$$

$$\mathbf{u}(0) = \mathbf{u}_0 \text{ in } U, \quad (13d)$$

For the sake of completeness, we add a definition of weak solutions of (13):

Definition 6. We say that $\mathbf{u}: Q \rightarrow \mathbb{R}^3$ is a weak solution of the abstract Euler system (13) if

- $\mathbf{u} \in \mathcal{C}([0, T]; L_w^2(U))$,
- \mathbf{u} satisfies (13a) in $\mathcal{D}'(Q)$,
- $\mathbf{u}\chi_U$ satisfies (13b) in $\mathcal{D}'((0, T) \times \mathbb{R}^3)$,
- $\mathbf{u}(0) = \mathbf{u}_0$.

Theorem 3.1. *Let $T > 0$, $\mathbf{u}_0 \in L^\infty(U; \mathbb{R}^3) \cap \mathcal{C}(U; \mathbb{R}^3)$ with $\operatorname{div}_{\mathbf{x}}(u_0\chi_U) = 0$ in the sense of distributions. Assume that the \mathbb{H} and Π have the following properties:*

- \mathbb{H} is continuous from $\mathcal{C}([0, T]; L_w^q(U))$ to $\mathcal{C}(\overline{Q}; \mathbb{R}_{0,sym}^{3 \times 3})$ and mapping bounded sets to bounded sets (with respect to the mentioned topologies).
- Π is continuous from $\mathcal{C}([0, T]; L_w^q(U))$ to $\mathcal{C}(\overline{Q})$ and there exists $\overline{\Pi} \in \mathbb{R}$ such that

$$\Pi[\mathbf{u}] < \overline{\Pi} \quad \text{for every } \mathbf{u} \in L^\infty(Q; \mathbb{R}^3). \quad (14)$$

- For $\mathbf{u}, \mathbf{w} \in L^\infty(Q; \mathbb{R}^3)$ with $\operatorname{supp} \mathbf{w} \subseteq (\tau, T) \times \overline{U}$

$$\Pi[\mathbf{u} + \mathbf{w}] = \Pi[\mathbf{u}], \quad \mathbb{H}[\mathbf{u} + \mathbf{w}] = \mathbb{H}[\mathbf{u}], \quad \text{almost everywhere in } (0, \tau) \times U. \quad (15)$$

Then there exist infinitely many weak solutions to (13) which moreover satisfy

$$\frac{3}{2}\Pi[\mathbf{u}](t, \mathbf{x}) + \frac{1}{2}|\mathbf{u}(t, \mathbf{x})|^2 = \frac{3}{2}Z(t) \quad \text{for every } t \in (0, T), \text{ almost everywhere in } U, \quad (16)$$

for any function $Z(t)$ continuous on $[0, T]$ satisfying $\sup_{t \in [0, T]} Z(t) > \bar{\Pi}$.

In the first part of this Section, we will show that Theorem 2.1 and 2.3 follow directly from Theorem 3.1 after suitable choices of \mathbb{H} and Π . In the second part, we will present the notion of subsolution for (13) and important properties of the set of subsolutions.

3.1 Reformulation of the Boussinesq equations

Assume that θ_0 and Ω comply with the assumptions of Theorem 2.1. Using the classical theory of parabolic equations (see e. g. Lemma 7.3) we can define an operator $\Theta = \Theta[\mathbf{u}]$ from $L^\infty(Q; \mathbb{R}^3)$ to $\mathcal{C}([0, T] \times \bar{U})$ such that $\theta = \Theta[\mathbf{u}]$ solves (1e) in the sense of Definition 1. The operator $\mathbf{u} \mapsto \Theta[\mathbf{u}]$ is continuous from $\mathcal{C}([0, T]; L_w^q(U))$ to $\mathcal{C}([0, T] \times \bar{U})$ (for q large enough).

Using Corollary 7.2, we obtain the existence of a linear operator $\mathbb{H}_{Bous} = \mathbb{H}_{Bous}[\mathbf{u}]$ from $L^\infty(Q; \mathbb{R}^3)$ to $\mathcal{C}(\bar{Q}; \mathbb{R}_{0, sym}^{3 \times 3})$ such that

$$\operatorname{div}_{\mathbf{x}}(\mathbb{H}_{Bous}[\mathbf{u}]) = \Omega \times \mathbf{u} + \begin{pmatrix} 0 \\ 0 \\ \Theta[\mathbf{u}] \end{pmatrix} - \nabla \left(\frac{2}{3}z\Theta[\mathbf{u}] \right).$$

Define $\Pi_{Bous}[\mathbf{u}] = \frac{2}{3}z\Theta[\mathbf{u}]$. The operator Π_{Bous} is continuous from $\mathcal{C}([0, T]; L_w^q(U))$ to $\mathcal{C}(\bar{Q})$ and \mathbb{H}_{Bous} is continuous from $\mathcal{C}([0, T]; L_w^q(U; \mathbb{R}^3))$ to $\mathcal{C}(\bar{Q})$ for any $q > 3$. Both operators are mapping bounded sets from $L^\infty(Q)$ on bounded sets in $\mathcal{C}(\bar{Q})$. Using the maximum principle for (2e), see Lemma 7.3, we obtain

$$|\Pi_{Bous}[\mathbf{u}](t, \mathbf{x})| \leq \frac{2}{3}\|z \cdot \theta_0\|_{L^\infty(U)} < \infty \text{ for every } (t, \mathbf{x}) \in Q.$$

The condition (15) holds from the definition of the operators. Indeed, $\Theta: L^\infty(Q; \mathbb{R}^3)$ is a unique solution of an evolutionary equation and $\mathbf{v} = 0$ is the only solution of (28) with $\mathbf{g} = 0$ with zero boundary conditions. If \mathbf{u} is a weak solution of (13) then the triplet $(\mathbf{u}, p, \theta) = (\mathbf{u}, 0, \Theta[\mathbf{u}])$ is a weak solution of (1), hence Theorem 2.1 is a corollary of Theorem 3.1.

