Post-print version of:

Publisher: **SAGE**

Journal paper: Journal of Strain Analysis for Engineering Design 2018, 53(4) 210-224

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Authors: M. Barsanti, M. Beghini, C. Santus, A. Benincasa, L. Bertelli

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DOI Link: https://doi.org/10.1177/0309324718760438

Integral method coefficients for the ring-core technique to evaluate non-uniform residual stresses

Journal Title

XX(X):1–20

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DOI: 10.1177/ToBeAssigned

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Michele Barsanti¹, Marco Beghini¹, Ciro Santus¹, Alessio Benincasa², Lorenzo Bertelli²

Abstract

The ring-core technique allows for the determination of non-uniform residual stresses from the surface up to relatively higher depths as compared to the hole-drilling technique. The integral method, which is usually applied to the hole-drilling, can also be used for elaborating the results of the ring-core test since these two experimental techniques share the axisymmetric geometry and the 0-45-90 degrees layout of the strain gage rosette. The aim of this paper is at providing accurate coefficients which can be used for evaluating the residual stress distribution by the ring-core integral method. The coefficients have been obtained by elaborating the results of a very refined plane harmonic axisymmetric finite element model and verified with an independent 3D model. The coefficients for small depth steps were initially provided, then the values for multiple integer step depths were also derived by manipulating the high resolution coefficient matrices, thus showing how the present results can be practically used for obtaining the residual stresses according to different depth sequences, even non-uniform. This analysis also allowed the evaluation of the eccentricity effect which turned out to be negligible due to the symmetry of the problem. An applicative example was reported in which the input of the experimentally measured relaxed strains were elaborated with different depth resolutions, and the obtained residual stress distributions compared.

Keywords

integral method coefficients, depth resolution, eccentricity sensitivity, FE modelling, ring-core.

Corresponding author:

Ciro Santus, University of Pisa, DICI dept. Largo Lucio Lazzarino 1, 56122 Pisa, Italy

Email: ciro.santus@ing.unipi.it

¹Dept. of Civil and Industrial Engineering (DICI), University of Pisa, Italy

²SINT Technology Srl, Florence, Italy

Introduction

The hole-drilling and the ring-core are semi-destructive mechanical techniques used for determining residual stresses at the surface and in the near surface regions, in components with a locally flat surface. Both techniques are based on axisymmetric material removal. The hole-drilling is a well established procedure defined by internationally accepted standards ^{1;2}. The ring-core was introduced more than 20 years ago ^{3–6}, however it was deeply investigated and developed only recently, especially in terms of sensitivity and uncertainty analysis ^{7–10}, and even applied at the microscale ^{11;12}. In the hole-drilling the material is removed at the centre of a rosette thus the relaxed strains are measured at the periphery of the hole, whereas in the ring-core the strains are measured in the central internal region, as shown in Figure 1. These two techniques can be considered complementary. The hole-drilling is more popular being dedicated to measure the residual stresses near the surface ^{13–18} (typically in the layer up to 1 mm, or slightly larger) while the ring-core technique, having a large groove diameter ¹⁹, is usually suitable for larger size components where the residual stresses at depths in the order of a few millimetres are of interest, such as rotor forging ²⁰ or thick welded plates ²¹.

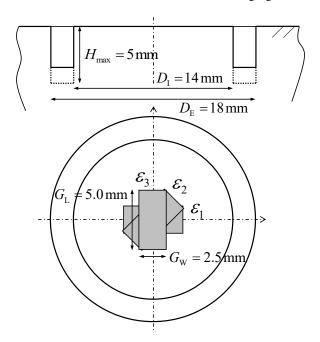


Figure 1. Ring-core technique, typical dimensions of the circular groove and strain gage grids.

Regarding the hole-drilling, the calculation of the residual stresses, after having produced a hole in incremental depths and the relieved strains recorded, can be performed with the standard ASTM E837 – 13a¹ that applies the *integral method*. The same calculation procedure can be applied to elaborate the relaxed strains produced by the ring-core ^{8;10;22}, since the axial-symmetry of the problem and the grid layout according to the 0-45-90 degrees scheme are the same. However, other numerical techniques for the residual stress determination have been proposed, such as the incremental strain method ^{21;23;24} or the influence function analytical technique as proposed by Beghini et al. ^{13;14} for the hole-drilling.

This paper presents an accurate Finite Element (FE) analysis, based on the plane harmonic axisymmetric elements, by which the coefficients for applying the integral method to the ring-core were obtained. It is worth noting that the use of a plane model with harmonic elements for solving this problem does not imply any approximation as the element type captures exactly the angular dependence of the solution. This FE approach is highly recommended for a parametric analysis of this type as dramatically reduces the number of nodes and elements if compared to a 3D model with equivalent level of accuracy. Recently, Salvati et al. 12 used an axisymmetric model to interpret the equibiaxial component in a micro ring-core measurement. However, as shown by Barsanti et al. 25 for the hole-drilling method, the axisymmetric elements with the harmonic feature allows to model the shear components too and consequently any in-plane stress condition. In other words, the (simple) axisymmetric element type allows the determination of the equibiaxial matrix $\bar{\bf a}$, while with the harmonic axisymmetric elements both matrices $\bar{\bf a}$ and $\bar{\bf b}$ can be obtained.

The ring-core geometrical parameters are shown in Figure 1 where the grid dimensions reproduce the HBM RY51 rosette. The aim of this paper is to obtain and provide the coefficients for a sequence of small depth steps $(\Delta H = 0.1 \text{ mm})$ in order to give the possibility to derive, with simple calculations, the coefficients for larger steps too. The consistency of the results was validated with a 3D FE model completely independent from the reference axisymmetric model used for the calculation of the proposed coefficients. Finally, an applicative example illustrates the practical use of the provided coefficients.

Outline of the integral method

For a plane problem under a uniform residual stress field and according to the hypothesis that the grid centre belongs to the cylindrical groove axis, the relationship relating the measured relaxed strain ε_r to the principal (residual) stresses, as introduced by Schaier^{26;27}, is:

$$\varepsilon_{\rm r}(\vartheta) = A(\sigma_{\rm max} + \sigma_{\rm min}) + B(\sigma_{\rm max} - \sigma_{\rm min})\cos(2\vartheta) \tag{1}$$

where σ_{max} and σ_{min} are the maximum and minimum residual normal stresses, respectively, ϑ is the angle between the principal direction of σ_{max} and the axis of the grid, and A, B are two constants depending on the geometry and on the elastic material properties E and V. From equation (1), the following matrix relationship is obtained:

$$\begin{bmatrix} (A+B) & (A-B) & 0 \\ A & A & 2B \\ (A-B) & (A+B) & 0 \end{bmatrix} \begin{bmatrix} \sigma_1 \\ \sigma_3 \\ \tau_{13} \end{bmatrix} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \end{bmatrix}$$
 (2)

in which the subscripts 1, 2, 3 are related to the three grid directions according to the 0-45-90 degrees scheme and then 1 and 3 are two orthogonal directions which can be taken as the local reference frame, Figure 1. As the directions 1 and 3 are in general not coincident with the residual stress principal directions, the shear stress component τ_{13} can be nonzero. The form of equation 2 suggests that three scalar relationships can be written in a decoupled form, after introducing three strains and three stresses new variables which are linear combinations of the reference frame strain and stress components. The definitions of these variables

can be retrieved in the standard ASTM E837, and the following quantities are needed to be introduced for the measured strains:

$$p = \frac{\varepsilon_3 + \varepsilon_1}{2} \qquad q = \frac{\varepsilon_3 - \varepsilon_1}{2} \qquad t = \frac{2\varepsilon_2 - (\varepsilon_3 + \varepsilon_1)}{2} = \varepsilon_2 - p \tag{3}$$

in which p is the equibiaxial and q and t are the shear components, and the sign of t is discussed below. The residual stresses can be similarly combined, thus defining an equibiaxial P and two shear components Q, T:

$$P = \frac{\sigma_3 + \sigma_1}{2} \qquad Q = \frac{\sigma_3 - \sigma_1}{2} \qquad T = \tau_{13} \tag{4}$$