3.2 Reformulation of the extended primitive equations

Assume that θ_0 , \mathbf{u}_0 , P and Ω comply with the assumptions of Theorem 2.3. For a given \mathbf{u} we can extend $\Theta[\mathbf{u}]$ continuously with respect to space on $[0, T] \times \mathbb{R}^3$. As U is bounded, one can define an extension $\Theta[\mathbf{u}]$ such that it has compact support. Let us take arbitrary function $P \in \mathcal{C}([0, T] \times \mathbb{R}^2)$. The function $p: Q \rightarrow \mathbb{R}$ defined by

$$p(t, x, y, z) = P(t, x, y) - \int_{-\infty}^z \Theta[\mathbf{u}](t, x, y, s) \, ds$$

satisfies (2c) and the operator $\Gamma_{Prim} = \Gamma_{Prim}[\mathbf{u}] : \mathbf{u} \mapsto p$ maps functions from $L^\infty(Q; \mathbb{R}^3)$ to $\mathcal{C}(\bar{Q})$. The operator Γ_{Prim} is continuous from $\mathcal{C}([0, T]; L_w^q(U))$ to $\mathcal{C}(\bar{Q})$. Using Corollary 7.2, we obtain existence of a linear operator $\mathbb{H}_{Prim} = \mathbb{H}_{Prim}[\mathbf{u}]$ from $L^\infty(Q; \mathbb{R}^3)$ to $\mathcal{C}(\bar{Q}; \mathbb{R}_{0, sym}^{3 \times 3})$ such that

$$\operatorname{div}_{\mathbf{x}}(\mathbb{H}_{Prim}[\mathbf{u}]) = \Omega \times \mathbf{u} + \nabla \Gamma_{Prim}[\mathbf{u}].$$

Similarly to the Boussinesq equations, \mathbb{H}_{Prim} is continuous from $\mathcal{C}([0, T]; L_w^q(U; \mathbb{R}^3))$ to $\mathcal{C}(\bar{Q})$ for any $q > 3$. Both operators are mapping bounded sets from $L^\infty(Q)$ on bounded sets in $\mathcal{C}(\bar{Q})$. For any weak solution \mathbf{u} of (13) the triplet $(\mathbf{u}, p, \theta) = (\mathbf{u}, \Gamma_{Prim}, \Theta[\mathbf{u}])$ is a weak solution of the extended primitive equations. Therefore also Theorem 2.3 is a corollary of Theorem 3.1.

3.3 Subsolutions for the abstract Euler equation

Let \mathbf{u}_0 comply with the assumptions of Theorem 3.1. Observe that the abstract system is invariant with respect to adding a continuous function $Z = Z(t)$ to the pressure term $\Pi[\mathbf{u}]$. Moreover, $\tilde{\Pi}[\mathbf{u}] = \Pi[\mathbf{u}] + Z$ satisfies the same qualitative properties as Π in Theorem 3.1.

Let us fix $Z = Z(t)$ continuous on $[0, T]$ such that

$$\Pi[\mathbf{v}(t, \mathbf{x})] < Z(t) \quad \text{for } (t, \mathbf{x}) \in Q$$

for any $\mathbf{v} \in L^\infty(Q; \mathbb{R}^3)$. Such function Z exists due to the boundedness of Π . We restrict our attention only on the so-called pressureless case, i. e. when solutions are satisfying

$$\Pi[\mathbf{u}] + \frac{1}{3}|\mathbf{u}|^2 - Z(t) = 0 \quad \text{in } Q.$$

Mimicking the strategy of De Lellis and Székelyhidi we recast the abstract system into a linear system supplemented by implicit constitutive (possibly non-algebraic) relations:

$$\partial_t \mathbf{u} + \operatorname{div}_{\mathbf{x}} \mathbb{V} = 0, \tag{17a}$$

$$\operatorname{div}_{\mathbf{x}} \mathbf{u} = 0, \tag{17b}$$

$$\mathbb{V} = \mathbf{u} \odot \mathbf{u} + \mathbb{H}(\mathbf{u}), \tag{17c}$$

$$\frac{1}{2}|\mathbf{u}|^2 = \frac{3}{2}(Z(t) - \Pi[\mathbf{u}]). \tag{17d}$$

To introduce a suitable notion of subsolution we put

$$\bar{e}[\mathbf{u}] = \frac{3}{2}(Z(t) - \Pi[\mathbf{u}])$$

and

$$e(\mathbf{u}, \mathbb{V}) = \frac{3}{2} \lambda_{\max}[\mathbf{u} \otimes \mathbf{u} + \mathbb{H}[\mathbf{u}] - \mathbb{V}],$$

where $\lambda_{\max}(\mathbb{U})$ denotes the maximal eigenvalue of $\mathbb{U} \in \mathbb{R}_{sym}^{3 \times 3}$. One has for any $\mathbf{v} \in \mathbb{R}^3$ and $\mathbb{U} \in \mathbb{R}_{0, sym}^{3 \times 3}$ the following inequality

$$\frac{1}{2}|\mathbf{v}|^2 \leq \frac{3}{2} \lambda_{\max}(\mathbf{v} \otimes \mathbf{v} + \mathbb{U}) \tag{18}$$

and the equality holds if and only if

$$\mathbb{U} = \mathbf{v} \otimes \mathbf{v} - \frac{1}{3}|\mathbf{v}|^2\mathbb{I}. \quad (19)$$

It is possible to estimate \mathbb{U} by the means of $|e(\mathbf{v}, \mathbb{U})|$, particularly

$$|\mathbb{U}|_{\ell^\infty} \leq 2|\lambda_{\min}(\mathbb{U})| \leq \frac{4}{3}e(\mathbf{v}, \mathbb{U}). \quad (20)$$

Analogously to [15]:

Definition 7. We call a pair (\mathbf{u}, \mathbb{V}) a *subsolution of the abstract Euler system* (or briefly a *subsolution*) if

1. $\mathbf{u} \in C([0, T]; L_w^2(U; \mathbb{R}^3)) \cap \mathcal{C}(Q; \mathbb{R}^3)$ and $\mathbb{V} \in L^\infty \cap \mathcal{C}(Q; \mathbb{R}_{0, sym}^{3 \times 3})$,
2. the pair (\mathbf{u}, \mathbb{V}) satisfies (17a) in the sense of distributions on Q and $\mathbf{u}\chi_U$ solves (17b) in the sense of distributions on $(0, T) \times \mathbb{R}^3$,
3. $\mathbf{u}(0) = \mathbf{u}_0$,
4. for every $0 < \tau < T$ $\text{ess inf}_{t \in (\tau, T), \mathbf{x} \in U} (\bar{e}[\mathbf{u}](t, \mathbf{x}) - e(\mathbf{u}(t, \mathbf{x}), \mathbb{V}(t, \mathbf{x}))) > 0$.

We denote X_0 the set of all \mathbf{u} for which exist \mathbb{V} such that (\mathbf{u}, \mathbb{V}) is a subsolution of the abstract Euler type system. Let us remark that there exists a constant $E > 0$ such that $\bar{e}[\mathbf{u}] \leq E$ for every $\mathbf{u} \in X_0$. Observe that (14), (18) and (20) imply the boundedness of X_0 in $L^\infty(Q; \mathbb{R}^3)$.

We consider for each $\tau \in (0, T/2)$ a negative functional I_τ on X_0 defined by

$$I_\tau(\mathbf{u}) = \inf_{t \in (\tau, T-\tau)} \int_U \frac{1}{2} |\mathbf{u}(t, \mathbf{x})|^2 - \bar{e}[\mathbf{u}(t, \mathbf{x})] \, d\mathbf{x}.$$

Lemma 3.2. *Let $\{(\mathbf{u}_n, \mathbb{V}_n)\}_{n \in \mathbb{N}}$ be subsolutions. Then there exists a pair (\mathbf{u}, \mathbb{V}) such that for a suitable subsequence (not relabeled)*

$$\mathbf{u}_n \rightarrow \mathbf{u} \text{ strongly in } \mathcal{C}([0, T]; L_w^2(U; \mathbb{R}^3)) \text{ and weakly-* in } L^\infty(Q; \mathbb{R}^3) \quad (21)$$

$$\mathbb{V}_n \rightarrow \mathbb{V} \text{ weakly-* in } L^\infty(Q; \mathbb{R}_{0, sym}^{3 \times 3}) \quad (22)$$

holds. The limit (\mathbf{u}, \mathbb{V}) is satisfying all conditions on subsolutions except condition 4, where only (nonstrict) inequality holds. Moreover, if

$$I_\tau(\mathbf{u}) = 0 \text{ for each } \tau > 0 \quad (23)$$

then \mathbf{u} is a weak solution of the abstract Euler system (13) satisfying (16) for suitable functions Z .

Proof. As X_0 consists of functions bounded in $L^\infty(Q; \mathbb{R}^3)$, \mathbf{u}_n resp. \mathbb{V}_n are also uniformly bounded in $L^\infty(Q; \mathbb{R}^3)$ resp. $L^\infty(Q; \mathbb{R}_{0, sym}^{3 \times 3})$. The standard time regularity for weak solutions together with the Arzelà-Ascoli theorem implies the existence of \mathbf{u} and \mathbb{V} such that (21) holds

for a suitable subsequence. With respect to Lemma 7.4, the pair (\mathbf{u}, \mathbb{V}) satisfies all conditions on subsolutions except condition 4.