After defining the combined strains p,q,t and combined stresses P,Q,T, equation 2 can be rewritten as three decoupled relations:

$$\begin{bmatrix} 2A & 0 & 0 \\ 0 & 2B & 0 \\ 0 & 0 & 2B \end{bmatrix} \begin{bmatrix} P \\ Q \\ T \end{bmatrix} = \begin{bmatrix} p \\ q \\ t \end{bmatrix}$$
 (5)

By introducing the material Young's modulus and the Poisson's ratio, the relationship available in the ASTM standard ¹ can be obtained:

$$-\frac{1}{E} \begin{bmatrix} a(1+v) & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & b \end{bmatrix} \begin{bmatrix} P \\ Q \\ T \end{bmatrix} = \begin{bmatrix} p \\ q \\ t \end{bmatrix}$$
 (6)

where the dimensionless positive coefficients a and b only depend on the ratios between the groove diameters and the grid dimensions. In principle, a and b are unaffected by the Poisson's ratio v only for a plane stress model, i.e. for a through-thickness hole geometry, while this is not true in a general three-dimensional problem. The Poisson's ratio dependence in equation (6) is therefore only approximate. In fact, the coefficients are functions of the Poisson's ratio, a(v) and b(v), however in the range 0.25 < v < 0.35 the differences are in the order of a few percent, thus it is usually assumed: a = a(0.3) and b = b(0.3).

When the residual stresses vary along the depth direction, the same approach can be followed but a vectorial form is required. If the circular groove is performed in n steps, usually each with the same depth ΔH , the scalars p,q,t and P,Q,T are replaced by n-dimensional vectors:

$$\mathbf{p} = (p^{(1)}, p^{(2)}, \dots, p^{(n)})^{\mathrm{T}}$$

$$\mathbf{q} = (q^{(1)}, q^{(2)}, \dots, q^{(n)})^{\mathrm{T}}$$

$$\mathbf{t} = (t^{(1)}, t^{(2)}, \dots, t^{(n)})^{\mathrm{T}}$$
(7)

and

$$\mathbf{P} = (P^{(1)}, P^{(2)}, \dots, P^{(n)})^{\mathrm{T}}
\mathbf{Q} = (Q^{(1)}, Q^{(2)}, \dots, Q^{(n)})^{\mathrm{T}}
\mathbf{T} = (T^{(1)}, T^{(2)}, \dots, T^{(n)})^{\mathrm{T}}$$
(8)

which represent the combined strains and stresses, respectively, at each *i*-th depth step: i = 1, ..., n. The general $p^{(i)}$ term represents the combined relaxed strain (equation 3) measured when the groove depth is $i \times \Delta H$, while $P^{(i)}$ represents the combined stress that is assumed to be uniform from the depth $(i-1) \times \Delta H$ to $i \times \Delta H$. Similar

definitions are valid for $q^{(i)}, t^{(i)}$ and shear stresses $Q^{(i)}, T^{(i)}$. Consequently, the scalars a and b in equation 6 have to be replaced by $n \times n$ lower triangular matrices $\overline{\bf a}$ and $\overline{\bf b}$. By combining the definitions and the relations introduced above, the matrix form of the integral method is:

$$-\frac{1+\nu}{E}\overline{\mathbf{a}}\,\mathbf{P} = \mathbf{p} \quad -\frac{1}{E}\overline{\mathbf{b}}\,\mathbf{Q} = \mathbf{q} \quad -\frac{1}{E}\overline{\mathbf{b}}\,\mathbf{T} = \mathbf{t}$$
 (9)

When the matrices $\overline{\bf a}$, $\overline{\bf b}$ are available, the residual stress distribution of any experimental case can be deduced from the measured strains by solving the linear systems 9. The elements a_{ij} , b_{ij} of the just defined calibration matrices for the ring-core are calculated and provided in the next section.

A discussion about the sign of the combined strain t has been already provided by Barsanti et al. ²⁵ for the hole-drilling, and it is reconsidered here for the ring-core as it can be a source of formal errors in the elaboration. After introducing the orientations of the directions 1 and 3, if the second grid is along the bisector of a quadrant where the coordinates have same sign (1st or 3rd quadrant), Figure 2, and the residual shear τ_{13} is positive, a negative (contraction) strain is measured by the second grid after introducing the groove. Assuming no equibiaxial strain component, the combined strain t is equal to ε_2 , equation (3), thus it is negative too. According to equation (9), the combined stress T, that is equal to the shear stress τ_{13} , and the combined strain t have opposite sign, thus confirming the accurate definition of the last of equation (3). On the contrary, if the second grid strain and the shear stress have the same sign, and then the opposite definition of the last of equation (3) is required, in agreement with the ASTM standard. However, the scheme with the second grid along the bisector of the 1st or the 3rd quadrant is preferred in the present work, thus the sign of the last of equations 3 is confirmed.

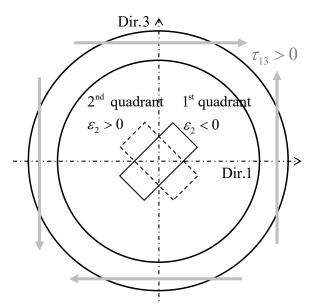


Figure 2. Scheme for deducing the sign of the second grid strain with respect to its angular position.

Axisymmetric harmonic FE model

A refined plane FE model was generated with 5 nested regions having different nodal density. The element size was reduced by a factor of two when passing from one region to the internal one, in order to have the innermost zone, where the material removal is simulated, with 0.1 mm square-shaped elements, and this element edge was 70 times smaller than the internal radius of the groove, Figure 3(a). The FE model height and width were chosen much larger than the groove internal radius, Figure 3(a), to reproduce the condition of a virtually semi-infinite body. The far field boundary conditions influenced the simulated displacements within the groove, and the calculated coefficients, with an estimated effect in the order of 10^{-3} . Approximately 126000 axisymmetric harmonic elements were used, and the element type was ANSYS® Plane25.

In agreement with equation (9), the general state of residual stress was represented by superimposing an equibiaxial stress and two pure shears. The equibiaxial and the pure shear stress components were applied as two independent load steps, Figure 3(b). Only a single shear stress component was actually required to be modelled, as the matrix to be determined is just $\overline{\mathbf{b}}$ for both shears. The equibiaxial load was modelled with a zero order harmonic analysis, i.e. a radial pressure constant in the angular direction, applied on the cylindrical surfaces of the groove. Whereas, the shear load was obtained by superimposing a normal and a tangential traction distributions, both as second order harmonics with 2ϑ variation, relatively shifted by an angle of 45° , Figure 3(b).

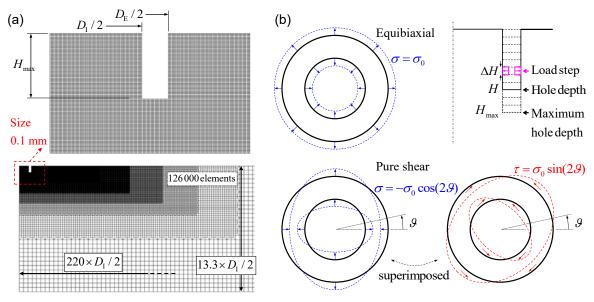


Figure 3. (a) Harmonic plane axisymmetric FE model. (b) Scheme of the basis loading conditions applied to the FE model.

Similarly to the simulations for the hole-drilling technique ²⁵, the FE model is residual stress free, the material at the groove is preliminarily removed and the proper tractions are applied to both the inner and outer cylindrical surfaces. Actually, the physical problem is the opposite. Residual stresses are pre-existing, so the material removal relaxes to zero the tractions at the surfaces of the groove. In order to take into account this

alternative way of modelling, a minus sign has to be introduced in the relation between stresses and strains. In fact, by applying the traction at the free surfaces, the opposite strain is obtained with respect to the theoretical removal of the material.

The same resolution of the model geometry was applied to the integral method load step, thus $\Delta H = 0.1$ mm. For example, when the groove had depth H = 4.2 mm, 42 load positions were analysed, the first with the load from 0.0 to 0.1 mm, then from 0.1 to 0.2 mm, and so on. Since the maximum considered groove depth was $H_{\text{max}} = 5.0$ mm, the total number of single simulations (equibiaxial and pure shear) was: $2 \times (50 \times (50 + 1)/2) = 2550$.

Coefficients for the integral method

Coefficient derivation from the displacement fields

The coefficients of the matrices $\bar{\bf a}, \bar{\bf b}$ can be derived by imposing a single unitary traction at each depth position, as described in the previous section, and calculating with the FE results the combined strains virtually measured by the rosette. For instance, to calculate the a_{ij} element, the stress components $P^{(j)}=1$, $P^{(k,k\neq j)}=0$ were imposed, and the strain component p_i calculated. The simulated strain measured by the grids was evaluated by computing the average displacement (in the grid direction) at the extreme edge segments, and dividing the averaged displacement differences by the grid length, without retrieving any displacement information at the intermediate positions of the grids. With reference to Figure 4, the whole procedure is summarized in detail hereafter:

- 1. Define the vertices A, B, C, D of each grid and a large enough number of integration points (about 100) on the sides AB and CD, both in cartesian and polar coordinates;
- 2. Introduce the components of the unit vectors transverse $\hat{\mathbf{t}}$ and normal $\hat{\mathbf{n}}$ (external to the grid) to the segments AB and CD, at each integration point;
- 3. Calculate the displacements along the radial and the tangential directions by local linear interpolation of the FE element results, at each integration point on sides *AB* and *CD*;
- 4. Evaluate the displacement components along the transverse and normal directions at the integration points;
- 5. Being the grid mainly sensitive to the extensional strain in the normal direction (transverse sensitivity, though not zero, is quite small and usually neglected) only the displacements along the $\hat{\bf n}$ direction at the integration points were considered. However, $\hat{\bf t}$ direction displacements could also be taken into account on the lateral sides BC and AD if the transversal strain sensitivity were significant.
- 6. Average the normal displacements on the active sides AB and CD.
- 7. Compute the difference between AB and CD averaged displacements and divide it by the grid length to obtain the simulated measured strains ε_1 , ε_3 .
- 8. Evaluate ε_1 , ε_3 to calculate the combined strains p and q, while ε_2 is unnecessary since the shear applied according to the load scheme of Figure 3 (b) is not along the 45 degrees direction.
- 9. Deduce the matrix coefficients by multiplying p_i by -E/(1+v) for a_{ij} , and q_i by -E for b_{ij} .

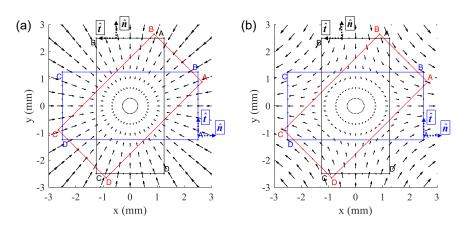


Figure 4. Displacement fields on the strain gage areas: (a) equibiaxial, and (b) pure shear load cases.

This calculation was repeated for all the 2550 simulated groove depths, load depths and load type combinations to obtain the coefficients a_{ij}, b_{ij} , with $i \ge j$ (coefficients with i < j are zero). The $\overline{\mathbf{a}}, \overline{\mathbf{b}}$ matrices obtained for the Poisson's ratio v = 0.3 are reported in Tables 1 and 2, split in blocks to fit the paper page, and also electronically available on the online Appendix (http://sdj.sagepub.com).

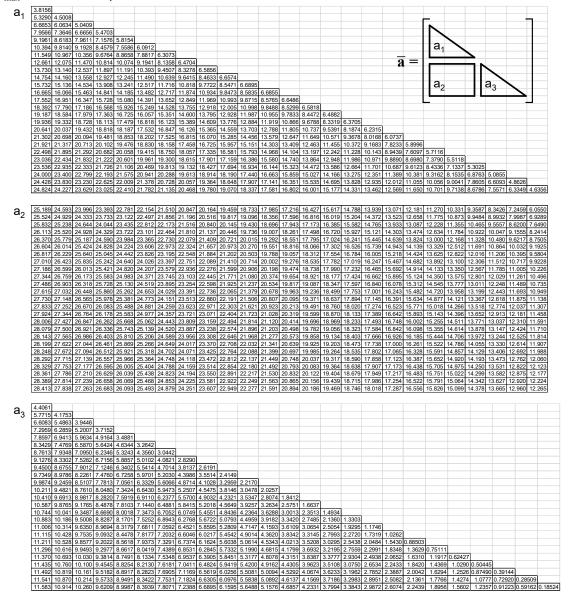
Integer multiple step coefficient determination

Lower resolution coefficients can be derived for any m multiple depth step of $\Delta H = 0.1$ mm, for instance m = 2, 5, 10 in order to be applied to measurements with higher depth steps. By implementing the superposition principle, the lower resolution coefficients can be obtained as simple summations of the original coefficients: one every m rows must be taken into account, corresponding to $m \times 0.1$ mm groove depth. For each of these rows, elements must be collected in blocks of size m (starting from the leftmost one), and all the elements in the same block must be summed. At the end of this procedure, two smaller lower triangular matrices of size $(50/m) \times (50/m)$ are obtained.

For example, in order to obtain a_{ij} and b_{ij} for 1 mm depth step (m = 10), only the row indices 10, 20, 30, 40, 50 must be considered. In the row with i = 10 of the matrix $\bar{\bf a}$, a single block of 10 values is built, whose sum is 0.1145. In the row with i = 20 two blocks of 10 values are built, whose sums are 0.1966 and 0.1139, and so on up to the row with i = 50 in which 5 values are obtained by summing the elements contained in each of the 5 blocks. The same procedure is to be repeated for the matrix $\bar{\bf b}$.