If, moreover, $I_\tau(\mathbf{u}) = 0$ for every $\tau \in (0, T)$ then $\frac{1}{2}|\mathbf{u}|^2 = \bar{e}[\mathbf{u}] = \frac{3}{2}(Z(t) - \Pi[\mathbf{u}])$ everywhere in $(0, T)$ and a.e. in U and (19) hold almost everywhere in $(0, T) \times \Omega$. Hence, thanks to the hypothesis of the lemma

$$\mathbb{V} = \mathbb{H}[\mathbf{u}] + \mathbf{u} \otimes \mathbf{u} - \frac{1}{3}|\mathbf{u}|^2 \mathbb{I} \quad \text{a. e. in } (0, T) \times \Omega$$

and \mathbf{u} is a weak solution of (17). □

4 Existence result for the abstract Euler-type system

An important step on the way to find $\mathbf{u} \in X$ satisfying (23) is the following possibility to appropriately perturb any subsolution so that I increases. The proof of the following lemma is postponed until Section 5.

Lemma 4.1 (Oscillatory lemma). *Let $\mathbf{u} \in X_0$ and (\mathbf{u}, \mathbb{V}) be a subsolution and $\tau > 0$. Then there exist sequences $\{\mathbf{w}_n\}_{n \in \mathbb{N}} \subseteq \mathcal{D}((\tau, T) \times U; \mathbb{R}^3)$ and $\{\mathbb{W}_n\}_{n \in \mathbb{N}} \subseteq \mathcal{D}((\tau, T) \times U; \mathbb{R}_{0, \text{sym}}^{3 \times 3})$ such that:*

- $(\mathbf{u} + \mathbf{w}_n, \mathbb{V} + \mathbb{W}_n)$ are subsolutions,
- $\mathbf{w}_n \rightarrow 0$ in $\mathcal{C}([0, T]; L_w^2(U))$,
- there exists $c = c(E) > 0$ such that

$$\liminf_{n \rightarrow \infty} I_\tau(\mathbf{u} + \mathbf{w}_n) \geq I_\tau(\mathbf{u}) + c(E) (I_\tau(\mathbf{u}))^2. \quad (24)$$

Remark. The constant $c(E)$ does not depend on \mathbf{u} or τ .

The existence of infinitely many weak solutions is then concluded from a Baire category argument similar to e. g. [10].

Lemma 4.2. *Let (X, d) be a complete metric space, $I: X \rightarrow (-\infty; 0]$ a function of Baire class 1. Let X_0 be a nonempty dense subset of X with the following property: for any $\beta < 0$ there exists $\alpha = \alpha(\beta) > 0$ such that for any $x \in X_0$ satisfying $I(x) < \beta < 0$ there exists $x_n \in X_0$ with*

- $x_n \rightarrow x$ in (X, d) and
- $\liminf_{n \rightarrow \infty} I(x_n) \geq I(x) + \alpha(\beta)$.

Then there exists a residual set $S \subseteq X$ such that $I(x) = 0$ on S .

Proof. As (X, d) is complete, the set of points of continuity of functions of Baire class 1 on X is residual. To complete the proof, it is sufficient to show that $I = 0$ on the set of points of continuity. We prove that by contradiction. Let x be a point of continuity of I such that $I(x) < \beta < 0$. Then from the density of X_0 , there exists a sequence $\{x_n\}_{n \in \mathbb{N}} \subseteq X_0$,

converging to x and $I(x_n) \rightarrow I(x)$. Without loss of generality, we may assume that $I(x_n) < \beta$. For each $n \in \mathbb{N}$ there exists sequence $\{x_{n,k}\}_{k \in \mathbb{N}}$ satisfying the conditions given by the hypothesis of the lemma. By a diagonal argument we can find a subsequence $\{x_{n,k(n)}\}_{n \in \mathbb{N}} \subseteq X_0$ such that $x_{n,k(n)} \rightarrow x$ and

$$\liminf_{n \rightarrow \infty} I(x_{n,k(n)}) \leq I(x_n) + \alpha(\beta).$$

This contradicts the assumption that x is a point of continuity of I . \square

Proof of Theorem 3.1. Let X_0 be the set of subsolutions to the abstract Euler system. X_0 consists of functions $\mathbf{u} : [0, T] \rightarrow L^2(U)$ taking values in a bounded subset Y of $L^2(U)$. Hence Y is metrizable with respect to the weak topology of L^2 . Correspondingly, we consider the metric d naturally defined on $\mathcal{C}([0, T]; Y)$ which induces a topology equivalent to the topology of $\mathcal{C}([0, T]; Y)$ as a subset of $\mathcal{C}([0, T]; L_w^2(U))$. We denote by X the completion of X_0 in $\mathcal{C}([0, T]; L_w^2(U))$ with respect to the metric d . Obviously, X is bounded in $L^\infty(Q; \mathbb{R}^3)$. The set X_0 is non-empty as it makes no difficulty to check that $\mathbf{u}(t) = \mathbf{u}_0$ with $\mathbb{V} = \mathbf{0}$ defines a subsolution.

For each $\tau \in (0, T/2)$, I_τ can be extended on a lower-semicontinuous functional on X and therefore is of Baire class 1. Indeed, observe that $\bar{\mathbf{e}}$ is continuous from (X, d) to $\mathcal{C}(\bar{Q})$, hence, the semicontinuity follows from the case when $\bar{\mathbf{e}}$ is a constant function (see [11, Lemma 5]).