Non-uniform steps, for example as initially proposed by Zuccarello⁶, and recently re-proposed by Menda et al. ^{8;9} and Zuccarello et al. ¹⁰, can be also obtained from the large matrices introduced above. However, the depths need to be approximated with the 0.1 mm resolution. At the beginning, the depth 0.6 mm is equivalent to 6 steps of the high resolution matrices, while 1.05 mm needs to be approximated as 1.1 mm, corresponding to 11 steps. According to this scheme, as graphically shown in Figure 5, the coefficient $a_{11}(b_{11})$ is the sum of all the six elements of the sixth row, then the coefficient $a_{21}(b_{21})$ is the sum of the first six elements of the eleventh row, $a_{22}(b_{22})$ is the sum of the coefficients from the seventh to the eleventh elements, and so on.

Table 1. a_{ij} coefficients ($\times 10^3$) for $D_{\rm I}=14$ mm, $D_{\rm E}=18$ mm, $G_{\rm L}=5.0$ mm, $G_{\rm W}=2.5$ mm, maximum depth $H_{\rm max}=5.0$ mm and depth resolution $\Delta H=0.1$ mm.



Validation of the calibration coefficients

A 3D model was implemented for validating the plane FE analysis and the proposed calculation procedure. Though coarser than the axisymmetric model, Figure 6, the load application and the relaxed strain calculation were completely different in this 3D analysis, thus it was unlikely to replicate the same error on both models. The successful comparison, even if verified for a few residual stress cases, gave high confidence about the proper application of the integral method and then the correctness of the coefficients. In principle, the same

Table 2. b_{ij} coefficients ($\times 10^3$) for $D_{\rm I}=14$ mm, $D_{\rm E}=18$ mm, $G_{\rm L}=5.0$ mm, $G_{\rm W}=2.5$ mm, maximum depth $H_{\rm max}=5.0$ mm and depth resolution $\Delta H=0.1$ mm.

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b_1	6.7987	5.9027																		_					_
			6.4355	i																					
		8.8915	8.1143	6.8750																					
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		22.499			19.807	18.901				14.865	13.675			8.6285											
		23.830			21.074	20.155				16.154	15.012				8.6157										
		25.148			22.327			19.464		17.398	16.288	15.109			10.847										
		26.453 27.742			23.566 24.788	22.614		20.666 21.846	19.654 20.828		17.514 18.699	16.369 17.574			13.829	10.807	8.5104 10.735	8.4210							
	30.080	29.013			25.991	25.003			21.978	20.928	19.849	18.736	17.581		15.108		12.274		8.3094						
	31.356	30.264			27.175	26.168				22.047	20.968	19.859		17.537	16.309					8.1771	i				
	32.610	31.494			28.337	27.311					22.055			18.647	17.444	16.196	14.891		12.003	10.349	8.0259				
		32.700			29.476	28.431		26.336	25.277		23.114	22.004	20.872	19.714	18.527	17.305	16.042	14.724	13.338	11.824	10.170	7.8575			
	35.046				30.592	29.527				25.241	24.143			20.741	19.564		17.123	15.849		13.132			7.6736		
		35.038			31.682	30.597					25.144			21.733		19.366	18.148		15.620	14.290	12.899	11.390	9.7507	7.4757	
	37.378	36.167	34.999	33.862	32.745	31.641	30.543	29.444	28.343	27.234	26.116	24.987	23.845	22.689	21.519	20.331	19.125	17.897	16.643	15.358	14.028	12.640	11.139	9.5140	7.2656
b_2				34.919			31.542	30.427	29.310	28.189	27.060	25.921	24.773	23.613	22.441	21.256	20.057	18.842	17.608		15.065		12.359		9.2620
~2		38.338			34.790			31.382		29.115			25.670				20.950		18.521	17.285		14.746	13.426	12.057	10.583
	40.659	39.379			35.769	34.608					28.861			25.366				20.602	19.390	18.167	16.930		14.402	13.093	11.737
	41.691 42.692	40.390	39.136 40.095		36.719 37.639	35.540 36.442		33.207			29.718 30.546		27.375 28.183	26.196	25.805		22.626	22.211	20.217	19.003 19.798	17.781 18.585	16.549 17.368	15.303 16.142	14.037	12.741
			41.023		38.530	37.314					31.346			27.767		25.369	24.167	22.964		20.555	19.349		16.930	15.715	14.491
			41.919		39.390	38.157			34.522		32.118	30.915		28.508	27.303		24.891	23.685	22.480	21.276	20.074	18.872	17.672	16.472	15.269
			42.785		40.219			36.510			32.860								23.168	21.964		19.566	18.373	17.183	15.995
	46.375	44.972	43.620		41.019			37.263			33.575				28.685		26.249					20.225	19.037		16.676
			44.423		41.789	40.507			36.741		34.262	33.027		30.563			26.886	25.667	24.454	23.246	22.045		19.665		17.318
			45.196		42.528	41.232					34.922			31.194		28.724	27.495	26.271	25.054	23.843	22.641	21.447	20.262	19.087	17.922
			45.938		43.239			39.352		36.814					30.553			26.849	25.627		23.208		20.828		18.494
			46.650 47.333		43.921 44.574	42.595		39.992 40.606			36.160 36.740				31.123	29.875 30.413	28.634 29.166	27.400	26.173 26.694	24.955 25.473	23.748 24.262		21.366 21.876		19.034 19.545
			47.987	46.577	45.199			41.193		38.586	37.295			33.456			29.673	28 427	27.191	25.965	24.751		22.361		20.029
			48.612		45.797	44.431		41.754			37.824				32.684		30.156	28.905		26.434	25.216		22.821		20.488
			49.210		46.368		43.632	42.290	40.960	39.641	38.330				33.158			29.361			25.659		23.258		20.922
			49.781		46.913	45.523		42.801			38.812				33.609		31.056	29.794			26.079		23.673	22.495	21.334
	53.399	51.833			47.433	46.032					39.272	37.951		35.335	34.038	32.751	31.473	30.206	28.950	27.707	26.478	25.264	24.066	22.886	21.723
	53.944	52.365 52.871			47.929	46.516			42.394		39.709		37.061	35.749	34.447	33.153	31.870	30.598	29.337	28.090	26.857	25.640	24.439	23.256	22.092
	54.462	53.352			48.400 48.849	46.977 47.416			42.826 43.238		40.125 40.520			36.144 36.519	34.835 35.204	33.536	32.247	30.970	29.705 30.054	28.454 28.798	27.558	26.334	25.128		22.771
			52.255		49.275	47.833		45.013			40.896			36.874	35.554			31.658		29.125		26.654	25.445		23.084
	55.872				49.680	48.229		45.392			41.252			37.212	35.886		33.266	31.975		29.434	28.187	26.957	25.745		23.379
				51.555																					23.659
h	7.0449																								
b_3	8.9966	6.8150																							
		8.7196																							
			8.4330																						
	12.373	11.054			7.8374	E 0220	-																		
	14.060	12.840			8.9720			i																	
	14.807	13.616			9.9512			5.3216	i																
	15.503	14.333			10.790			6.9116	5.0651																
	16.155	14.999	13.848	12.698	11.544	10.377	9.1872	7.9288	6.5998																
	16.768	15.623			12.229	11.100			7.5779																
	17.344	16.207			12.858	11.755			8.4159																
	17.888 18.402	16.757	15.638 16.161		13.440 13.981	12.357	11.280 11.854	10.206	9.1264	8.0312	6.8794 7.6487			3.8078											
	18.402	17.762			14.486	13.427			10.331		8.2979	6.5338 7.2697		5.0668	3.5664										
	19.346	18.222			14.959	13.908			10.852	9.8595	8.8746	7.8890			4.7715	3 3296									
	19.780		17.553		15.402						9.3925				5.5236		3.0980								
		19.068		16.881	15.819	14.777	13.756	12.755	11.774		9.8640	8.9311		7.0877	6.1627		4.1977	2.8717							
	20.580	19.456	18.353	17.271	16.210	15.172	14.155	13.159	12.185	11.231	10.296	9.3787	8.4762	7.5845	6.6969	5.8064	4.8794	3.9201	2.6514						
	20.947	19.823	18.719		16.579	15.542		13.537	12.568	11.621	10.695	9.7886	8.9009	8.0286	7.1685	6.3136	5.4575	4.5678	3.6493	2.4370					
	21.295	20.169			16.926	15.890		13.890		11.983	11.064	10.166		8.4312	7.5895	6.7609		5.1166	4.2639	3.3856	2.2289	0.0075			
	21.623	20.497			17.252 17.560	16.218 16.526		14.221 14.531	13.259 13.571		11.406	10.515		8.7987 9.1364	7.9705	7.1594	6.3621	5.5723	4.7841 5.2151	3.9679 4.4605	3.1294	2.0273	1.8323		
		21.099			17.850	16.816					12.023			9.4481	8.6370		7.0794	6.3290	5.5936	4.4605	4.1459		2.6399	1.6439	
		21.375			18.123					13.207	12.301			9.7366		8.1490	7.3891			5.2246		3.8407	3.1306	2.4070	1.4623

level of accuracy would have been obtained with a 3D model just by replicating the discretization in the section plane and then introducing a large number of divisions, for example 100, along the angular direction. However, such a higher number of elements would require huge computing performances, basically without any significant advantage.

In the 3D analyses, the external load was applied as far field along the two principal directions x and y and the material removal simulated with no traction applied to the groove surfaces. The relaxed strains were then

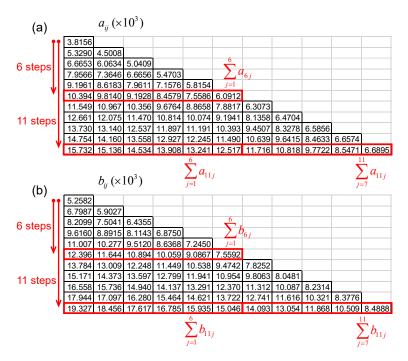


Figure 5. Calculation scheme with non-uniform depths for deriving the lower resolution coefficients of matrices a_{ij} (a) and b_{ij} (b).

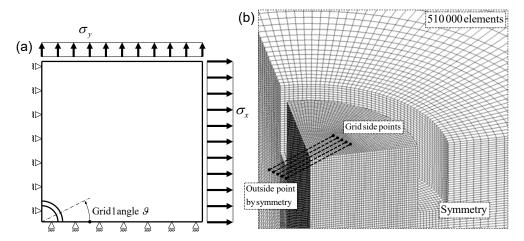


Figure 6. FE model for validation, (a) load scheme, (b) 3D mesh grid side points.

obtained as the difference between the final grooved geometry and the load uniformly applied before the material removal, which could be computed with the Hooke's law. The problem features two symmetry planes which were considered to reduce the modelled volume by a factor of 4. The grid side points were simulated as any angle with respect to the first principal direction x and those points outside the quarter volume were computed by exploiting the symmetries of the problem. The matrices for the integral method according to 0.5

mm resolution of the 3D model, were obtained by applying the procedure introduced in the previous section, and reported in Table 3. Equations (9) were inverted to obtain the stresses, assuming as input the strains of the 3D FE analysis which was treated as a virtual residual stress experiment.

Table 3. Calibration coefficients with resolution $\Delta H = 0.5 \text{ mm}$ for the validation analysis.

							•		
a_{ij} coe	fficients	$(\times 10^{3})$							
38.75	0	0	0	0	0	0	0	0	0
67.64	46.89	0	0	0	0	0	0	0	0
89.84	72.73	47.66	0	0	0	0	0	0	0
106.4	90.14	70.30	43.64	0	0	0	0	0	0
118.1	102.2	83.90	62.71	36.92	0	0	0	0	0
125.9	110.3	92.68	73.15	52.35	29.17	0	0	0	0
130.8	115.4	98.21	79.45	60.16	41.14	21.54	0	0	0
133.8	118.5	101.5	83.20	64.60	46.80	30.43	14.71	0	0
135.4	120.3	103.4	85.32	67.07	49.82	34.35	20.97	9.004	0
136.3	121.2	104.4	86.43	68.37	51.38	36.29	23.52	13.12	4.485
b_{ij} coe	fficients	$(\times 10^3)$							
46.68	0	0	0	0	0	0	0	0	0
81.41	56.78	0	0	0	0	0	0	0	0
114.6	90.99	60.67	0	0	0	0	0	0	0
146.2	120.6	93.39	59.51	0	0	0	0	0	0
175.2	147.2	119.2	89.35	54.59	0	0	0	0	0
200.7	170.4	140.9	111.0	80.65	47.29	0	0	0	0
222.3	190.0	159.0	128.4	98.37	69.24	38.90	0	0	0
240.1	206.0	173.7	142.2	111.9	83.35	56.81	30.39	0	0
254.4	218.8	185.3	153.0	122.3	93.71	67.79	44.58	22.43	0
265.7	228.8	194.4	161.4	130.2	101.5	75.61	52.96	33.34	15.37

The calculated stress components were finally compared with the stresses imposed to the 3D model, after applying a tensor rotation to obtain the components according to the 1,3 grid rosette frame. Indeed, a misalignment angle was introduced between the principal stress directions and the rosette frame to have a nonzero shear stress τ_{13} which also allowed to verify the sign definition of the strain component t (equation 3). Five load and angle combinations were considered and the average stress over the depth of 5 mm of each component was compared to the reference value, then the differences were evaluated. This comparison is shown in Table 4 in which differences not larger than 1% are shown, and in Figure 7 where the three stress components of the last case of Table 4 are plotted. The back-calculated stress distributions resulted quite uniform with just small variations at the extremes where the method is more sensitive to the disturbance, and the slight different results of the two FE models produced a detectable effect. It is worth noting that these differences are mainly to be imputed to the coarseness of the 3D analysis, as the plane axisymmetric model features a finer mesh and an exact angular dependence.

Table 4. Validation cases with different combinations of loads and rosette angles, and obtained small average stress differences.

σ_{x} , MPa	σ_y , MPa	σ_y/σ_x	Grid 1 ϑ	σ_1 diff.	σ_3 diff.	τ_{13} diff.
100	0	0.0	0°	0.1%	_	_
100	100	1.0	0°	-0.2%	-0.2%	_
100	-100	-1.0	0°	0.3%	0.3%	_
75	-30	-0.4	-45°	-0.2%	-0.2%	0.3%
75	-30	-0.4	20°	0.2%	1.0%	0.3%

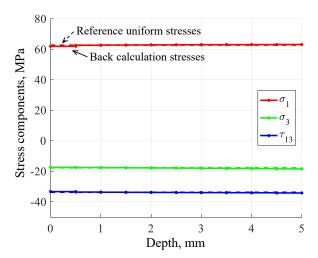


Figure 7. Comparison between the imposed and the back-calculated stresses of a validation case.