Finally, a combination of Lemma 4.1, 4.2 and 3.2 implies the existence of residual sets

$$S_\tau = \{x \in X : I_\tau(x) = 0\}.$$

The set $S = \bigcap_{n=1}^\infty S_{\frac{1}{n}}$ is also residual, especially nonempty and of infinite cardinality. Due to Lemma 3.2, all functions in S are weak solutions to the abstract Euler problem with $\mathbf{u}(0, \mathbf{x}) = \mathbf{u}_0$ and such that (16) holds. \square

5 Proof of Lemma 4.1

We start with a special case of the oscillatory lemma when the operators \mathbb{H} and $\bar{\mathbf{e}}$ are not depending on \mathbf{u} . Let us define $\tilde{\mathbf{e}} : \mathbb{R}^3 \times \mathbb{R}_{0, \text{sym}}^{3 \times 3} \times \mathbb{R}_{0, \text{sym}}^{3 \times 3} \rightarrow \mathbb{R}$ by

$$\tilde{\mathbf{e}}(\mathbf{u}, \mathbb{V}, \mathbb{G}) = \frac{3}{2} \lambda_{\max}(\mathbf{u} \otimes \mathbf{u} + \mathbb{G} - \mathbb{V}).$$

For $f \in L^\infty \cap \mathcal{C}(Q)$ and $\mathbb{G} \in L^\infty \cap \mathcal{C}(Q; \mathbb{R}_{0, \text{sym}}^{3 \times 3})$ we denote $X_{0, \mathbb{G}, f}$ the set of all functions \mathbf{u} satisfying

1. $\mathbf{u} \in C([0, T]; L_w^2(U; \mathbb{R}^3)) \cap \mathcal{C}((0, T) \times U; \mathbb{R}^3)$,
2. exists $\mathbb{V} \in L^\infty \cap \mathcal{C}((0, T) \times U; \mathbb{R}_{0, \text{sym}}^{3 \times 3})$ such that the pair (\mathbf{u}, \mathbb{V}) satisfies (17a) in the sense of distributions on $(0, T) \times U$ and $\mathbf{u} \chi_U$ solves (17b) in the sense of distributions on $(0, T) \times \mathbb{R}^3$,
3. $\mathbf{u}(0) = \mathbf{u}_0$,
4. for every $\tau > 0$ $\inf_{t \in (\tau, T), \mathbf{x} \in U} (f(t, \mathbf{x}) - \tilde{\mathbf{e}}(\mathbf{u}(t, \mathbf{x}), \mathbb{V}(t, \mathbf{x}), \mathbb{G}(t, \mathbf{x}))) > 0$.

The following auxiliary result was proven in [13] for I_τ defined using integrals with respect to time and space. In our case, the proof remains the same and we will omit it (see also [11] where the functional setting is the same as ours).

Lemma 5.1. *Let $O = (\tau_1, \tau_2) \times U \subseteq Q$ be an open set, \mathbb{G} and f be as above with $f > 0$ in Q . Assume that $\mathbf{u} \in X_{0,f,\mathbb{G}}$. Then exists $\Lambda > 0$ and sequences $\{\mathbf{w}_n\}_{n \in \mathbb{N}} \subseteq \mathcal{D}(O; \mathbb{R}^3)$ and $\{\mathbb{W}_n\}_{n \in \mathbb{N}} \subseteq \mathcal{D}(O; \mathbb{R}_{0,sym}^{3 \times 3})$ such that $(\mathbf{u} + \mathbf{w}_n, \mathbb{V} + \mathbb{W}_n) \in X_{0,f,\mathbb{G}}$,*

$$\mathbf{w}_n \rightarrow 0 \text{ in } \mathcal{C}([0, T]; L_w^2(U))$$

and

$$\liminf_{n \rightarrow \infty} \inf_{t \in (\tau_1, \tau_2)} \int_U |\mathbf{u} + \mathbf{w}_n|^2 dx \geq \inf_{t \in (\tau_1, \tau_2)} \int_U |\mathbf{u}|^2 dx + \Lambda \left(\inf_{t \in (\tau_1, \tau_2)} \int_U f - \frac{1}{2} |\mathbf{u}|^2 dx \right)^2, \quad (25)$$

where $\Lambda = \Lambda(\sup_{(t,\mathbf{x}) \in Q} |f|)$ (namely, Λ does not depend on O or \mathbf{u}_n).

Let us show that Lemma 4.1 follows from Lemma 5.1 using a perturbation argument.

Proof of Lemma 4.1. If $\mathbf{u} \in X_0$ then there exists an increasing continuous function $\delta: (0, T) \rightarrow (0, +\infty)$ such that for any $s \in (0, T)$

$$\inf_{t \in (s, T), x \in U} (\bar{e}[\mathbf{u}] - e(\mathbf{u}, \mathbb{V})) > \delta(s).$$

Hence, $\mathbf{u} \in X_{0, \bar{e}[\mathbf{u}] - \delta, \mathbb{H}[\mathbf{u}]}$ and we obtain sequences $\{\mathbf{w}_n\}_{n \in \mathbb{N}}$ and $\{\mathbb{W}_n\}_{n \in \mathbb{N}}$ satisfying Lemma 5.1 with $f = \bar{e}[\mathbf{u}] - \delta$ and $\mathbb{G} = \mathbb{H}[\mathbf{u}]$. Moreover, due to the boundedness of \mathbf{w}_n and \mathbb{W}_n , we have

$$\mathbf{w}_n \rightarrow 0 \text{ in } \mathcal{C}([0, T]; L_w^p(U)) \text{ for any } p \in [1, \infty),$$