Sensitivity to eccentricity

The eccentricity between the hole and the rosette is an important issue in the hole-drilling method. The generalization of the integral method proposed by Barsanti et al. 25 , for taking into account of the eccentricity in the hole-drilling, was adapted to the ring-core too. According to that general approach, the p,q,t and P,Q,T decomposition can be no more applied as the axisymmetry of the problem is lost. A more general (still linear) relationship between all the components of stress and strain is consequently introduced:

$$-\frac{1}{F}\overline{\mathbf{A}}\mathbf{S} = \mathbf{e} \tag{10}$$

In equation (10), $\mathbf{S} = (\sigma_1^{(1)}, \sigma_3^{(1)}, \tau_{13}^{(1)}, \dots, \sigma_1^{(n)}, \sigma_3^{(n)}, \tau_{13}^{(n)})^T$ is the vector collecting all the components of residual stresses in blocks of three elements (one block for each drilling depth) and $\mathbf{e} = (\varepsilon_1^{(1)}, \varepsilon_2^{(1)}, \varepsilon_3^{(1)}, \dots, \varepsilon_1^{(n)}, \varepsilon_2^{(n)}, \varepsilon_3^{(n)})^T$ is the vector collecting the relaxed strains, again in blocks of three

elements. The lower triangular 3×3 block matrix \overline{A} is defined in equation (11):

$$\overline{\mathbf{A}} = \begin{bmatrix} A_{11}^{(11)} & A_{12}^{(11)} & A_{13}^{(11)} & 0 & 0 & 0 & 0 & 0 \\ A_{21}^{(11)} & A_{22}^{(11)} & A_{23}^{(11)} & 0 & 0 & 0 & 0 & 0 & 0 \\ A_{31}^{(11)} & A_{32}^{(11)} & A_{33}^{(11)} & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline A_{31}^{(21)} & A_{32}^{(21)} & A_{33}^{(21)} & 0 & 0 & 0 & 0 & 0 & 0 \\ \hline A_{11}^{(21)} & A_{12}^{(21)} & A_{13}^{(21)} & A_{11}^{(21)} & A_{12}^{(22)} & A_{13}^{(22)} & 0 & 0 & 0 \\ A_{21}^{(21)} & A_{22}^{(21)} & A_{23}^{(21)} & A_{21}^{(21)} & A_{22}^{(22)} & A_{23}^{(22)} & 0 & 0 & 0 \\ A_{31}^{(21)} & A_{22}^{(21)} & A_{23}^{(21)} & A_{31}^{(21)} & A_{32}^{(22)} & A_{33}^{(22)} & 0 & 0 & 0 \\ \hline A_{11}^{(31)} & A_{12}^{(31)} & A_{13}^{(31)} & A_{11}^{(32)} & A_{12}^{(32)} & A_{23}^{(32)} & A_{21}^{(32)} & A_{23}^{(32)} & A_{23}^{(33)} & A_{13}^{(33)} & A_{13}^{(33)} \\ A_{21}^{(31)} & A_{22}^{(31)} & A_{23}^{(31)} & A_{31}^{(31)} & A_{32}^{(32)} & A_{23}^{(32)} & A_{23}^{(32)} & A_{23}^{(33)} & A_{23}^{(33)} & A_{31}^{(33)} & A_{32}^{(33)} & A_{33}^{(33)} \\ A_{31}^{(31)} & A_{32}^{(31)} & A_{33}^{(31)} & A_{31}^{(32)} & A_{32}^{(32)} & A_{33}^{(32)} & A_{33}^{(33)} & A_{33}^{(33)} & A_{33}^{(33)} \\ A_{31}^{(31)} & A_{32}^{(31)} & A_{33}^{(31)} & A_{31}^{(32)} & A_{32}^{(32)} & A_{33}^{(32)} & A_{33}^{(33)} & A_{33}^{(33)} & A_{33}^{(33)} \\ A_{31}^{(31)} & A_{32}^{(31)} & A_{33}^{(31)} & A_{32}^{(32)} & A_{33}^{(32)} & A_{33}^{(32)} & A_{33}^{(33)} & A_{33}^{(33)} & A_{33}^{(33)} & A_{33}^{(33)} \\ A_{31}^{(31)} & A_{32}^{(31)} & A_{33}^{(31)} & A_{32}^{(32)} & A_{33}^{(32)} & A_{33}^{(33)} & A_{33}^{(33)} & A_{33}^{(33)} & A_{33}^{(33)} \\ A_{31}^{(31)} & A_{32}^{(31)} & A_{33}^{(31)} & A_{32}^{(32)} & A_{33}^{(32)} & A_{33}^{(33)} & A_{33}^{(33)} & A_{33}^{(33)} & A_{33}^{(33)} \\ A_{31}^{(31)} & A_{32}^{(32)} & A_{33}^{(33)} & A_{33}^{(32)} & A_{33}^{(32)} & A_{33}^{(33)} & A_{33}^{(3$$

The elements $A_{hk}^{(ij)}$ have indices h, k = 1, ..., 3, i = 1, ..., n and j = 1, ..., i, where n is the number of drilling steps. Each coefficient of this matrix depends on the eccentricity components e_1 and e_3 defined in the frame of the grid with axes in the directions 1 and 3 as shown in Figure 8. A power series expansion can be used to represent the dependence of these coefficients to the eccentricity, as shown in equation (12):

$$A_{hk}^{(ij)} = A_{0,hk}^{(ij)} + \frac{\partial A_{hk}^{(ij)}}{\partial e_1} e_1 + \frac{\partial A_{hk}^{(ij)}}{\partial e_3} e_3 + \frac{1}{2} \frac{\partial^2 A_{hk}^{(ij)}}{\partial e_1^2} e_1^2 + \frac{1}{2} \frac{\partial^2 A_{hk}^{(ij)}}{\partial e_3^2} e_3^2 + \frac{\partial^2 A_{hk}^{(ij)}}{\partial e_1 \partial e_3} e_1 e_3 + \dots$$
 (12)

If the eccentricity is small, as it is expected in a correctly applied procedure, only the constant and the linear terms of these expansions are sufficient to approximate the effect. For the hole-drilling, both the two first order derivatives are nonzero, while these terms are zero for the ring core. The physical reason of this result is the symmetry property of the geometry. As the grids are located at the centre, a displacement of the groove either parallel or orthogonal with respect to the grid direction, produces a higher sensitivity at one side and a lower sensitivity at the opposite side, as schematically shown in Figure 8, thus inducing a compensating effect. In fact, a displacement of the grid along a direction produces the same layout as the opposite direction plus a rotation of 180 degrees, which this latter is equivalent from the stress point of view. On the contrary for the hole-drilling technique, a first order net effect results unless special compensating grids are used, as investigated by Beghini et al. ²⁸ and used by Iurea et al. ²⁹, featuring an opposite grid, connected in series, for each of the three directions.

Numerical evaluation of the elements $A_{hk}^{(ij)}$ for different eccentricities performed with the proposed model, numerically confirmed that the ring-core method does not experience sensitivity to eccentricity at the first order. Two examples of this analysis are reported in Figure 9 in which it is evident that the tangent plane of the functions $A_{hk}^{(ij)}(e_1,e_3)$ at the origin is horizontal, with typical local shapes which are either an ellipsoidal surface, Figure 9(a), or a saddle surface, Figure 9(b). For this reason, it was considered not necessary to introduce the form of equation (10) which is more cumbersome, and then the procedure based on p,q,t was assumed accurate enough even with a moderate eccentricity. Indeed, as evident in Figure 9 for the examined geometry, the coefficients $A_{hk}^{(ij)}$ vary less than 1% when the eccentricity vector components (e_1,e_3) are in the

range ± 0.2 mm. The effects of the second order terms in equation 12 are significant only for eccentricities which are relatively large and uncommon in typical experimental applications.

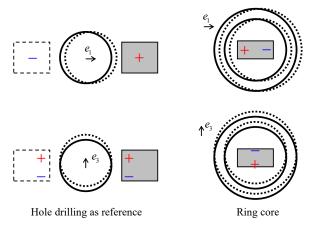


Figure 8. Self compensated eccentricity sensitivity of the ring-core, comparison with the hole-drilling.

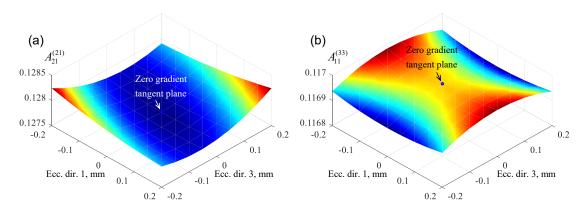


Figure 9. Eccentricity sensitivity of the general form matrix coefficients: (a) A_{21}^{21} , (b) A_{11}^{33} examples, and zero first partial derivatives at the origin.

Experimental application

The mechanical system for automatically drilling the groove and performing the strain gage measurement, manufactured by SINT Technology 30 , is shown in Figure 10 along with the HBM RY51 rosette. The drilling spindle of the device is hollow thus allowing the strain gage cables to pass through. The rosette requires a special preparation to protect the grids during the drilling. The overall dimensions of the system are 310 mm long, 160 mm wide, 230 mm maximum height. The centring is performed with two independent mechanical micrometric guides and a control webcam, connected with Ethernet TCP/IP. By this system a positioning accuracy in the order of ± 0.15 mm can be obtained. The vertical feed motion is driven by a stepping motor, and the machining of the annular groove around the strain gage rosette is operated with a DC motor to have

the tool rotational speed at approximately 200 rpm.



Figure 10. Equipment by SINT Technology for the ring-core automatic testing and HBM rosette.

The application introduced here is not intended to represent a validation, but an experimental example in which the residual stresses are effectively evaluated with different resolutions by means of the proposed coefficients. The ring-core rosette was applied on the lateral surface of a tubular square bar made by ASTM A500 Grade B steel carrying a longitudinal weld. The centre of the measurement region was at 40 mm from the weld, and the grid 1 direction perpendicular to the weld bead. The measured relaxed strains with 0.1 mm milling tool incremental step are plotted in Figure 11 (a). Initially, the residual stresses were calculated with two resolutions, Figure 11 (b): 1.0 mm (dashed lines) and 0.5 mm (solid lines). Higher resolution residual stress distributions, such as 0.2 mm or even 0.1 mm, can also be calculated with the proposed calibration matrices. However, for these small step values, the application of a filtering technique when solving equations 9 is recommended to reduce the effect of the noise. In particular the Tikhonov regularization proposed in the standard ASTM E837, which can be applied to the integral method for the ring core in the same way as for the hole-drilling, was demonstrated by Barsanti et al.³¹ to mitigate the effect of the measurement noise. Finally, the non-uniform step sequence, proposed by Zuccarello⁶ for this arrangement, with 8 depth increments and optimized strain measurement sensitivity, was implemented by means of the coefficients derived with the calculation scheme of Figure 5. The obtained residual stress distribution is reported in Figure 11 (c), where it is evident that the trends of the components are quite similar to the solution obtained with 0.5 mm step. In fact, the optimized step sizes range between 0.4 mm and 0.7 mm up to 3.5 mm depth.

Conclusions

The paper provides the calibration coefficients to apply the integral method in the ring-core technique for measuring non-uniform in depth residual stress distributions. The harmonic plane axisymmetric finite element model used for the numerical simulation was described along with the procedure to deduce the numerically simulated measured strains. The use of a 2D FE model produced results with high resolution and accuracy. Similar results could be obtained with a more intuitive 3D model but with 2 orders of magnitude more

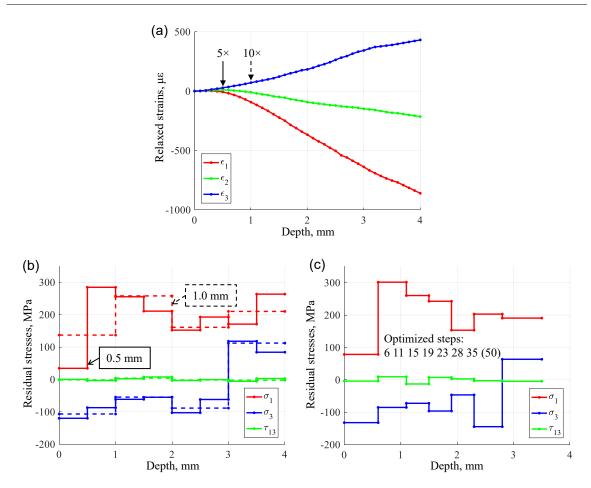


Figure 11. Ring-core experimental example, (a) relaxed strains with 0.1 mm incremental step, (b) residual stresses obtained with different depth steps: 0.5 mm and 1.0 mm, (c) residual stresses obtained with the optimized steps.

elements. In order to make the procedure suitable for processing experimentally obtained relaxed strains, a method for deriving lower resolution coefficients was proposed by which coarser and also non-uniform step sequences can be analysed. A more general form of the integral method, and the related coefficient analysis, confirmed that first order expansions of the relaxed strains, as a function of groove eccentricity with respect to the rosette centre, are zero. As a consequence, the integral method with the combined strains and stresses can be considered accurate enough even if the ring-core is produced with an eccentricity entity typical of the correct experimental implementation of the technique, hence still by using the proposed high resolution coefficient matrices. An example of practical application of the obtained coefficients was finally presented. The residual stress distributions obtained with different depth steps, and in particular with an optimized non-uniform step sequence, were calculated and compared, thus demonstrating the applicability of the lower resolution coefficient determination procedure.

Acknowledgements

Regione Toscana is acknowledged for funding this project: Bando 2009. Reg. (CE) n.1083/2006. POR CReO/FESR 2007-2013. Linea di intervento 1.3 a.

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Appendix I

Notation $D_{\rm I}, D_{\rm E}$ Internal and external diameter of the ring-core groove. $G_{\rm L}, G_{\rm W}$ Grid length and width of the strain gage rosette. ΔH Groove depth incremental step. Н Groove depth at a specific drilling step. Maximum groove depth. H_{max} Number of the step increments at the final depth. Principal maximum and minimum residual stresses. $\sigma_{max},\sigma_{min}$ Generic grid orientation with respect to the maximum principal stress direction. ϑ Relaxed strain measured by a generic grid. $\varepsilon_{\rm r}$ General elastic constants relating the residual stresses to the relaxed strains. A,BResidual stress components according to the rosette reference frame. $\sigma_1, \sigma_3, \tau_{13}$ Relaxed strains measured by the 0-45-90 degrees grids. $\varepsilon_1, \varepsilon_2, \varepsilon_3$ P,Q,TEquibiaxial and shear combined stresses. Combined relaxed strains according to the P, Q, T stresses. p,q,tE, vYoung's modulus and Poisson's ratio material properties. Calibration coefficients relating the P,Q,T residual stresses to the p,q,t relaxed strains. a,bVectors containing the combined stresses along the depth. P, Q, TVectors containing the combined strains along the depth. $\mathbf{p}, \mathbf{q}, \mathbf{t}$ Calibration coefficient matrices. $\bar{\mathbf{a}}, \bar{\mathbf{b}}$ Calibration coefficient elements. a_{ii},b_{ii} î, n Transverse and normal unit vectors along the directions of the grid. Integer multiple for lower resolution calibration matrices. m Stress components introduced as input for the FE 3D model validation. σ_x, σ_y \mathbf{S} Vectors containing the blocks of the three uncoupled residual stress components. e Vectors containing the blocks of the three grid relaxed strains. Ā Calibration coefficient 3×3 block matrix. Calibration matrix depth indices, i = 1, ..., n and j = 1, ..., i. i, jBlock indexes, for the matrix $\bar{\mathbf{A}}$, ranging from 1 to 3. h, k