see Lemma 7.4. Inequality (24) follows directly from (25) as $\bar{e}[\mathbf{u} + \mathbf{w}_n] \rightarrow \bar{e}[\mathbf{u}]$ uniformly in Q . Hence, to finish the proof, it is sufficient to check that $\mathbf{u} + \mathbf{w}_n \in X_0$ at least for indices large enough. As $\mathbf{u} + \mathbf{w}_n \in X_{0, \bar{e}[\mathbf{u}] - \delta, \mathbb{H}[\mathbf{u}]}$, we get

$$e(\mathbf{u} + \mathbf{w}_n, \mathbb{V} + \mathbb{W}_n) = \tilde{e}(\mathbf{u} + \mathbf{w}_n, \mathbb{V} + \mathbb{W}_n, \mathbb{H}[\mathbf{u}]) + r_n < \bar{e}[\mathbf{u}] - \delta + r_n = \bar{e}[\mathbf{u} + \mathbf{w}_n] - \delta + r_n + t_n,$$

where

$$r_n = \tilde{e}(\mathbf{u} + \mathbf{w}_n, \mathbb{V} + \mathbb{W}_n, \mathbb{H}[\mathbf{u} + \mathbf{w}_n]) - \tilde{e}(\mathbf{u} + \mathbf{w}_n, \mathbb{V} + \mathbb{W}_n, \mathbb{H}[\mathbf{u}])$$

and

$$t_n = \bar{e}[\mathbf{u}] - \bar{e}[\mathbf{u} + \mathbf{w}_n].$$

The function $\mathbb{A} \mapsto \lambda_{max}(\mathbb{A})$ restricted on the symmetric positive semidefinite matrices is equal to $\ell^2 \rightarrow \ell^2$ operator norm, hence it is 1-Lipschitz. Thus, using the continuity of \mathbb{H} and \bar{e} , we obtain

$$r_n + t_n \rightarrow 0 \text{ uniformly in } [\tau, T] \times U.$$

Having in mind (15), we claim that $r_n + t_n = 0$ for $(t, \mathbf{x}) \in (0, \tau) \times U$, therefore

$$e(\mathbf{u} + \mathbf{w}_n, \mathbb{V} + \mathbb{W}_n) < \bar{e}[\mathbf{u} + \mathbf{w}_n] - \frac{\delta}{2}$$

holds on Q for sufficiently large n . □

6 Dissipative solutions

This Section is devoted to the proofs of Theorems 2.2 and 2.5. Thanks to the reformulation of the Boussinesq and the extended primitive equations in the framework of abstract Euler-type systems carried out in Section 3, Theorems 2.2 and 2.5 can be reduced to prove the following more general theorem on the abstract system.

Theorem 6.1. *Under the same hypotheses on \mathbb{H} and Π of Theorem 3.1, there exists $\mathbf{u}_0 \in L^\infty(U; \mathbb{R}^3)$ for which we can find infinitely many weak solutions to (13) emanating from \mathbf{u}_0 and such that the functional*

$$E_{abs}(t) := \int_U \left(\frac{3}{2} \Pi[\mathbf{u}](t, \mathbf{x}) + \frac{1}{2} |\mathbf{u}(t, \mathbf{x})|^2 \right) dx \quad \text{is non-increasing on } [0, T]. \quad (26)$$

Remark. Thanks to Theorem 3.1, and in particular to the property (16), the conclusion that the functional $E_{abs}(t)$ is non-increasing on $(0, T)$ can be achieved for any $\mathbf{u}_0 \in L^\infty(U; \mathbb{R}^3) \cap \mathcal{C}(U; \mathbb{R}^3)$ with $\operatorname{div}_{\mathbf{x}}(u_0 \chi_U) = 0$ by simply choosing the function $Z(t)$ to be non-increasing on $(0, T)$. But in order to obtain dissipative solutions for the Boussinesq and primitive equations the property (26) is required up to time $t = 0$: this forces the construction of suitable initial data $\mathbf{u}_0 \in L^\infty(U; \mathbb{R}^3)$.

We now show how Theorems 2.2 and 2.5 follow from Theorem 6.1.

Proofs of Theorems 2.2 and 2.5. Due to the reformulations of the Boussinesq and extended primitive equations of Section 3, the respective choices for Π are $\Pi_{Bous}[\mathbf{u}] = \frac{2}{3} z \Theta[\mathbf{u}]$ and $\Pi_{Prim} = 0$. These choices allow to obtain from E_{abs} exactly E_{Bous} and E_{Prim} respectively. Hence the conclusion of Theorem 6.1 implies the existence of infinitely many dissipative solutions to the Boussinesq and extended primitive equations starting from suitably constructed initial data \mathbf{u}_0 , as stated in Theorems 2.2 and 2.5. \square

6.1 Construction of initial data

The abstract Euler system (13) fits the framework introduced by Feireisl in [15]. In particular, we can apply Theorem 6.1 therein to obtain strong continuity in L^2 at time $t = 0$. For the sake of completeness, we report here a version of [15, Theorem 6.1] adapted to our context. For other variants of the following result we refer to [11] and also to [7], [8].

Lemma 6.2. *Let \mathbb{H} and Π satisfy the hypotheses of Theorem 3.1. Then there exist a set of times $\mathcal{R} \subset (0, T)$ dense in $(0, T)$ such that for any $\tau \in \mathcal{R}$ there is $\mathbf{u} \in X$ with the following properties*

- (i) $\mathbf{u} \in C(((0, \tau) \cup (\tau, T)) \times U) \cap C([0, T], L_w^2)$, $\mathbf{u}(0, \cdot) = \mathbf{0}$,
- (ii) there exists $\mathbb{V} \in C(((0, \tau) \cup (\tau, T)) \times U; \mathbb{R}_{0, sym}^{3 \times 3})$ the pair (\mathbf{u}, \mathbb{V}) satisfies (17a) in the sense of distributions on Q and $\mathbf{u} \chi_U$ solves (17b) in the sense of distributions on $(0, T) \times \mathbb{R}^3$,
- (iii) $(\bar{e}[\mathbf{u}](t, \mathbf{x}) - e(\mathbf{u}(t, \mathbf{x}), \mathbb{V}(t, \mathbf{x}))) > 0$ for all $(t, \mathbf{x}) \in ((0, \tau) \cup (\tau, T)) \times U$,

(iv) $\frac{1}{2}|\mathbf{u}(\tau, \mathbf{x})|^2 = \bar{e}[\mathbf{u}](\tau, \mathbf{x})$ a.e. in U

where we recall that

$$\bar{e}[\mathbf{u}](t, \mathbf{x}) = \frac{3}{2}(Z(t) - \Pi[\mathbf{u}](t, \mathbf{x}))$$

for a continuous function $Z(t)$ satisfying $\sup_{t \in [0, T]} Z(t) > \bar{\Pi}$.

Remark. Lemma 6.2 provides subsolutions which are strongly continuous at the point τ and allow to obtain the desired strong energy conditions.

For the proof we refer the reader to [15].

Proof of Theorem 6.1. The proof consists in finding an initial datum $\mathbf{u}_0 \in L^\infty(U; \mathbb{R}^3)$ and a function $Z(t)$ with the following properties

$$\frac{1}{2}|\mathbf{u}_0(\mathbf{x})|^2 = \bar{e}[\mathbf{u}_0](\mathbf{x}) \quad \text{a.e. in } U; \quad (27)$$

- $Z(t)$ continuous on $[0, T]$ and $\sup_{t \in [0, T]} Z(t) > \bar{\Pi}$,
- $Z'(t) \leq 0$ for all $t \in [0, T]$

and such that the set X_0 of subsolutions \mathbf{u} associated to this datum is non-empty. First of all, we notice that we can easily choose $Z(t) = C_Z$ for some constant $C_Z > \bar{\Pi}$. Once Z has been chosen, then we apply Lemma 6.2 which provides the existence of a time $\tau \in \mathcal{R}$ and a function \mathbf{u} for which (i)–(iv) hold. We define the initial datum \mathbf{u}_0 to be $\mathbf{u}_0(\cdot) = \mathbf{u}(\tau, \cdot)$ in U . To such a datum we associate, as in Section 3, the set of subsolutions X_0 and we can prove that it is non-empty by choosing as eligible element the following subsolution

$$\bar{\mathbf{u}}(t, \mathbf{x}) = \begin{cases} \mathbf{u}(t + \tau, \mathbf{x}) & \text{for } t \in [0, T - \tau] \\ \mathbf{u}(t - (T - \tau), \mathbf{x}) & \text{for } t \in [T - \tau, T] \end{cases}$$

with relative matrix field $\bar{\mathbb{V}}$ analogously defined. Indeed from (27), redoing the proof of Theorem 3.1, we would now obtain infinitely many solutions to (13) emanating from \mathbf{u}_0 and such that

$$\left(\frac{3}{2}\Pi[\mathbf{u}](t, \mathbf{x}) + \frac{1}{2}|\mathbf{u}(t, \mathbf{x})|^2 \right) = \frac{3}{2}C_Z \quad \text{for all } t \in [0, T] \text{ and a.e. in } U$$

(we remark that the equality now holds up to time $t = 0$) which implies Theorem 6.1. □

7 Appendix

7.1 The Lamé system

Let us denote

$$\mathbb{D}_0(\mathbf{v}) = \left(\nabla \mathbf{v} + \nabla \mathbf{v}^T - \frac{2}{3} \operatorname{div}_{\mathbf{x}} \mathbf{v} \mathbb{I} \right)$$

and let $\mathbf{g}: U \rightarrow \mathbb{R}^3$. The Dirichlet boundary value problem for the Lamé system is whether there exists a function $\mathbf{v}: U \rightarrow \mathbb{R}^3$ with zero trace on $\partial\Omega$ such that

$$\operatorname{div}_{\mathbf{x}} \mathbb{D}_0(\mathbf{v}) = \mathbf{g}. \quad (28)$$

Lemma 7.1. *Let $U \subseteq \mathbb{R}^3$, $\partial U \in \mathcal{C}^2$, $\mathbf{g} \in L^p(U, \mathbb{R}^3)$ and $p \in (1, \infty)$. Then there exists a unique $\mathbf{v} \in W^{2,p}(U, \mathbb{R}^3)$ with zero trace satisfying (28) almost everywhere in U and the operator $\mathbf{g} \mapsto \mathbf{v}: L^p(U; \mathbb{R}^3) \rightarrow W^{2,p}(U; \mathbb{R}^3)$ is continuous.*