Eccentricity components along the grid directions 1 and 3.

 e_1, e_3

Online Appendix:

M. Barsanti, M. Beghini, C. Santus, A. Benincasa, L. Bertelli

Integral method coefficients for the ring-core technique to evaluate non-uniform residual stresses

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Coefficients for $D_{\rm I}$ = 14 mm, $D_{\rm E}$ = 18 mm, $G_{\rm L}$ = 5.0 mm, $G_{\rm W}$ = 2.5 mm, maximum depth $H_{\rm max}$ = 5.0 mm and depth resolution ΔH = 0.1 mm $a_{ij} \times 10^3$

$a_{ij} \times 10^3$	$b_{ij} \times 10^3$
y	y .
3.8156	h. 5.2582
5.3290 4.5008	D ₁ 5.2582
6.6653 6.0634 5.0409	8.2099 7.5041 6.4355
7.9566 7.3646 6.6656 5.4703	9.6160 8.8915 8.1143 6.8750
9.1961 8.6183 7.9611 7.1576 5.8154	11.007 10.277 9.5120 8.6368 7.2450
10.394 9.8140 9.1928 8.4579 7.5586 6.0912	12.396 11.644 10.894 10.059 9.0867 7.5592
11.549 10.967 10.356 9.6764 8.8658 7.8817 6.3073	13 784 13 009 12 248 11 449 10 538 9 4742 7 8252
12.661 12.075 11.470 10.814 10.074 9.1941 8.1358 6.4704	15.171 14.373 13.597 12.799 11.941 10.954 9.8063 8.0481
3.730 13.140 12.537 11.897 11.191 10.393 9.4507 8.3278 6.5856	16.558 15.736 14.940 14.137 13.291 12.370 11.312 10.087 8.2314
4.754 14.160 13.558 12.927 12.245 11.490 10.639 9.6415 8.4633 6.6574	17.944 17.097 16.280 15.464 14.621 13.722 12.741 11.616 10.321 8.3776
5.732 15.136 14.534 13.908 13.241 12.517 11.716 10.818 9.7722 8.5471 6.6895	19.327 18.456 17.617 16.785 15.935 15.046 14.093 13.054 11.868 10.509 8.4888
6.665 16.066 15.463 14.841 14.185 13.482 12.717 11.874 10.934 9.8473 8.5835 6.6855	20.706 19.810 18.948 18.098 17.237 16.347 15.411 14.407 13.313 12.071 10.655 8.5666
7.552 16.951 16.347 15.728 15.080 14.391 13.652 12.849 11.969 10.993 9.8715 8.5765 6.6486	22.078 21.158 20.273 19.403 18.528 17.632 16.700 15.717 14.663 13.520 12.226 10.760 8.6126
3.392 17.790 17.186 16.568 15.926 15.249 14.528 13.755 12.918 12.005 10.998 9.8488 8.5299 6.5818	23.443 22.499 21.590 20.699 19.807 18.901 17.967 16.992 15.964 14.865 13.675 12.336 10.826 8.6285
0.187 18.584 17.979 17.363 16.725 16.067 15.351 14.600 13.795 12.928 11.987 10.955 9.7833 8.4472 6.4882	24.799 23.830 22.897 21.984 21.074 20.155 19.213 18.240 17.224 16.154 15.012 13.782 12.403 10.854 8.6157
1.936 19.332 18.728 18.113 17.479 16.818 16.123 15.389 14.609 13.776 12.884 11.919 10.866 9.6788 8.3319 6.3705	26.142 25.148 24.192 23.256 22.327 21.393 20.441 19.464 18.453 17.398 16.288 15.109 13.842 12.428 10.847 8.5758
641 20.037 19.432 18.818 18.187 17.532 16.847 16.126 15.365 14.559 13.703 12.788 11.805 10.737 9.5391 8.1874 6.2315	27.471 26.453 25.473 24.515 23.566 22.614 21.651 20.666 19.654 18.606 17.514 16.369 15.155 13.857 12.413 10.807 8.5104
302 20.698 20.094 19.481 18.853 18.202 17.525 16.815 16.070 15.285 14.456 13.579 12.647 11.649 10.571 9.3678 8.0168 6.0737	28.785 27.742 26.738 25.757 24.788 23.818 22.840 21.846 20.828 19.781 18.699 17.574 16.397 15.154 13.829 12.361 10.735 8.4210
921 21.317 20.713 20.102 19.476 18.830 18.158 17.458 16.725 15.957 15.151 14.303 13.409 12.463 11.455 10.372 9.1683 7.8233 5.8996 498 21.895 21.292 20.682 20.058 19.415 18.750 18.057 17.335 16.581 15.793 14.968 14.104 13.197 12.242 11.228 10.143 8.9439 7.6097 5.7116	30.080 29.013 27.985 26.981 25.991 25.003 24.010 23.003 21.978 20.928 19.849 18.736 17.581 16.376 15.108 13.761 12.274 10.633 8.3094
498] 21.895] 21.292] 20.682] 20.058] 19.415] 18.750] 18.057] 17.335] 16.581] 15.793] 14.588] 14.104] 13.197] 12.242] 11.228] 10.143] 8.9439] 7.6097] 5.7116] 30.56] 24.344] 14.382] 21.228] 10.143] 8.9439] 7.6097] 5.7116] 30.56] 24.344] 41.386] 12.344] 11.386] 10.971] 8.8890] 8.980] 7.3790] 5.5118]	31.356 30.264 29.212 28.186 27.175 26.168 25.158 24.138 23.102 22.047 20.968 19.859 18.718 17.537 16.309 15.020 13.654 12.154 10.504 8.1771
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536 22.935 22.333 21.726 21.106 20.469 19.813 19.132 18.427 17.694 16.934 16.144 15.323 14.472 13.586 12.664 11.701 10.687 9.6123 8.436 7.1337 5.3025 10.00 23.400 22.799 22.193 21.575 20.941 20.288 19.613 18.914 18.190 17.440 16.663 15.859 15.027 14.166 13.275 12.351 11.389 10.381 9.3162 8.1535 6.8763 5.0855	33.840 32.700 31.601 30.530 29.476 28.431 27.386 26.336 25.277 24.203 23.114 22.004 20.872 19.714 18.527 17.305 16.042 14.724 13.338 11.824 10.170 7.8575
0001 23-4001 22-7891 22-199 21-7575 20-9841 20-266 18-915 16-914 16-199 17-4840 16-0659 15-089 18-02-17 18-080 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-08 18-	35,046 33,882 32,760 31,667 30,592 29,527 28,464 27,398 26,325 25,241 24,143 23,028 21,895 20,741 19,564 18,359 17,123 15,849 14,523 13,132 11,619 19,9701 7,6736
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