Proof. We only show that the elliptic operator in (28) satisfies the Legendre-Hadamard conditions. As the operator has constant coefficients, the existence, uniqueness and regularity follows directly from the standard theory of elliptic systems (see for example [16]). Let us denote $A_{i,j}^{\alpha,\beta}$, where $\alpha, \beta, i, j \in \{1, 2, 3\}$ the coefficients of the elliptic system (28) (for the notation check [16]). Then

$$\sum_{\alpha,\beta,i,j=1}^3 A_{i,j}^{\alpha,\beta} \xi_\alpha \xi_\beta \eta^i \eta^j = \xi \otimes \eta : \left(\xi \otimes \eta + (\xi \otimes \eta)^T - \frac{2}{3} \xi \cdot \eta \mathbb{I} \right) = |\xi|^2 |\eta|^2 + \frac{1}{3} |\xi \cdot \eta|^2 \geq |\xi|^2 |\eta|^2.$$

□

Corollary 7.2. *Let $U \subseteq \mathbb{R}^3$, $\partial U \in \mathcal{C}^2$ and $p \in (1, \infty)$. Then there exists a continuous operator $\mathbb{G}: L^p(U, \mathbb{R}^3) \rightarrow W^{1,p}(U; \mathbb{R}^{3 \times 3}_{sym,0})$ such that*

$$\operatorname{div}_{\mathbf{x}}(\mathbb{G}[\mathbf{g}]) = \mathbf{g}.$$

7.2 Parabolic regularity

The standard regularity result for parabolic equations (see e. g. [1]) gives

$$W^{1,q}((0, T); L^q(U)) \cap L^q((0, T); W^{2,q}(U) \cap W_0^{1,q}(U)) \hookrightarrow \mathcal{C}([0, T]; W_0^{1,q}(U)) \hookrightarrow \mathcal{C}([0, T] \times \bar{U}) \quad (29)$$

whenever $q > 3$. Therefore we have:

Lemma 7.3. *Assume that $q \in (3, \infty)$. Let $\theta_0 \in W_0^{1,q}(U)$ and $\mathbf{u} \in L^\infty(Q; \mathbb{R}^3)$. Then exists a unique*

$$\theta \in W^{1,q}((0, T); L^q(U)) \cap L^q((0, T); W^{2,q}(U) \cap W_0^{1,q}(U))$$

which satisfies (2e) almost everywhere and $\theta(0) = \theta_0$. Moreover, the operator $u \mapsto \Theta[\mathbf{u}]$ is continuous from $L^\infty(Q)$ to $\mathcal{C}([0, T] \times \bar{U})$ and the comparison principle holds, i. e. for two solutions θ^1, θ^2 emanating from θ_0^1, θ_0^2 holds that

$$\text{if } \theta_0^1 \leq \theta_0^2 \text{ a. e. in } U \text{ then } \theta^1(t, \mathbf{x}) \leq \theta^2(t, \mathbf{x}) \text{ a. e. in } Q.$$

Moreover,

$$\|\theta\|_{W^{1,q}((0,T);L^q(U)) \cap L^q((0,T);W^{2,q}(U) \cap W_0^{1,q}(U))} \leq C(\|\theta_0\|_{W^{1,q}} + \|\mathbf{u}\|_{L^\infty}),$$

therefore given $\theta_0 \in W^{1,q}$, the solving operator

$$\mathbf{u} \mapsto \Theta[\mathbf{u}]$$

is continuous from $\mathcal{C}([0, T]; L_w^q(\Omega))$ to $\mathcal{C}([0, T] \times \bar{U})$.

7.3 Convergence in linear conservation laws

For the reader's convenience, we also recall the following standard weak compactness result for linear conservation laws.

Lemma 7.4. *Let $\{\mathbf{u}_{n,0}\}_{n \in \mathbb{N}}$ converges weakly-* in $L^\infty(U; \mathbb{R}^3)$ to \mathbf{u}_0 . Let $\{\mathbf{u}_n\}_{n \in \mathbb{N}}$ be a bounded sequence in $(L^\infty(Q; \mathbb{R}^3))$ and $\{\mathbb{V}_n\}_{n \in \mathbb{N}}$ be a bounded sequence in $(L^\infty(Q; \mathbb{R}_{0,sym}^{3 \times 3}))$ satisfying*

$$\partial_t \mathbf{u}_n + \operatorname{div}_{\mathbf{x}} \mathbb{V}_n = 0 \quad \text{in } \mathcal{D}'(Q; \mathbb{R}^3), \quad (30)$$

$$\operatorname{div}_{\mathbf{x}}(\mathbf{u}_n \chi_U) = 0 \quad \text{in } \mathcal{D}'(\mathbb{R}^3), \quad (31)$$

$$\mathbf{u}_n(0) = \mathbf{u}_{n,0}. \quad (32)$$

Then $\{\mathbf{u}_n\}_{n \in \mathbb{N}}$ is precompact in $\mathcal{C}([0, T]; L_w^p(U))$ for every $p \in [1, \infty)$. Moreover, if (\mathbf{u}, \mathbb{V}) is a limit of any weakly- convergent subsequence of $\{(\mathbf{u}_n, \mathbb{V}_n)\}_{n \in \mathbb{N}}$ then (\mathbf{u}, \mathbb{V}) satisfies (30), (31) and $\mathbf{u}(0, \cdot) = \mathbf{u}_0(\cdot)$.*

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